

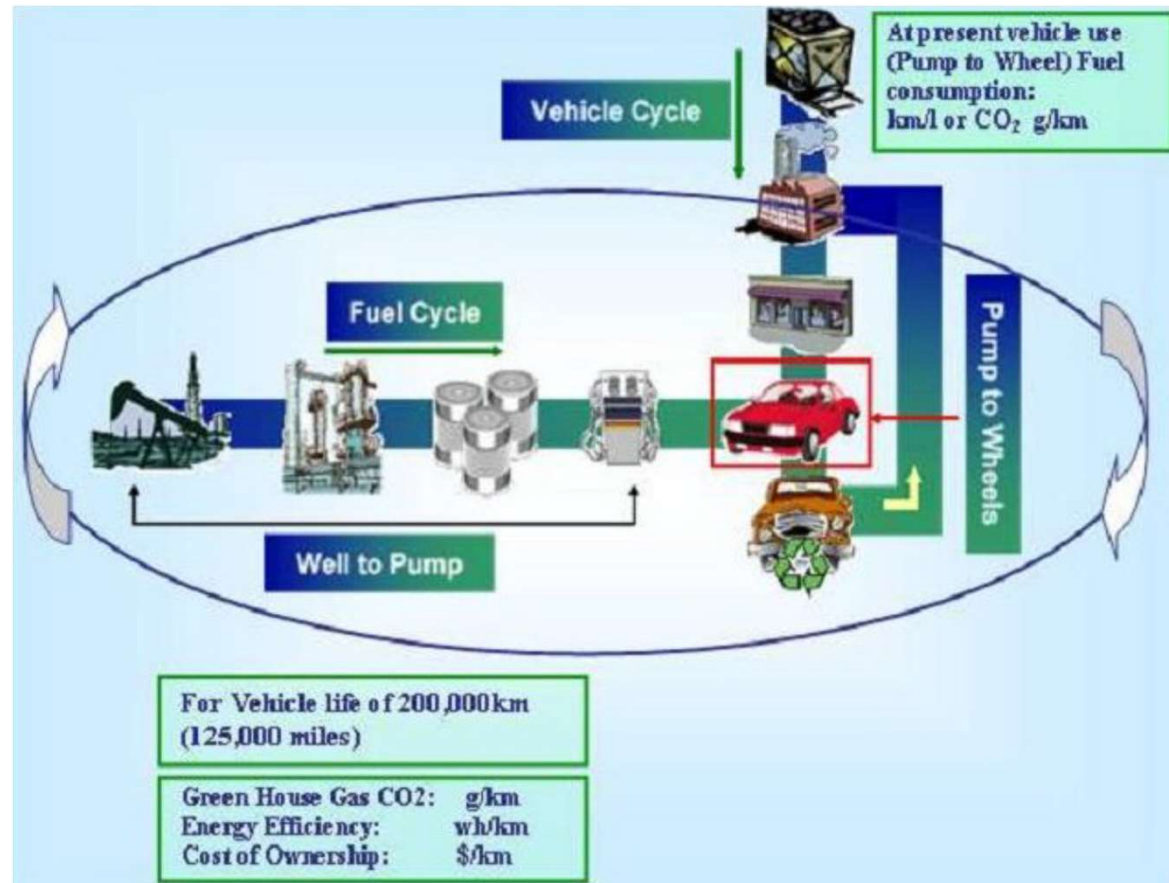
# Environmental Impact

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- Overview
  - Fuel Efficiency and CO2 Relevance
  - Air Pollution
  - Noise Pollution
- Well-to-Wheel Efficiencies
- FSV Environmental Assessment
- Well-to-Wheel Energy Usage

# Total Life Cycle Assessment

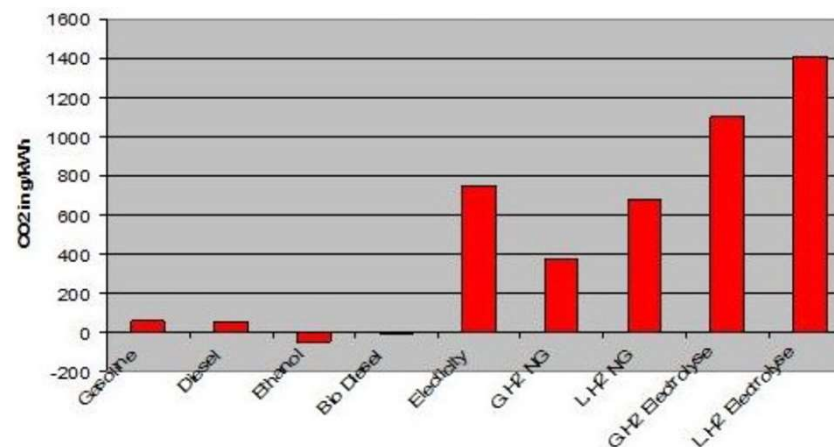
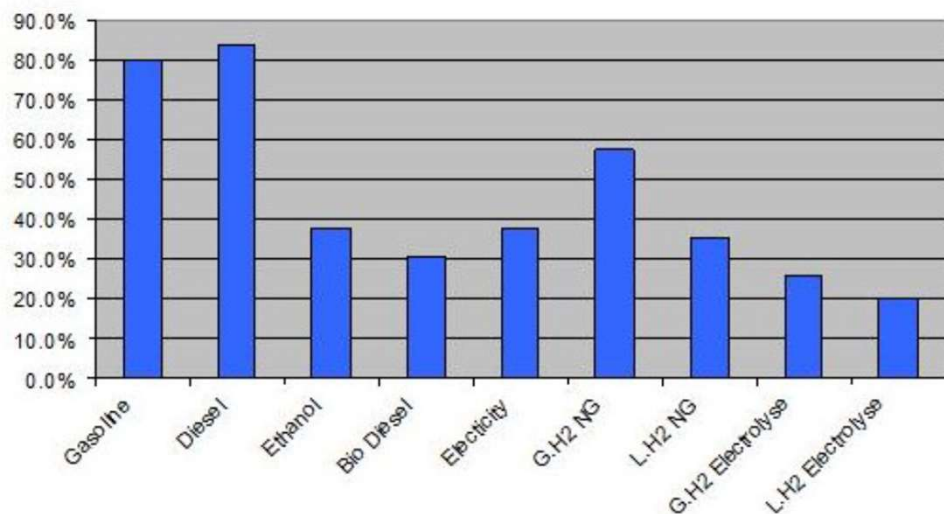
- “Pump-to-Wheel” fuel consumption and corresponding CO<sub>2</sub> emissions
- Fuel production cycle also known as “Well-to-Pump”
- Vehicle manufacturing cycle



# Well-to-Pump Assessment: Fuel Cycle

- Electricity (US mix, Europe, China, Japan, India, 100% coal and 100% renewable)
- Gasoline and diesel from petroleum
- Bio-fuels, ethanol and bio-diesel
- Hydrogen gas and liquid made using electrolysis process and from natural gas

Feedstocks [%]	USA	Europe	China	Japan	India	Coal	USA Green Mix
Coal	50.7	29.5	79	28.1	68.7	100	0
Natural Gas	18.9	9.9	0	21	8.9	0	0
Oil	2.7	4.5	2.4	13.2	4.5	0	0
Nuclear	18.7	31	2.1	27.7	2.5	0	20
Biomass	1.3	2.1	0	0	0	0	0
Others	7.7	13	16.5	10	15.4	0	80
	100	100	100	100	100	0	100
Electricity Pathway:							
Efficiency [%]	37.9	44.2	35	41.6	35.1	30.7	91.5
CO <sub>2</sub> [g/kWh]	750.6	520.3	973	596.7	923.5	1201.3	0
VOC [g/kWh]	0.07	0.05	0.08	0.06	0.08	0.09	0
Nox [g/kWh]	0.82	0.61	1.05	0.76	1.01	1.26	0
Sox [g/kWh]	1.8	1.25	2.64	1.74	2.46	3.15	0



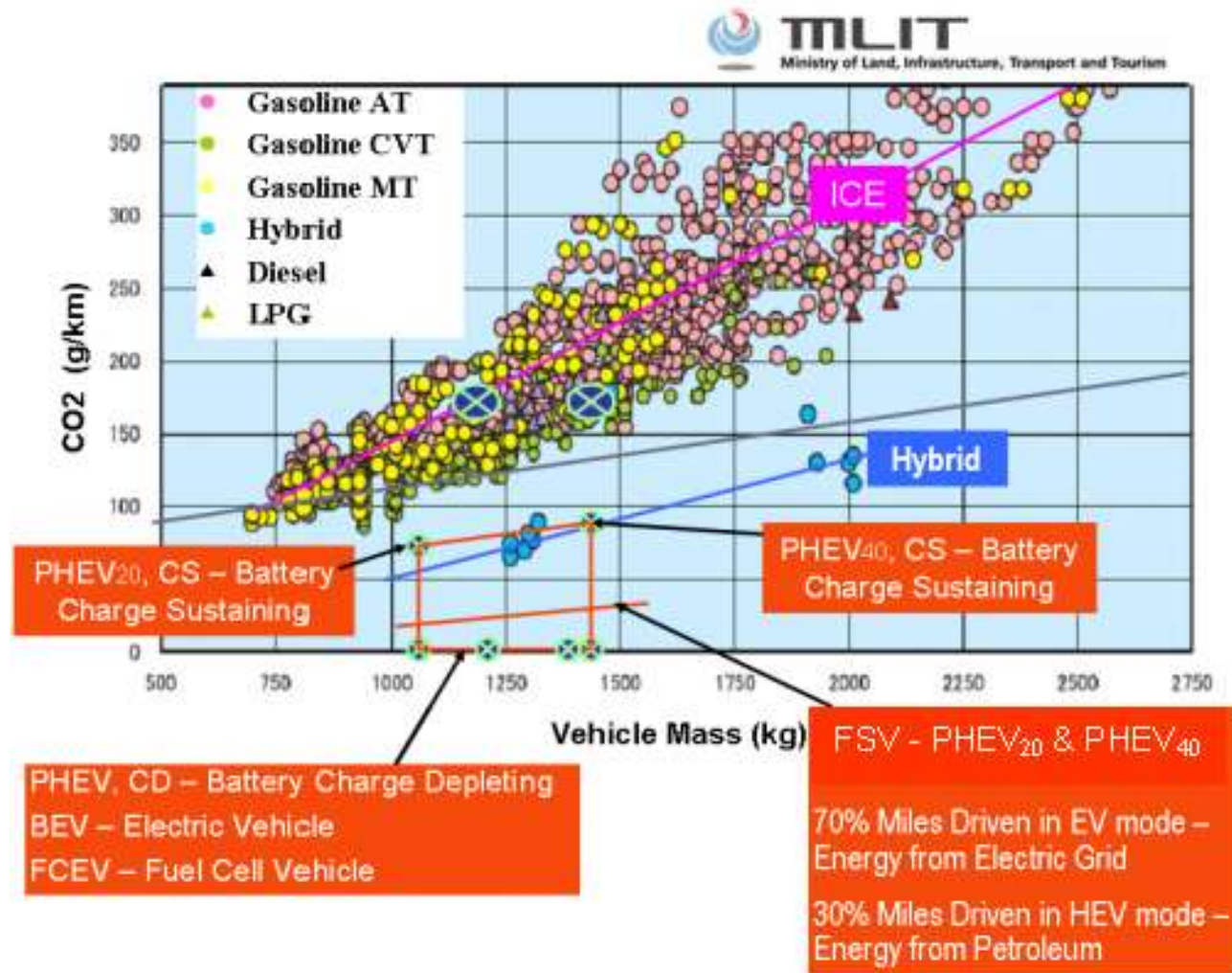
# Pump-to-Wheel Assessment: FSV

European Union (EU): 95 g(CO<sub>2</sub>)/km (passenger car fleet average), by year 2020  
Zero Emissions Vehicles (ZEV) by the California Air Resources Board (CARB)

	FSV1 BEV PHEV <sub>20</sub>		FSV2 FCEV PHEV <sub>40</sub>		Reg. Limit ALL
European Drive Cycle (NEDC)					
CO2 Emissions g/km	0	23	0	27	95
Fossil Fuel l/100km	0	0.99	0	1.14	4.1
Electricity Usage $\frac{Wh}{km}$	89	65	0	75	N/A
Total Energy Usage ** $\frac{Wh}{km}$	89	152	211	175	361
2008 US EPA Drive Cycle					
CO2 Emissions (combined) g/km	0	31	0	35	156
Combined MPG	∞	177	∞	157	35
Combined Electricity Usage $\frac{Wh}{km}$	109	80	0	92	N/A
Combined Energy Usage ** $\frac{Wh}{km}$	109	196	295	224	590
City MPG	∞	177	∞	157	N/A
City Electricity Usage $\frac{Wh}{km}$	103	75	0	86	N/A
City Energy Usage ** $\frac{Wh}{km}$	103	192	304	218	N/A
Highway MPG	∞	177	∞	157	N/A
Highway Electricity Usage $\frac{Wh}{km}$	117	85	0	99	N/A
Highway Energy Usage ** $\frac{Wh}{km}$	117	202	295	231	N/A



# Fuel Economy and CO<sub>2</sub> Emissions

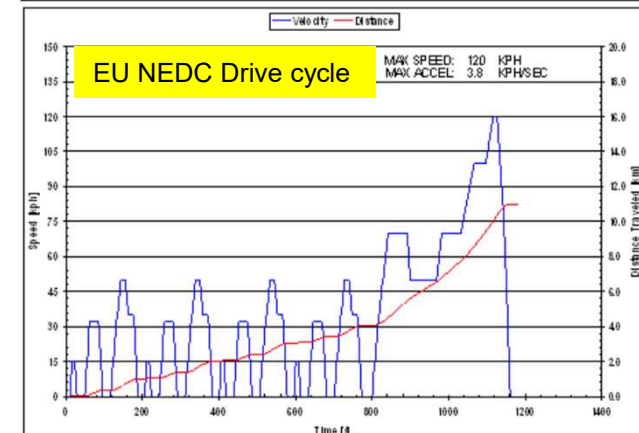
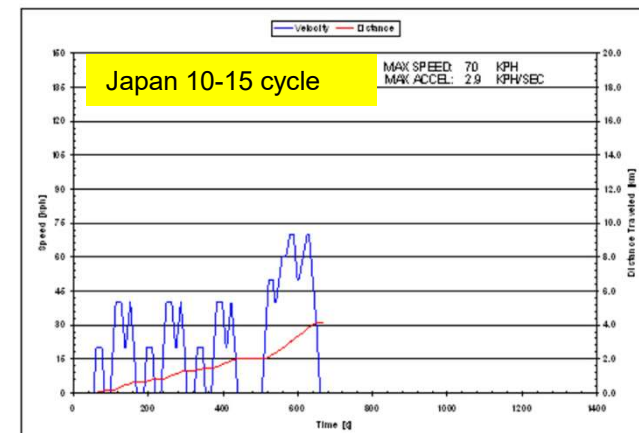
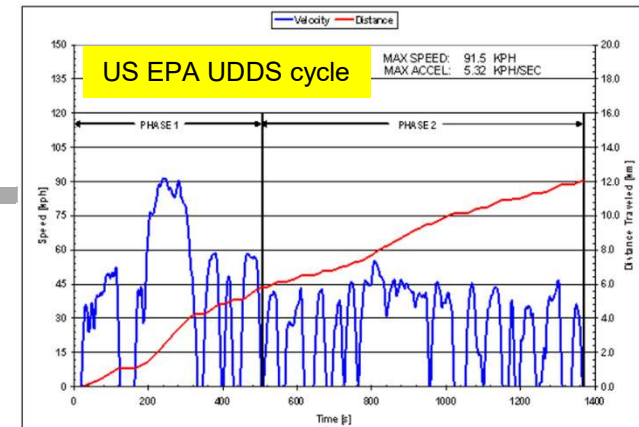


Japan - Ministry of Land, Infrastructure, Transport and Tourism

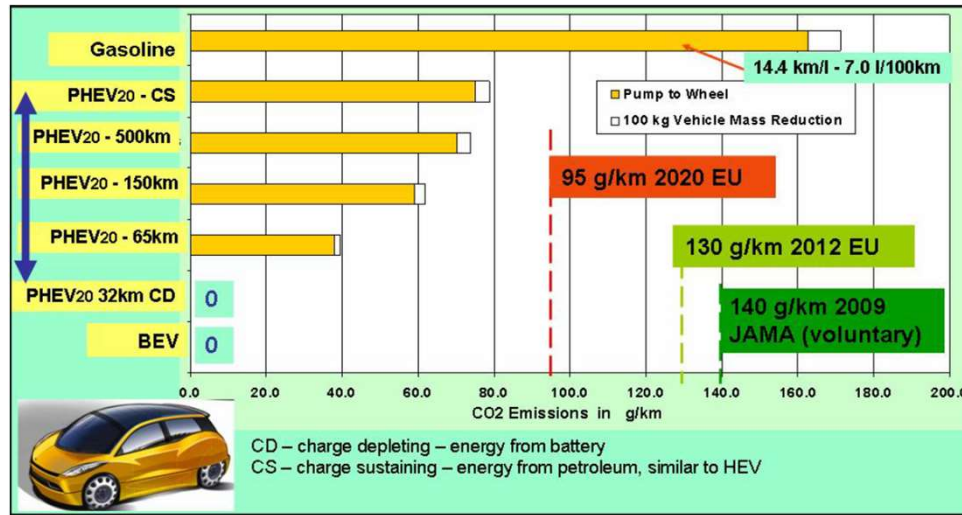
# FSV Environmental Assessment

- Pump-to-Wheel fuel economy
  - Powertrain System Analysis Toolkit (PSAT)
  - standard drive cycles from North America, Japan, and Europe

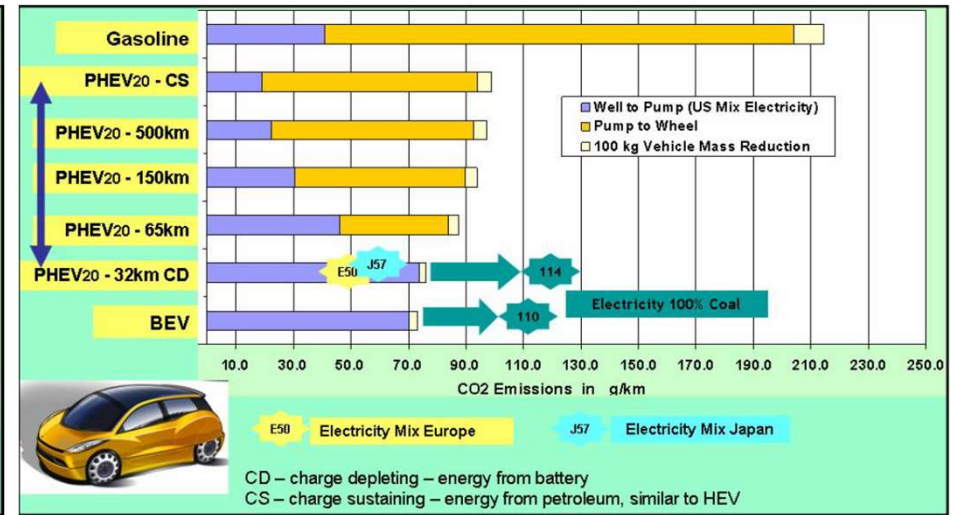
		UDDS	Japan 10-15	NEDC
<b>PHEV<sub>40</sub> Series Mid-size: 1300kg Vehicle + 75kg driver</b>				
Charge Depleting	[Wh / km]	107	110	111
	[L / 100km]	0	0	0
	[g CO <sub>2</sub> / km]	0	0	0
Charge Sustaining	[Wh / km]	0	0	0
	[L / 100km]	3.8	3.79	3.79
	[g CO <sub>2</sub> / km]	88.4	88	88
<b>PHEV<sub>20</sub> Series Small-size: 1000kg Vehicle + 75kg driver</b>				
Charge Depleting	[Wh / km]	92.5	94.9	96.9
	[L / 100km]	0	0	0
	[g CO <sub>2</sub> / km]	0	0	0
Charge Sustaining	[Wh / km]	0	0	0
	[L / 100km]	3.3	3.27	3.43
	[g CO <sub>2</sub> / km]	76.7	76	79.8
<b>EV Series Small-size: 1100kg Vehicle + 75kg driver</b>				
	[Wh / km]	88.9	92.8	96.4
	[g CO <sub>2</sub> / km]	0	0	0
<b>FCEV Series Mid-size: 1300kg Vehicle + 75kg driver</b>				
	[kg / 100km]	0.632	0.669	0.653
	[g CO <sub>2</sub> / km]	0	0	0



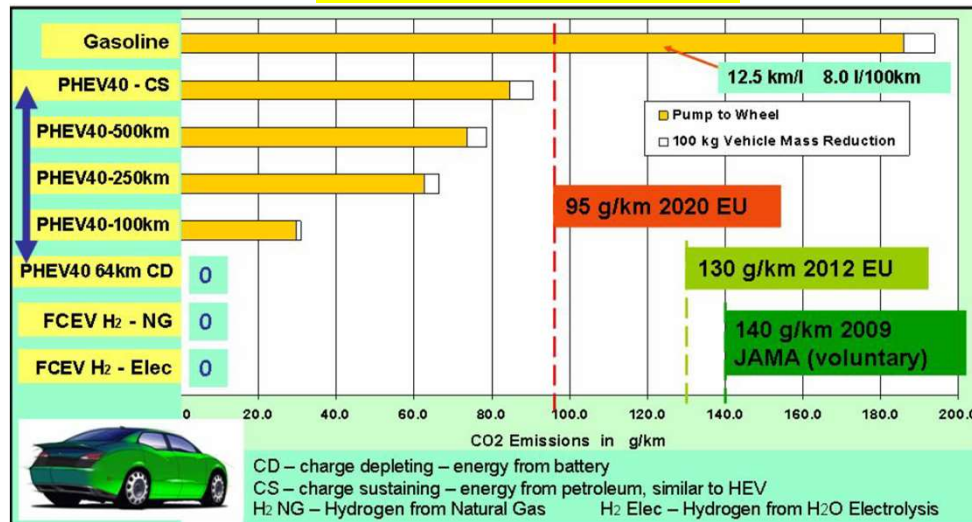
# Assessment: FSV-1, FSV-2



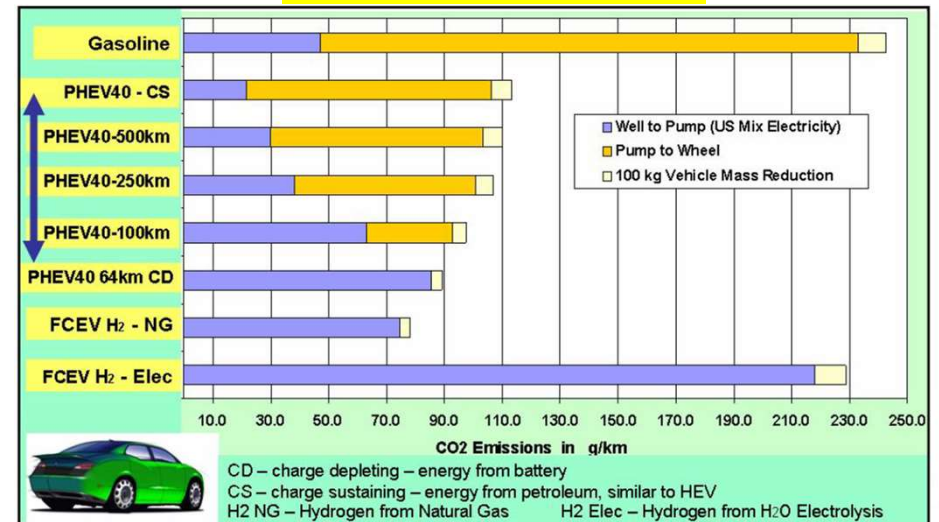
Pump-to-Wheel CO<sub>2</sub> Emissions



Well-to-Wheel CO<sub>2</sub> Emissions



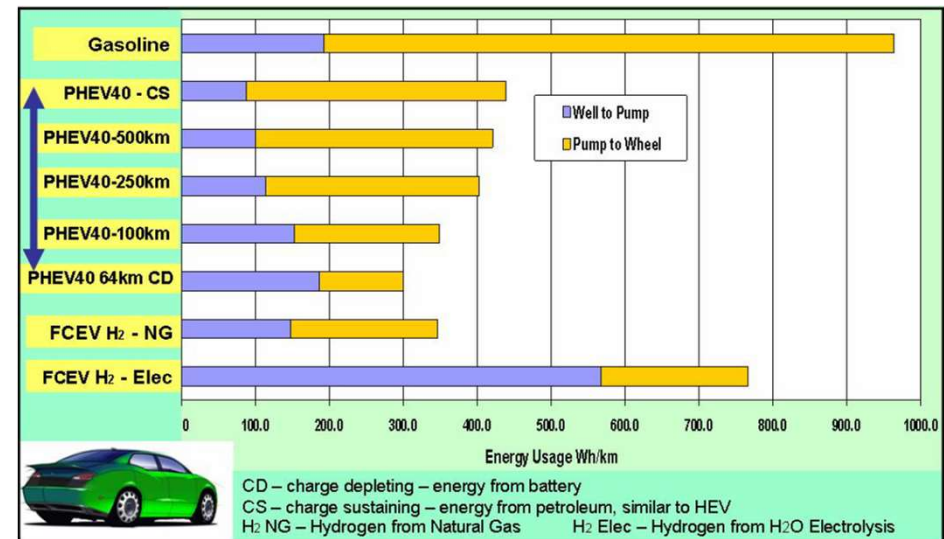
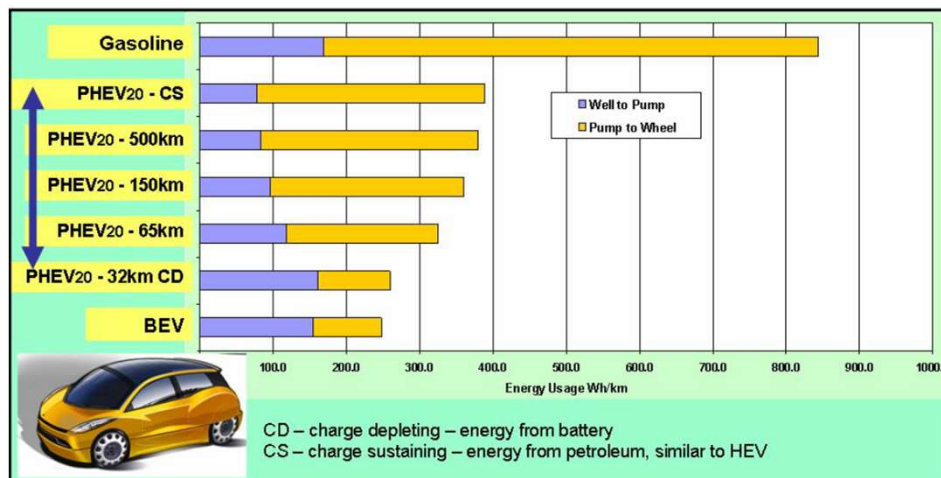
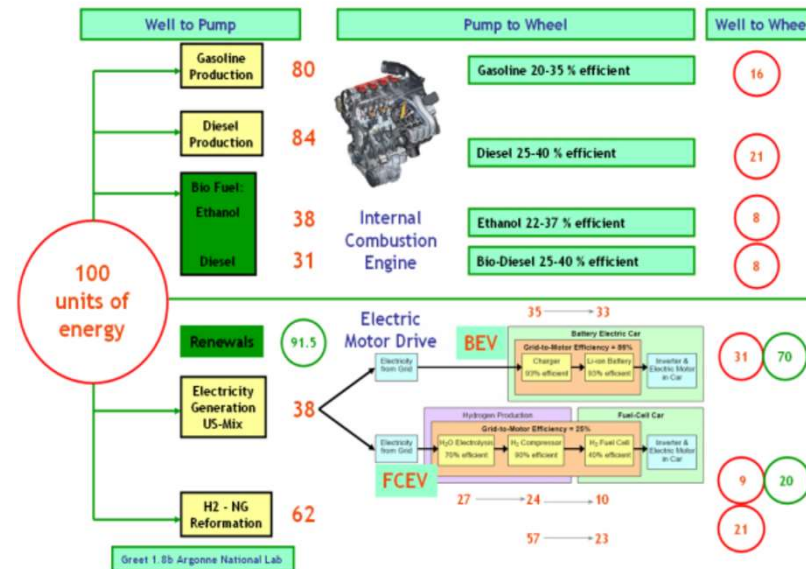
Future Steel Vehicle



Phase I Summary - 121



# Well-to-Wheel Energy Usage

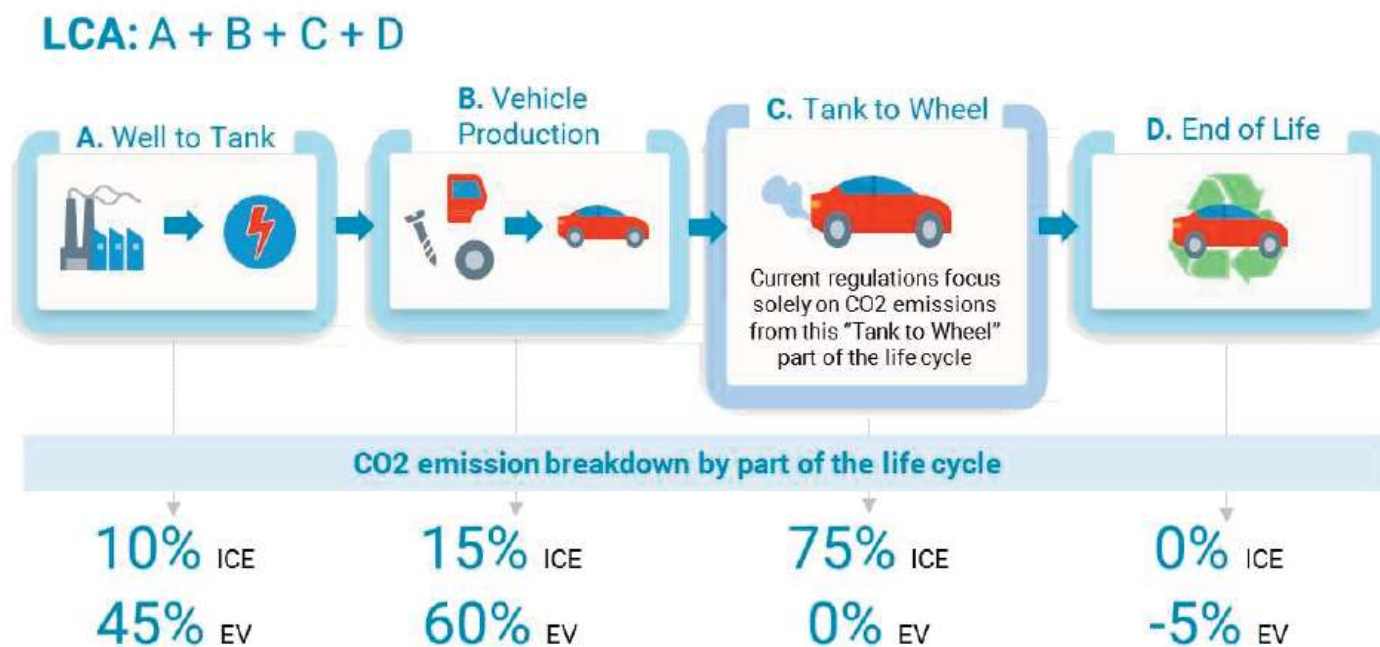




# Life Cycle Assessment

- measures the environmental burden across the whole life cycle of a car, from production to driving and ultimately recycling parts of the vehicle
- CO2 emissions on a tank-to-wheel basis vs. LCA approach

Exhibit 1: LCA takes a holistic view of CO2 emissions  
CO2 life cycle for automobiles (image of mid-size sedan)

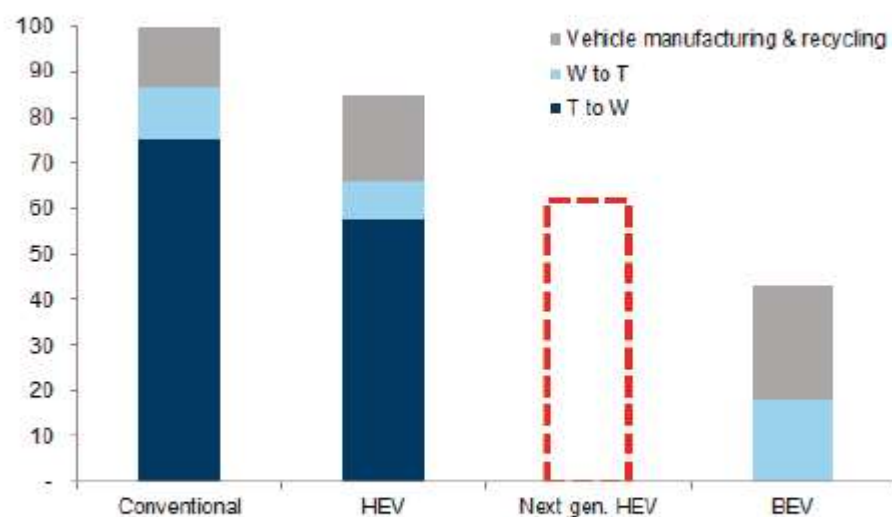


CO2 (g/km)	Well-to-Tank	Tank-to Wheel
ICE	50~60	120
EV	100~120	0

– total driving distance(km): 180k(EU), 110k(Japan)

#### Exhibit 2: EVs come out on top in Europe

CO2 emissions measured on an LCA basis in Europe (assuming emissions of 100 for ICE vehicles)

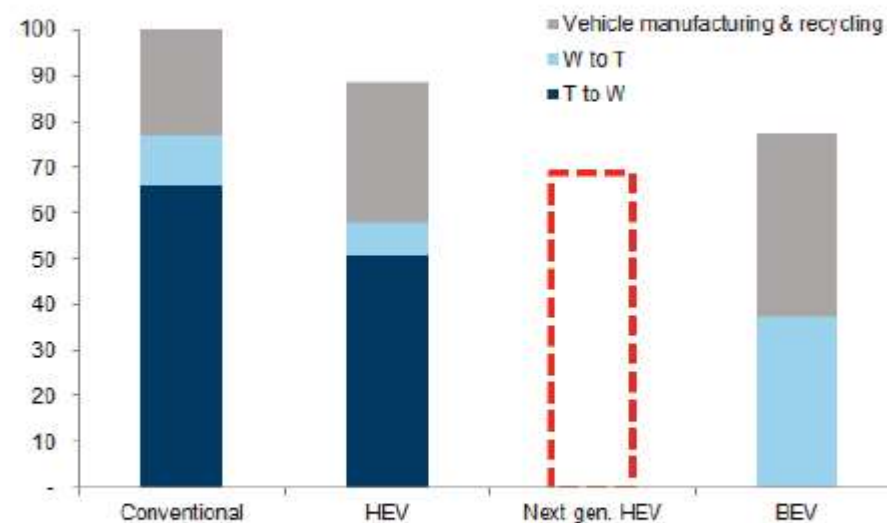


Based on Europe's projected energy mix in 2030, CO2 intensity includes power transmission loss

Source: Toyota Motor presentation at the 2019 Vienna Motor Symposium

#### Exhibit 3: Next-generation hybrid vehicles may provide a solution

CO2 emissions measured on an LCA basis in Japan (assuming emissions of 100 for ICE vehicles)

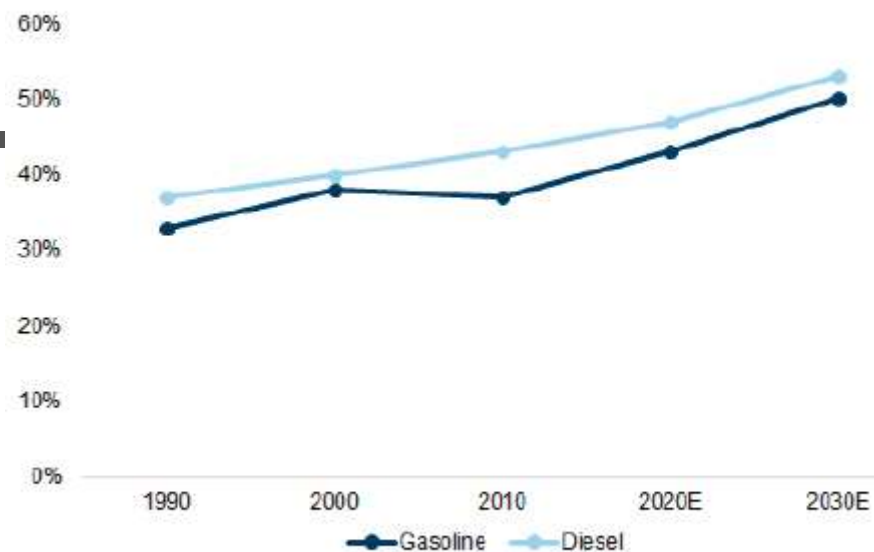


Based on Japan's projected energy mix in 2030, CO2 intensity includes power transmission loss

Source: Toyota Motor presentation at the 2019 Vienna Motor Symposium

#### Exhibit 4: Good prospects for increased engine efficiency

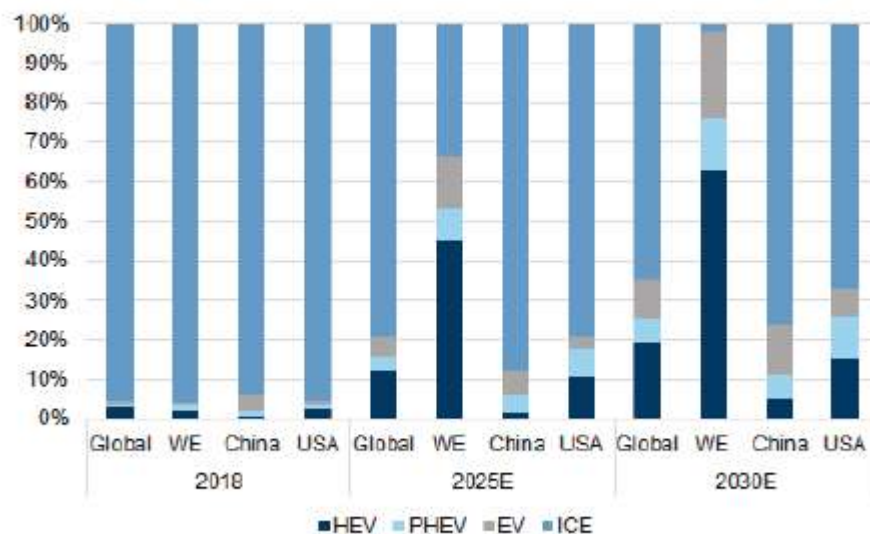
Engine thermal efficiency



Source: Goldman Sachs Global Investment Research

#### Exhibit 7: Europe set to take the lead in the shift to EVs

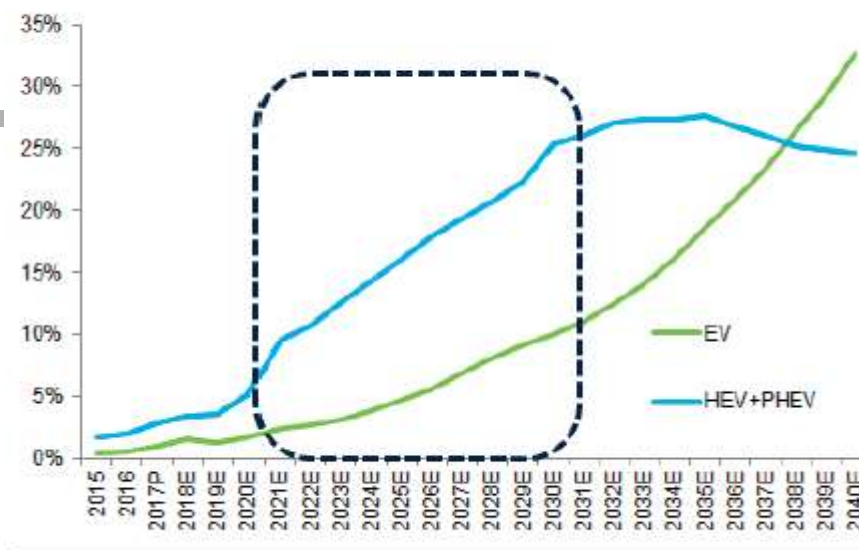
Powertrain forecasts by region



Source: Goldman Sachs Global Investment Research

#### Exhibit 6: EVs and HEVs likely to trade places in 2037

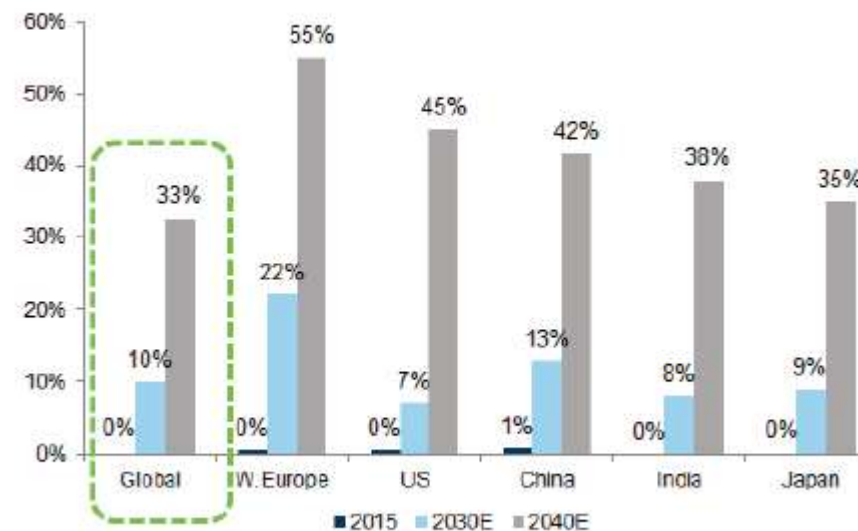
Electrification forecasts through 2040



Source: IHS Global Insight, Goldman Sachs Global Investment Research

#### Exhibit 8: Other countries likely to catch up with Europe by 2040

EV sales weighting



Source: Global Insight, Goldman Sachs Global Investment Research

# Paris Agreement

- international treaty on climate change control that was concluded by numerous countries at the 2015 United Nations Climate Change Conference (COP21) in Paris

## Exhibit 9: Waiting for 2050 target announcements

Countries' CO2 emission reduction targets and weightings in global auto demand

### Each Country's Target

#### Developed Countries

USA Cutting more than 80% CO2 by 2050 vs. 2005 (Obama Administration). President Trump announced to quit the agreement on Nov. 2020

Japan Cutting 80% CO2 by 2050 vs. 2013

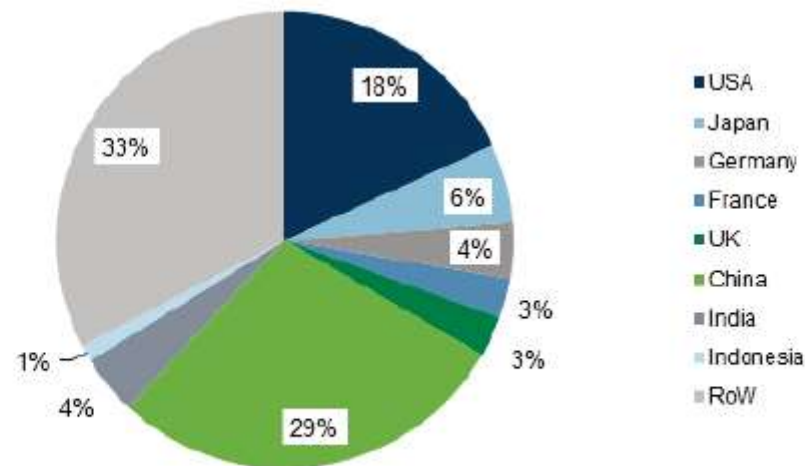
EU Cutting 80-95%/75%/more than 80% CO2 in Germany/France/UK by 2050 vs. 1990.

#### Developing Countries

China Cutting 60-65% CO2 per GDP by 2030 vs. 2005.

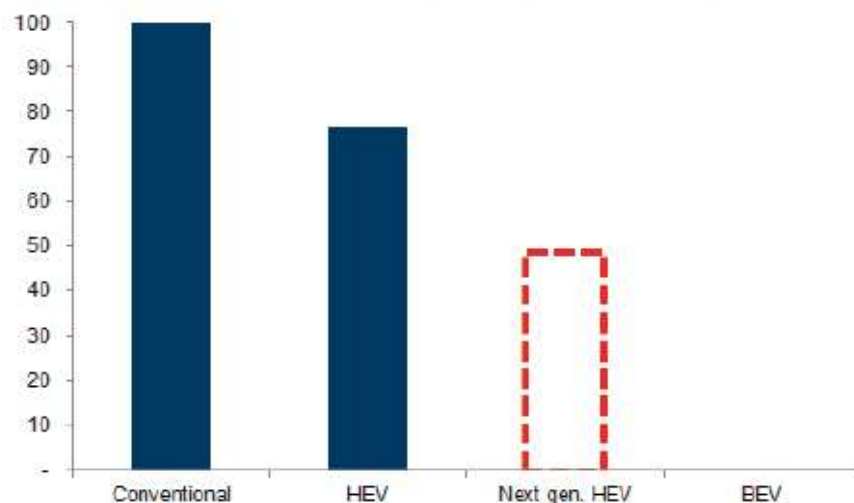
India Cutting 33-35% CO2 per GDP by 2030 vs. 2005.

Indonesia Cutting 29% CO2 by 2030 vs. BAU (business as usual). Cutting at most 41% CO2 based on the international support.





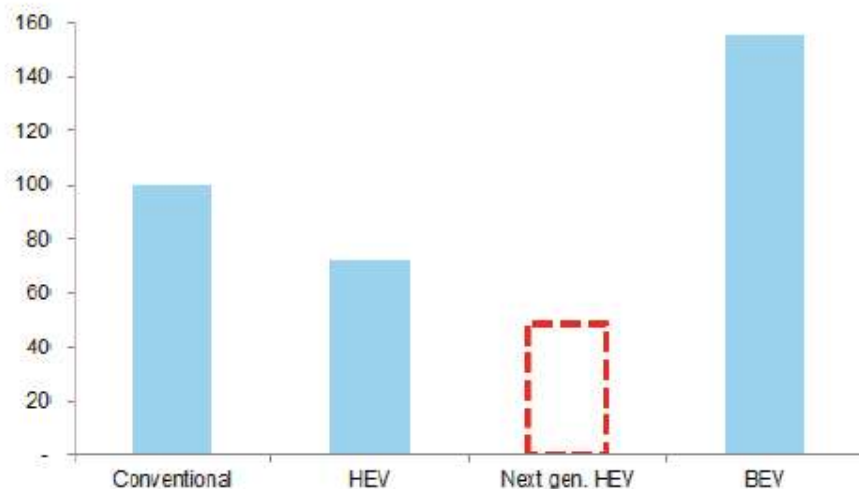
**Exhibit 10: EVs are the most logical choice under current rules**  
Tank-to-wheel CO2 emissions (LCA emissions of existing vehicles = 100)



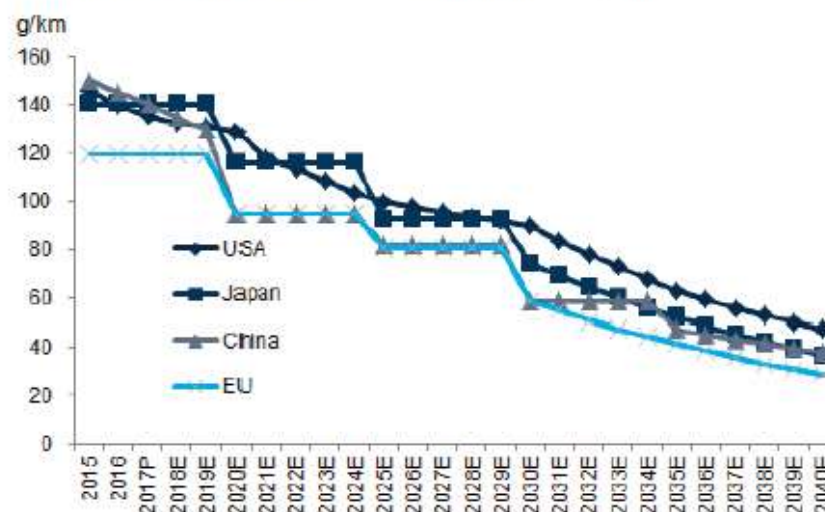
Source: Toyota Motor presentation at the 2019 Vienna Motor Symposium, Data compiled by Goldman Sachs Global Investment Research

**Exhibit 12: Electricity generation produces more CO2 than gasoline in the production/transportation process**

Well-to-tank CO2 emissions (LCA emissions of existing vehicles = 100)

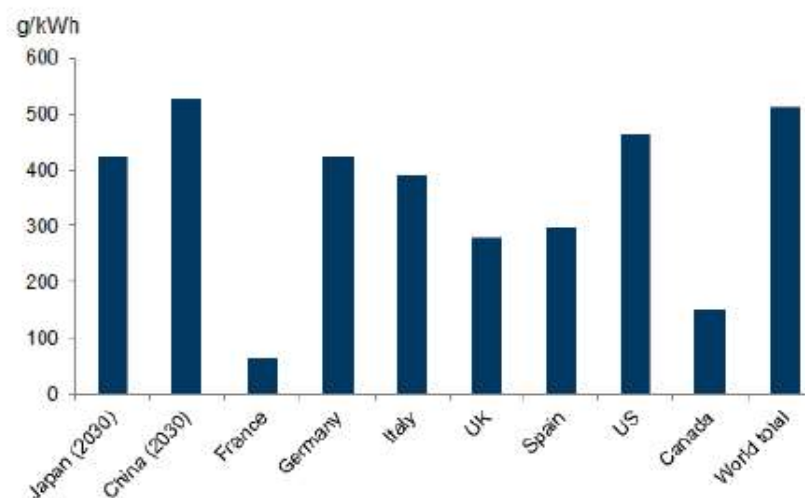


**Exhibit 11: European rules are the strictest**  
CO2 emission regulations for certain countries/regions



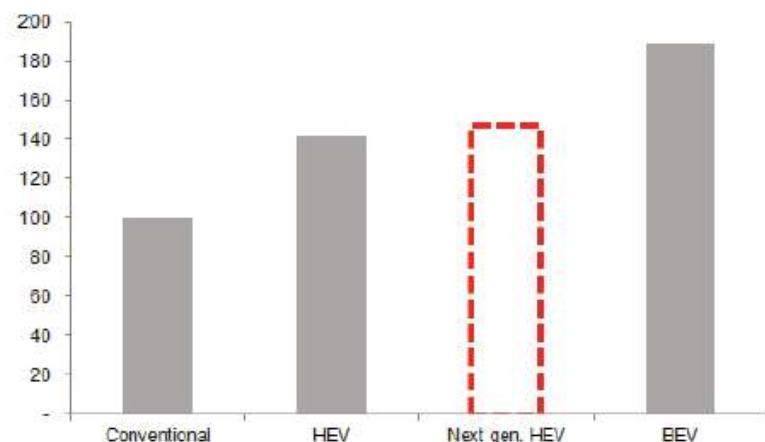
Source: US Department of Transportation, European Commission, Ministry of Industry and Information Technology, Ministry of Land, Infrastructure, Transport and Tourism, Goldman Sachs Global Investment Research

**Exhibit 14: Environmental load varies by region**  
CO2 emissions during power generation per kWh by region



### Exhibit 17: Battery production process has high environmental load in EV production

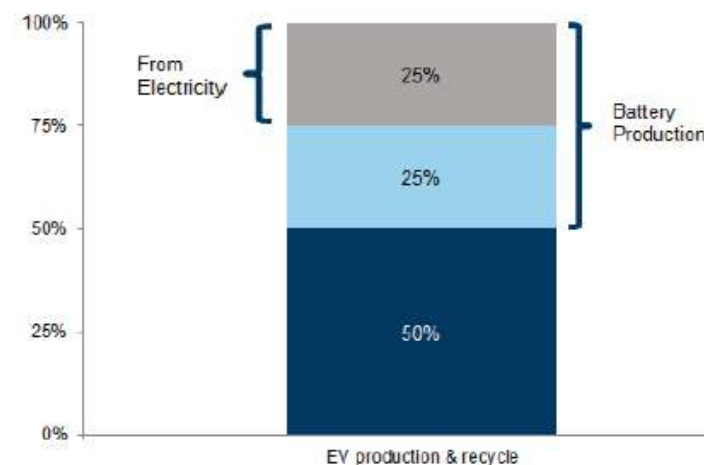
CO2 emissions from vehicle production/recycling (LCA emissions of conventional vehicle=100)



Source: Toyota Motor presentation at the 2019 Vienna Motor Symposium, Data compiled by Goldman Sachs Global Investment Research

### Exhibit 18: CO2 emissions from battery production account for roughly half of emissions from EV production

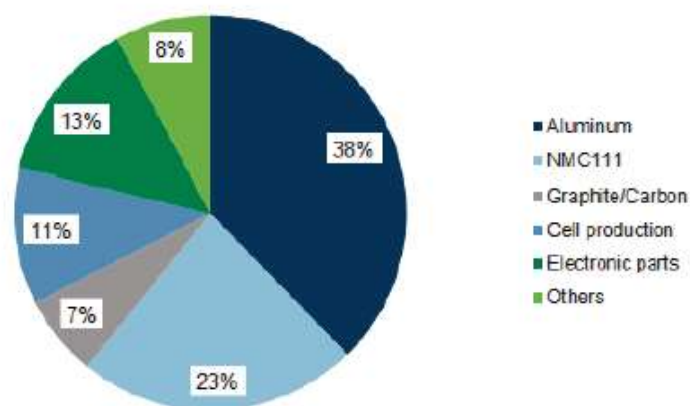
Breakdown of CO2 emissions from EV production



Source: compiled by Goldman Sachs Global Investment Research

### Exhibit 19: Aluminum and cathodes account for most of electricity consumption in battery production

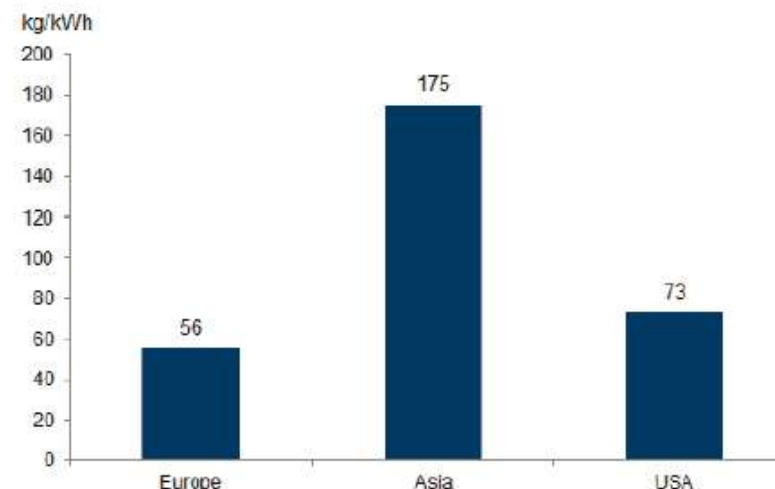
Breakdown of electricity consumption in NMC111 battery production



Source: Qiang et al. 2019, "Life Cycle Analysis of Lithium-Ion Batteries for Automotive Applications"

### Exhibit 20: Batteries made in Asia have high CO2 load

CO2 emissions from battery production per kWh by region



Source: ICCT

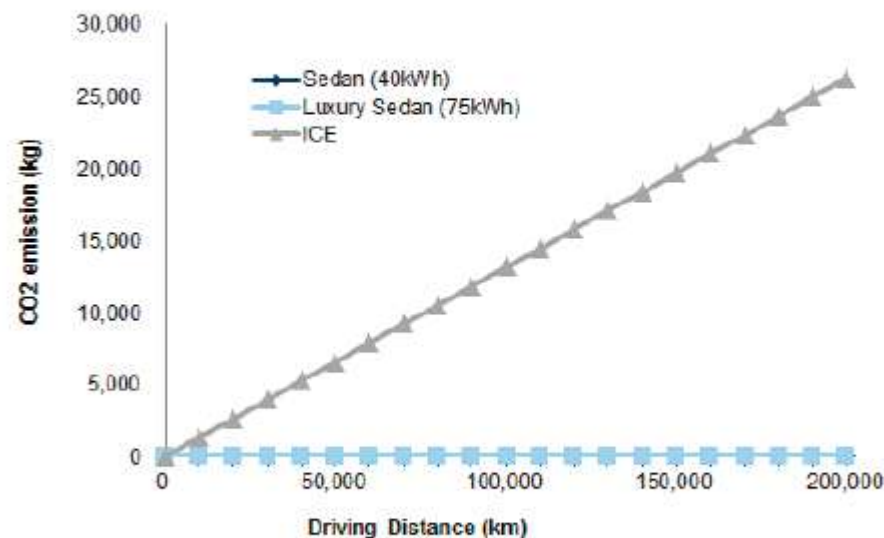
**Exhibit 21: Honda/Mazda batteries only 36 kWh**  
Comparison of EV models

	Price	Battery Size (kWh)	WLTP Range (km)
VW ID.3 Standard Range	30,000 €	45.0	330
VW ID.3 Mid Range	< 40,000 €	58.0	420
VW ID.3 Long Range	> 40,000 €	77.0	550
Honda e	29,660 €	35.5	220
Honda e Advance	32,160 €	35.5	220
Mazda MX-30	33,990 €	35.5	200
Tesla Model 3	60,390 €	75.0	530
Nissan Leaf	36,800 €	40.0	270

Source: Company data, Goldman Sachs Global Investment Research

**Exhibit 22: EVs clear winner under current assessment criteria, but...**

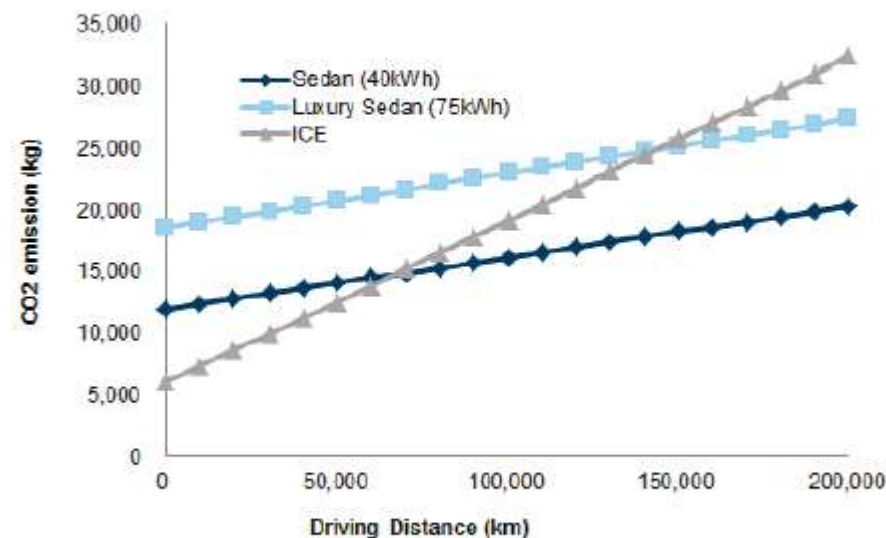
Tank to wheel: Relationship between distance travelled and CO2 emissions



Sedan is totally overlapping with Luxury Sedan

Source: Auto Catalog, Data compiled by Goldman Sachs Global Investment Research

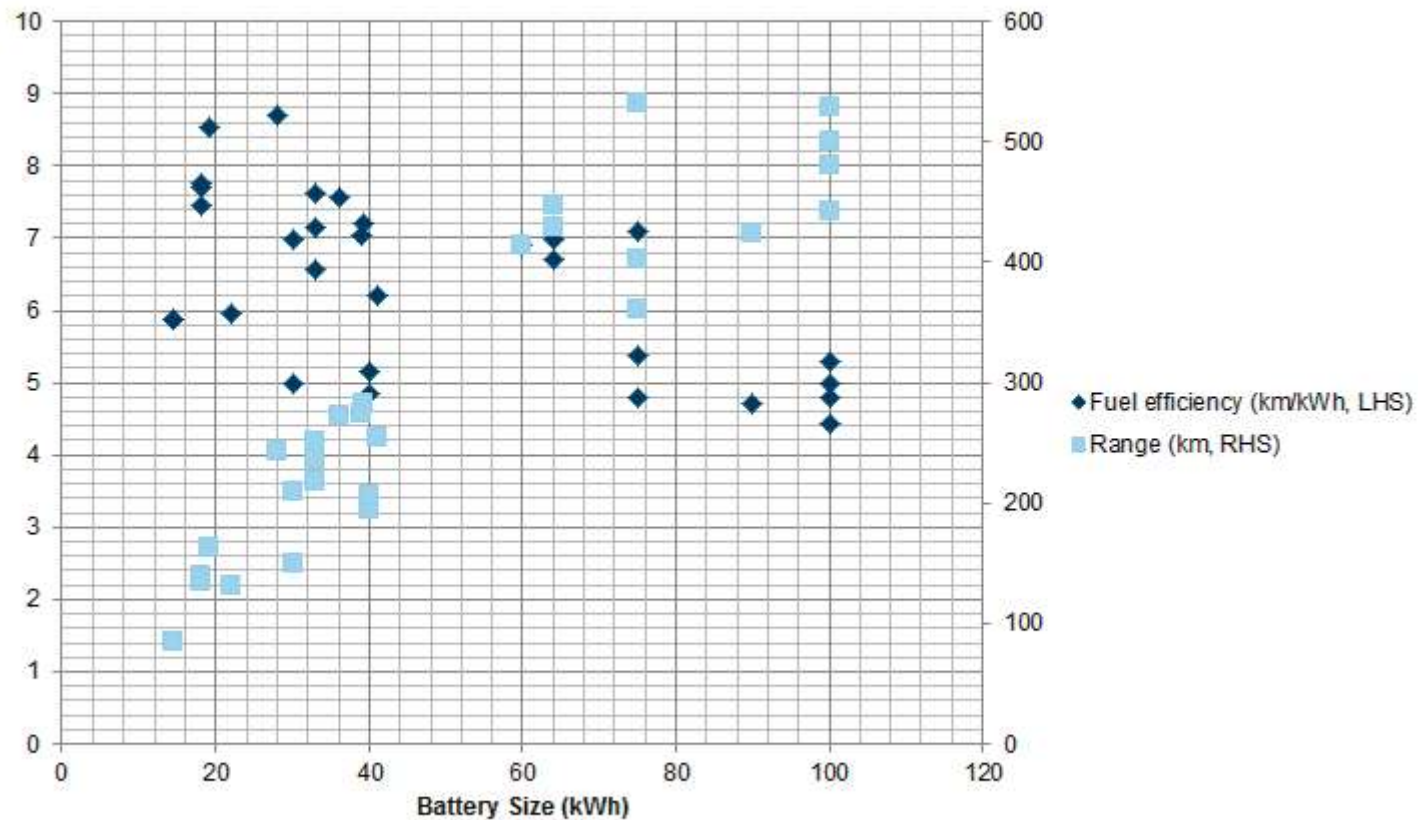
**Exhibit 23: LCA: The larger the battery, the worse the emissions**  
LCA: Relationship between distance travelled and CO2 emissions



Source: Company data, BP, Auto Catalog, Data compiled by Goldman Sachs Global Investment Research



**Exhibit 33: Range increases with greater battery capacity, but energy efficiency decreases**  
 Relationship between battery capacity and energy efficiency/range



Source: Auto Catalog, Goldman Sachs Global Investment Research



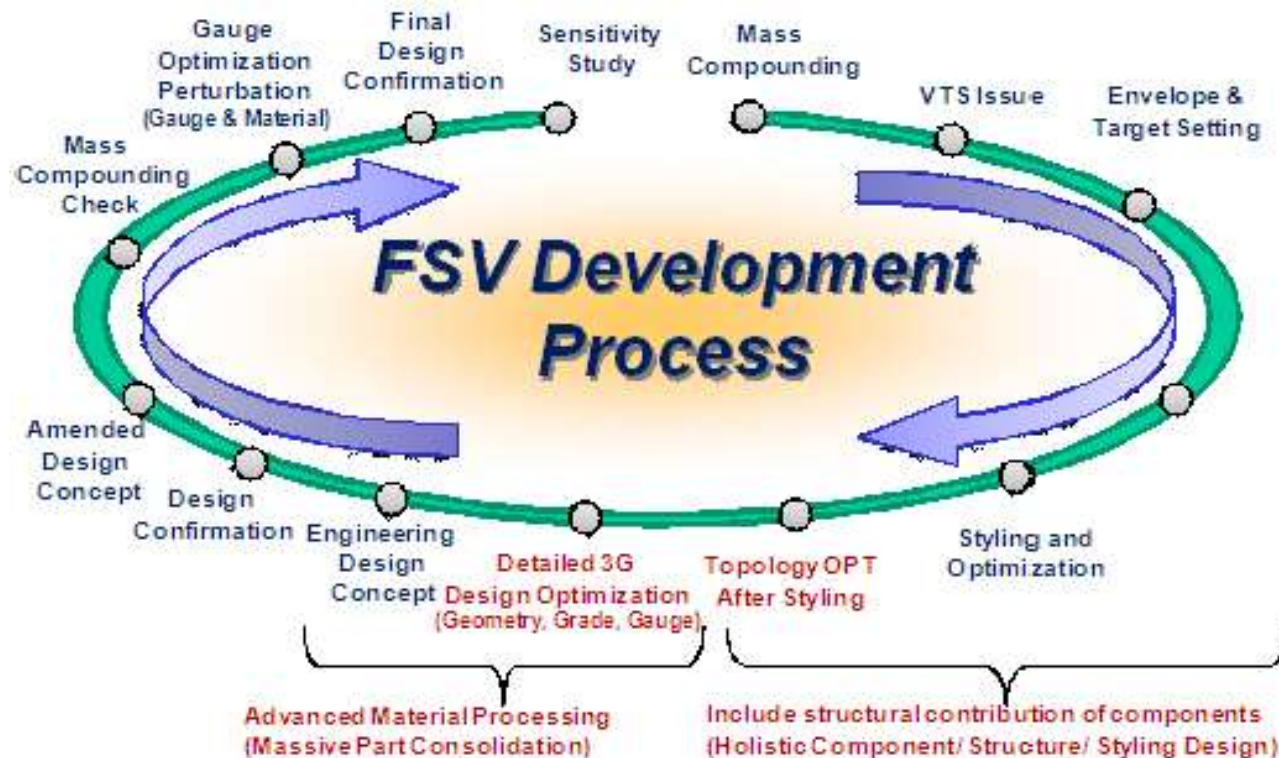
# Structure Design Methodology

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- Overview
- Baseline model
- Topology optimization
- 3G optimization
- Final design and validation

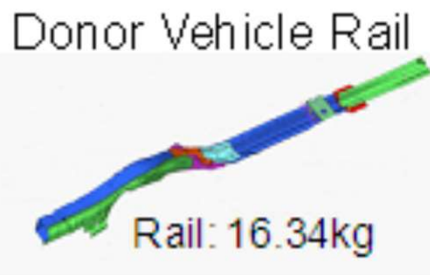
# FSV Development Process

- 3G Optimization: Geometry, Grade, Gauge
  - Auto/Steel Partnership (A/SP) projects
  - Future Generation Passenger Compartment(FGPC) Phases 1 & 2
- Topology Optimization
  - define the optimum load path of a clean sheet design

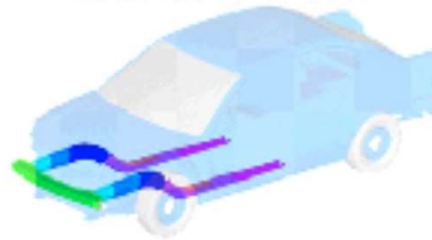


# FSV Pilot Project

- A/SP Lightweight Front End (LWFE) front rail to establish any additional mass savings

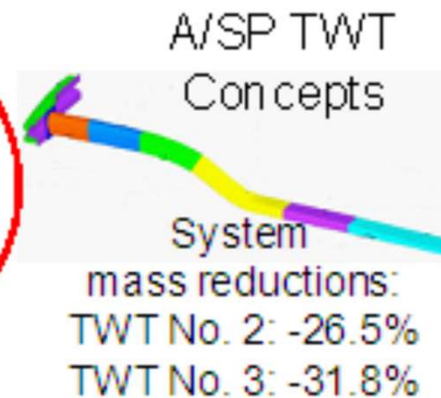
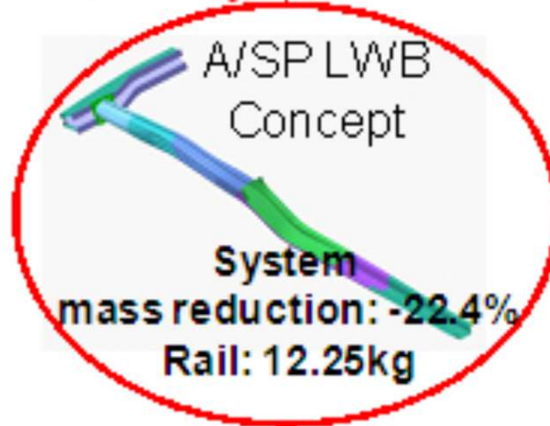


Donor Vehicle



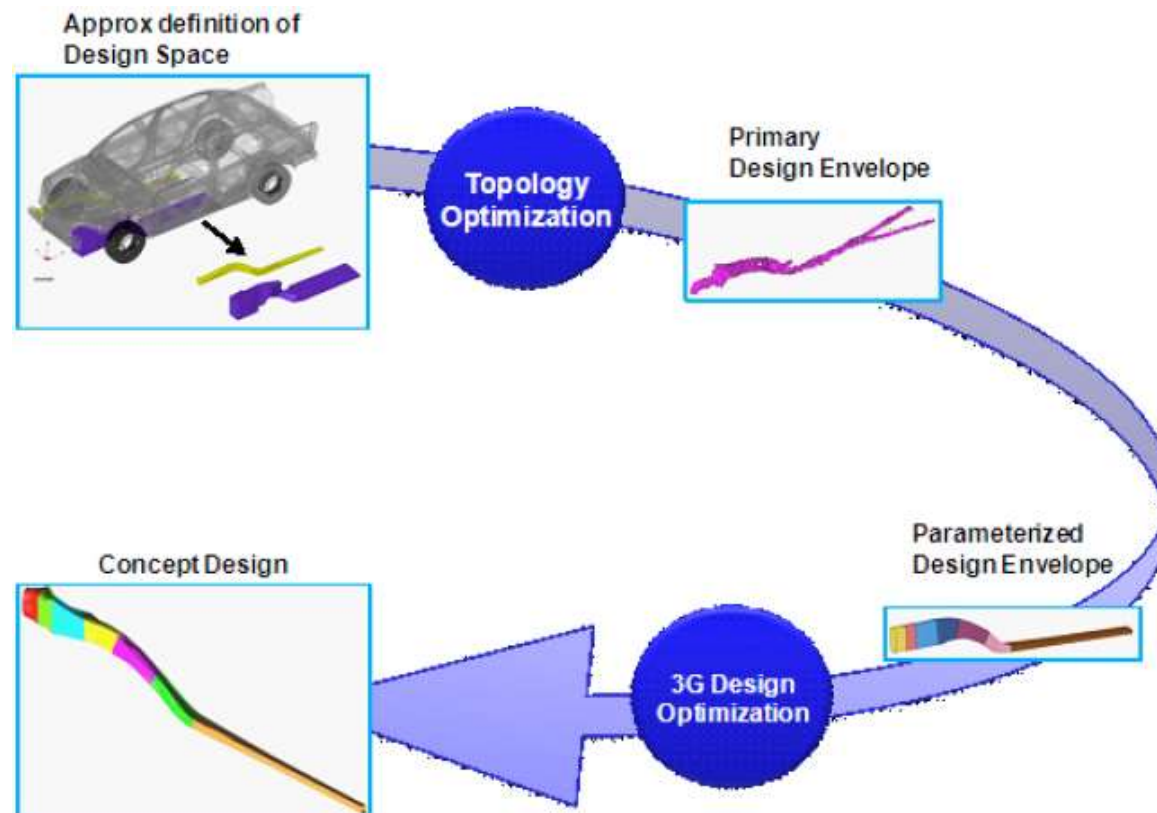
- US-NCAP zero degree front crash
- IIHS front crash 40% ODB
- Torsion
- Bending

## Pilot Project Baseline



# Optimization Methodology

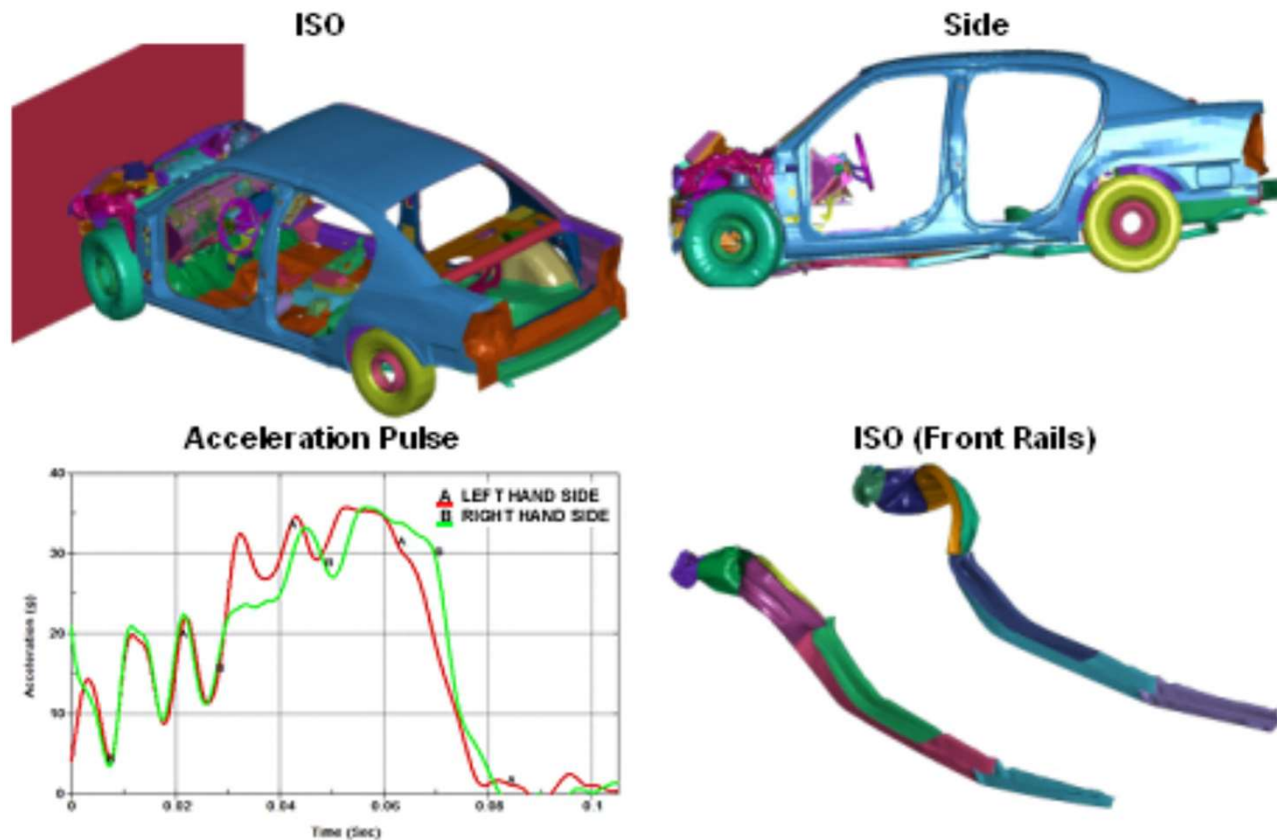
- Block out design envelope
- Topology Optimization
- Parameterize Geometry
- Detailed 3G Optimization: Geometry (Shape), Grade (material) & Gauge





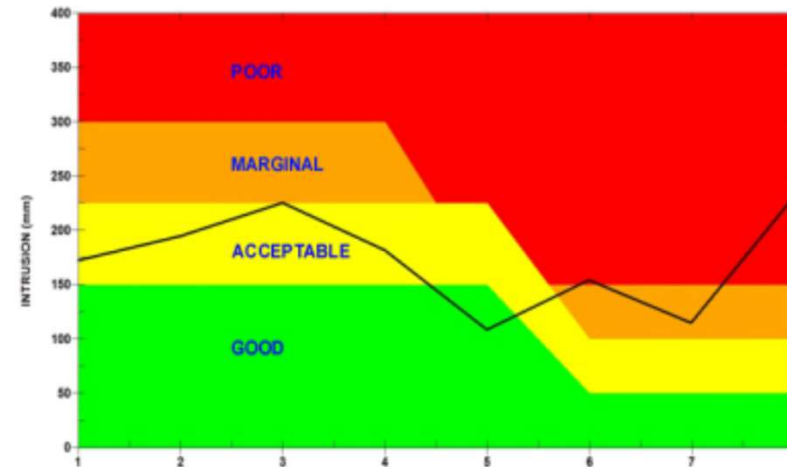
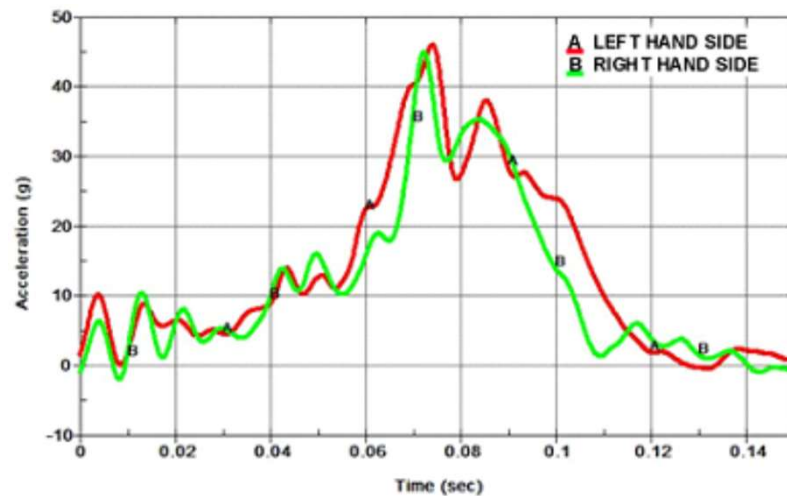
# US-NCAP Zero Degree Front Crash

- impact barrier: fixed rigid wall positioned so that it almost contacts the front tip of the front bumper at the start of the simulation
- Ground: rigid wall positioned at the very lowest points of the tires
- vehicle is impacted into a rigid wall at an initial velocity of 35 mph



# IIHS Front Crash 40% ODB

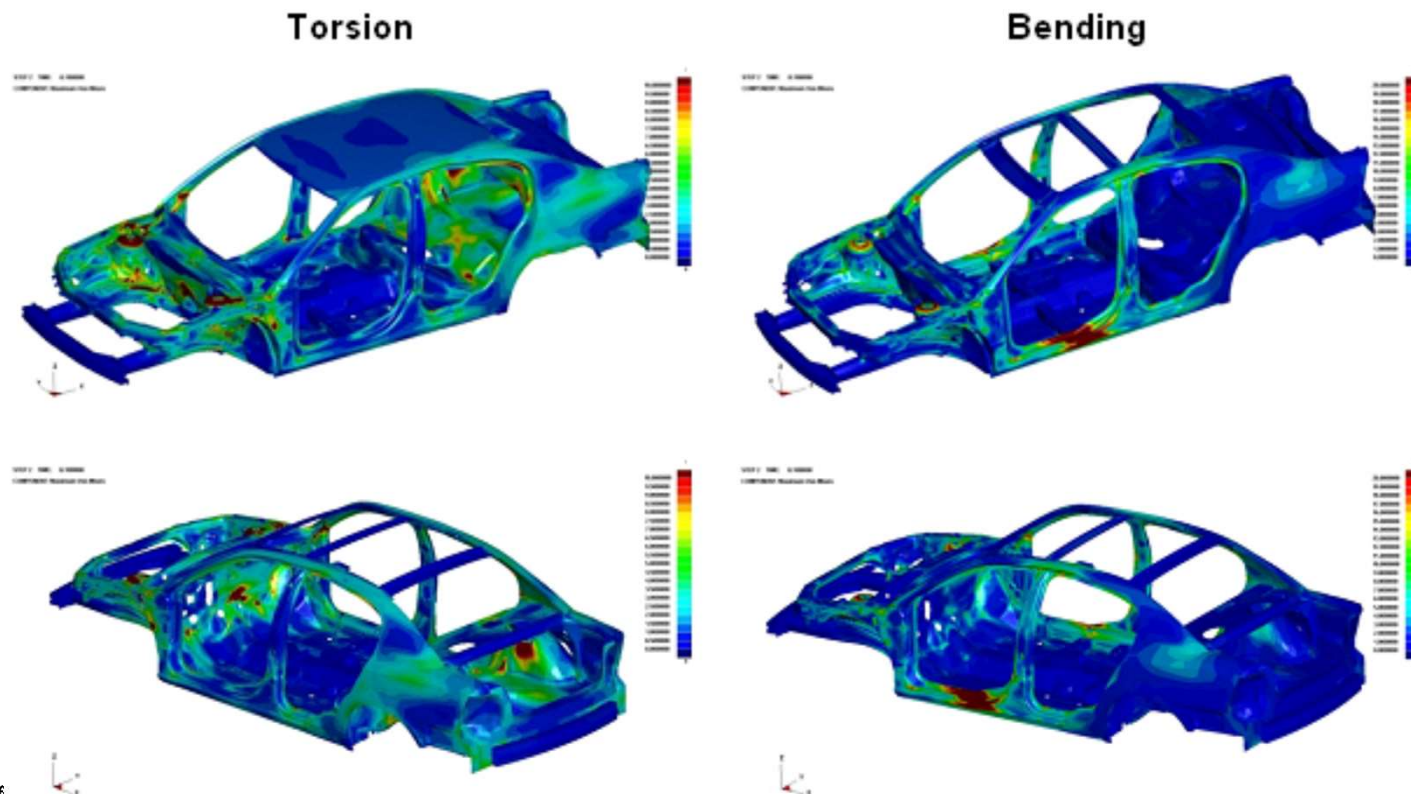
- vehicle impacts a deformable barrier, offset 10% from centerline (40% overlap), at 40 mph



1: Footwell, 2:Left Toe, 3:Center Toe, 4:Right Toe, 5:Brake Pedal, 6:Left IP, 7:Right IP, 8:Door

# Static Stiffness

- Torsion: Vehicle is held at the rear stock towers and front bumper. A couple is applied to the front shock towers.
- Bending: Vehicle is supported at all four shock towers, a load is applied in the vertical (negative z-direction) to the rocker at the front door opening



# Performance Summary

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LOADCASE	PERFORMANCE	
NCAP Front Impact	Max B-Pillar Pulse	
	Left Hand Side	36g
	Right Hand Side	36g
IIHS Front Impact 40% ODB	IIHS Peak Intrusion	
	Left Toepan	15 cm
	Center Toepan	20 cm
	Right Toepan	24 cm
	A-B Pillar Closure	19 cm
Static Stiffness	Torsion	17,788 Nm/deg
	Bending	12,122 N/mm



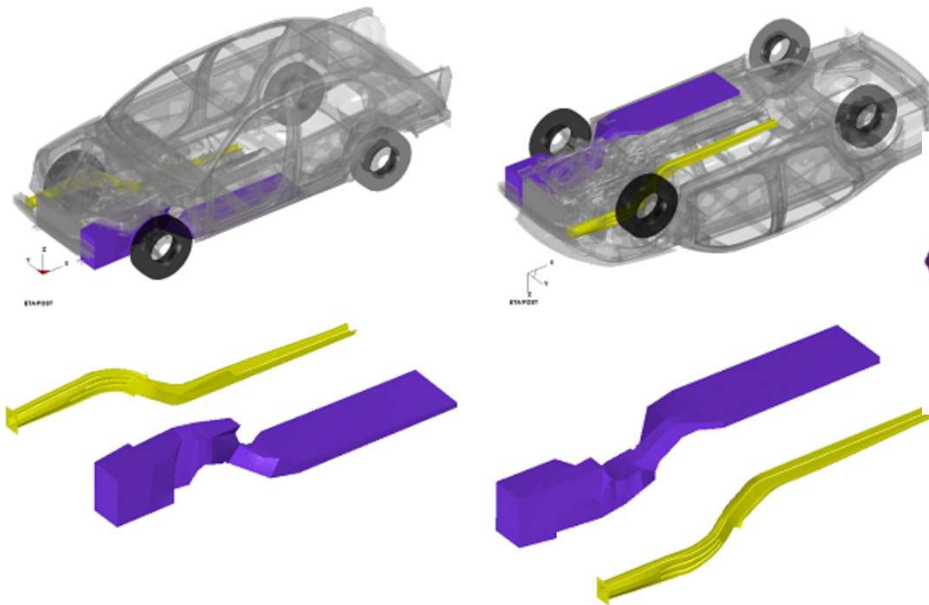
# Topology Optimization

Top View

Bottom View

Comparison:

Existing Front Rail Geometry (shown in yellow)  
Design Space (shown in purple)



Full Vehicle Model  
Dynamic impact analysis

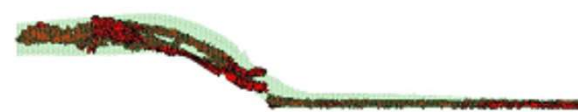
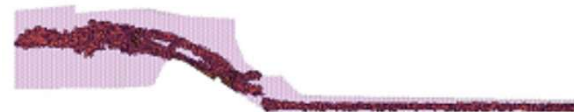
De-Coupled Sub-Model  
Static analysis



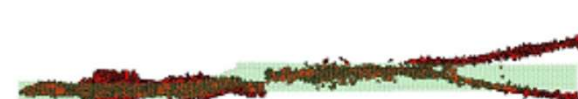
Design Space & Topology Optimization

Original Rail & Topology Optimization

Side View

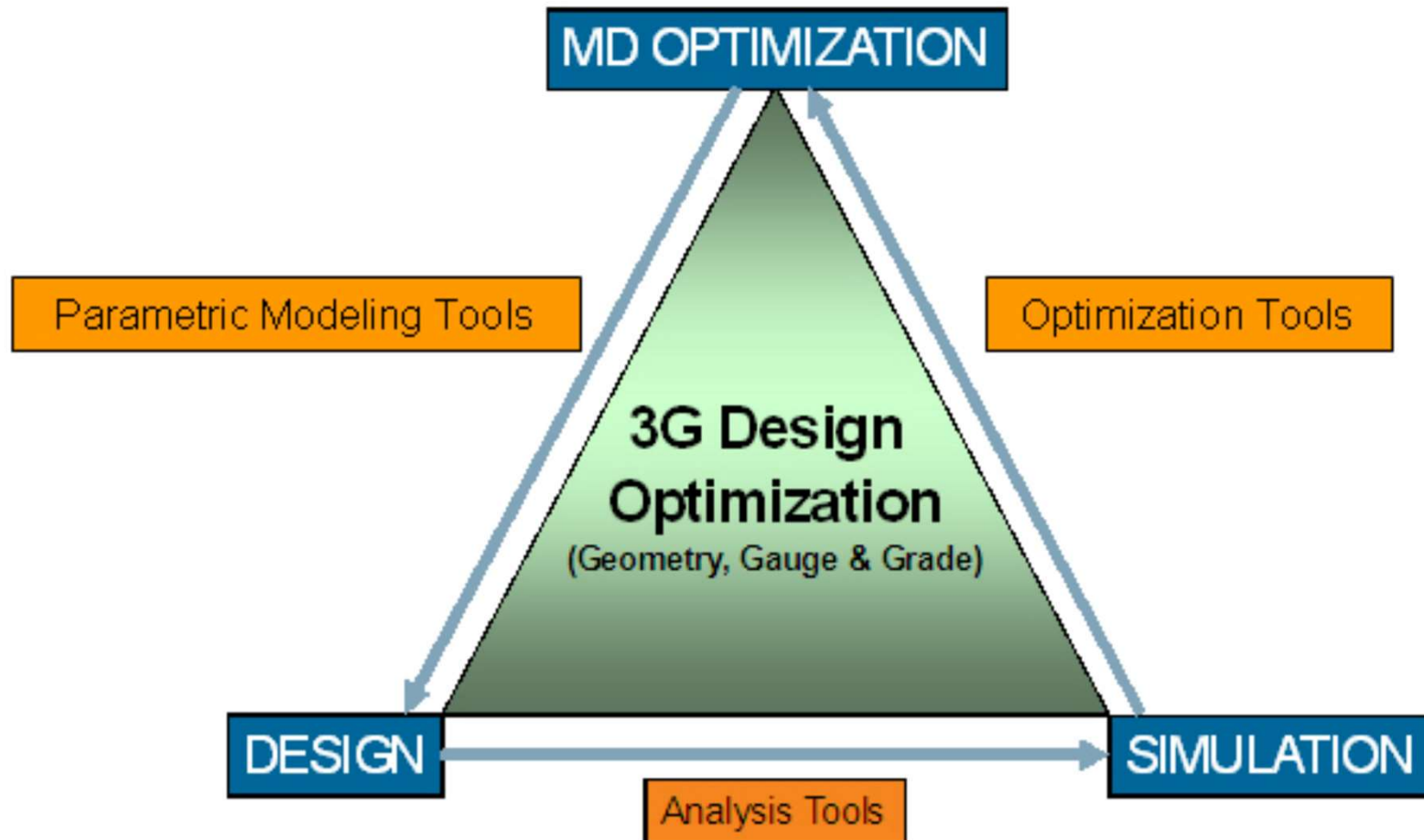


Top View

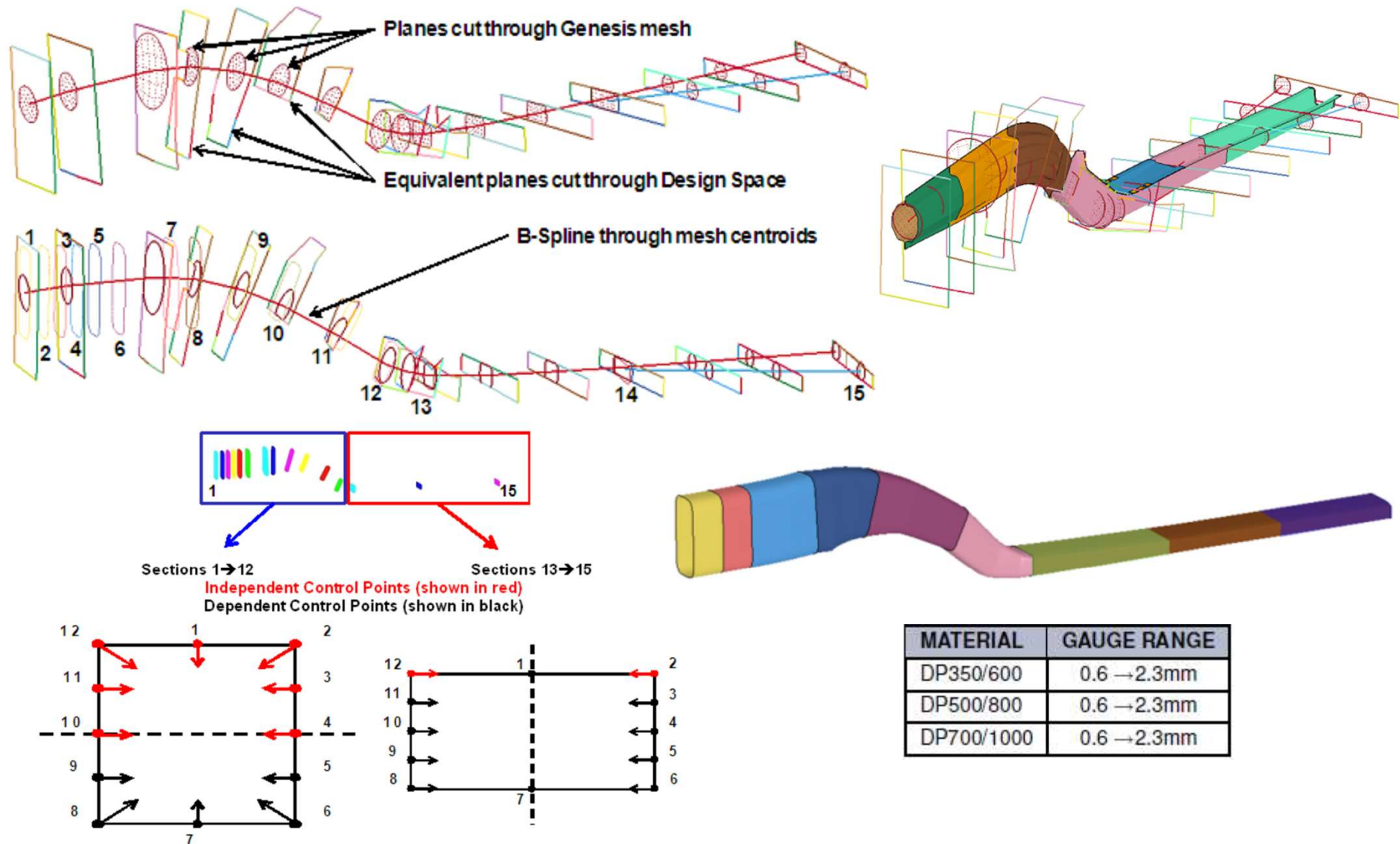


# 3G Optimization

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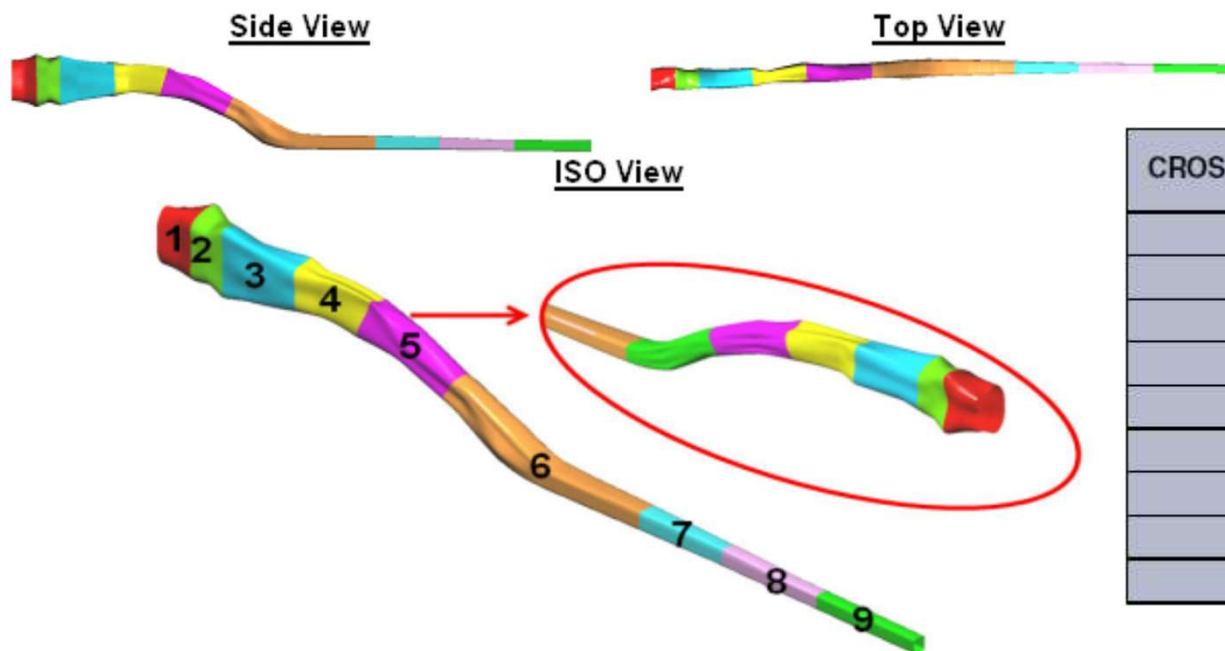


# Load Path Parameterization



# Optimization Problem

Maximize:	Mass Reduction
Subject to:	Section Force $\leq 35\text{kN}$
By Varying:	Cross-sectional Shape (106 variables)
Material:	DP350/600, DP500/800, DP700/1000 (9 variables)
Gauge:	0.6 $\rightarrow$ 2.3 mm (9 variables)

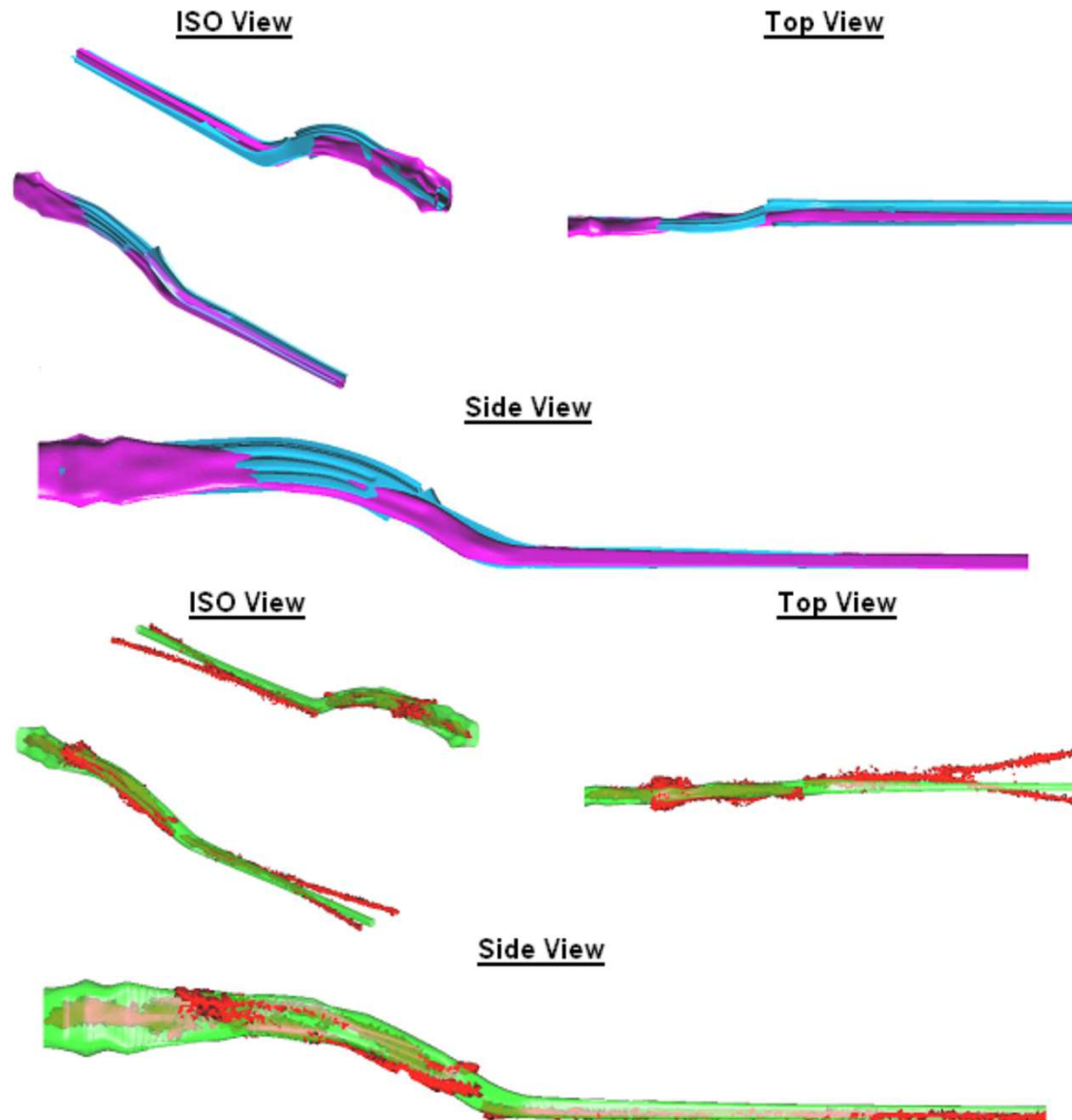


CROSS-SECTION	MATERIAL	GAUGE [mm]	MASS [kg]
1	DP350/600	1	0.48
2	DP500/800	1	0.46
3	DP700/1000	0.7	0.64
4	DP500/800	1.5	0.99
5	DP700/1000	2	1.58
6	DP700/1000	2.3	3.53
7	DP700/1000	1.5	0.69
8	DP700/1000	0.8	0.37
9	DP700/1000	0.6	0.26
TOTAL			8.98



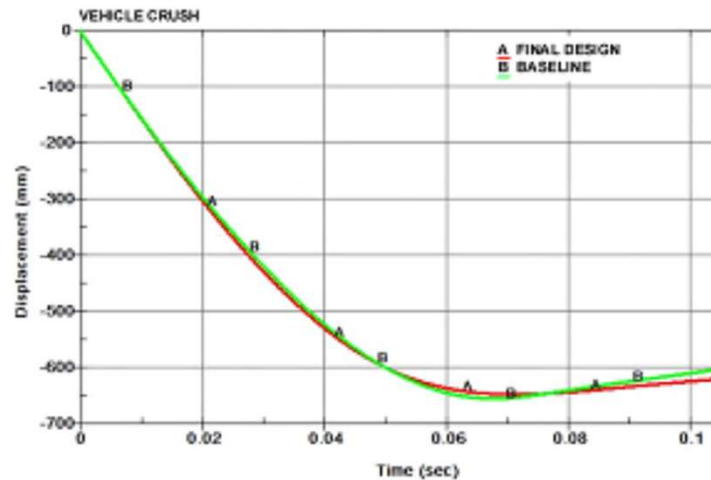
# Optimization Results

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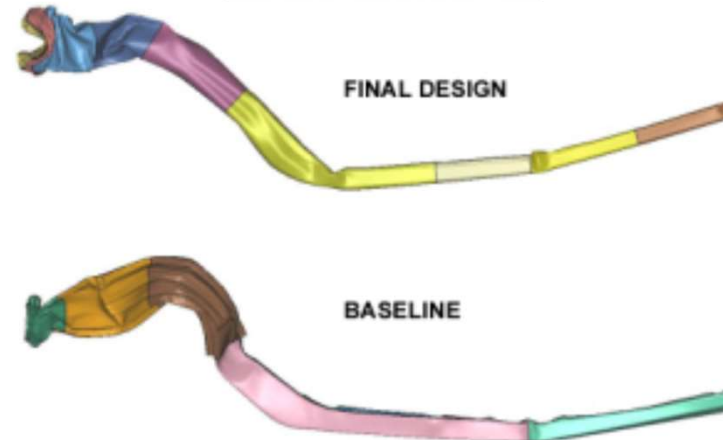


# US-NCAP Zero Degree Front Crash

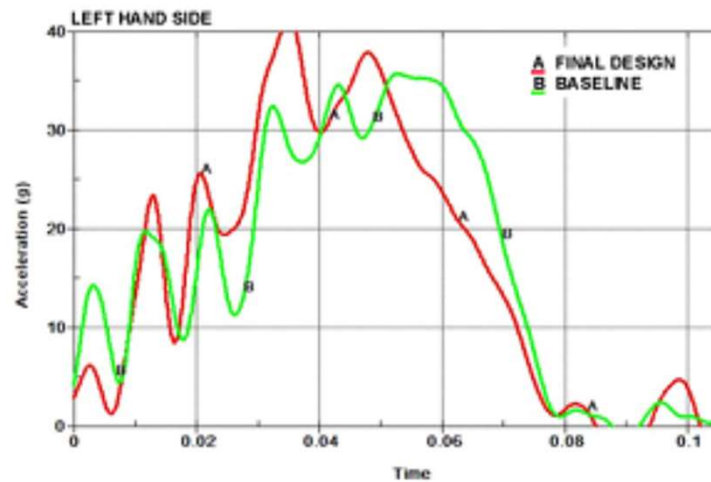
## Vehicle Crush



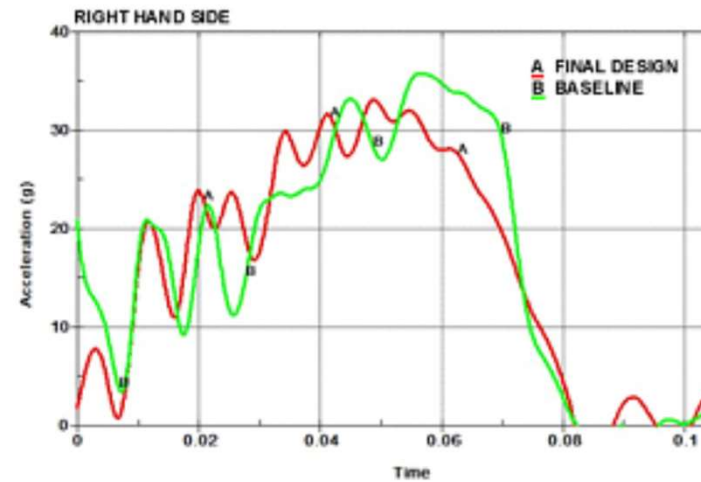
## Deformed Shapes



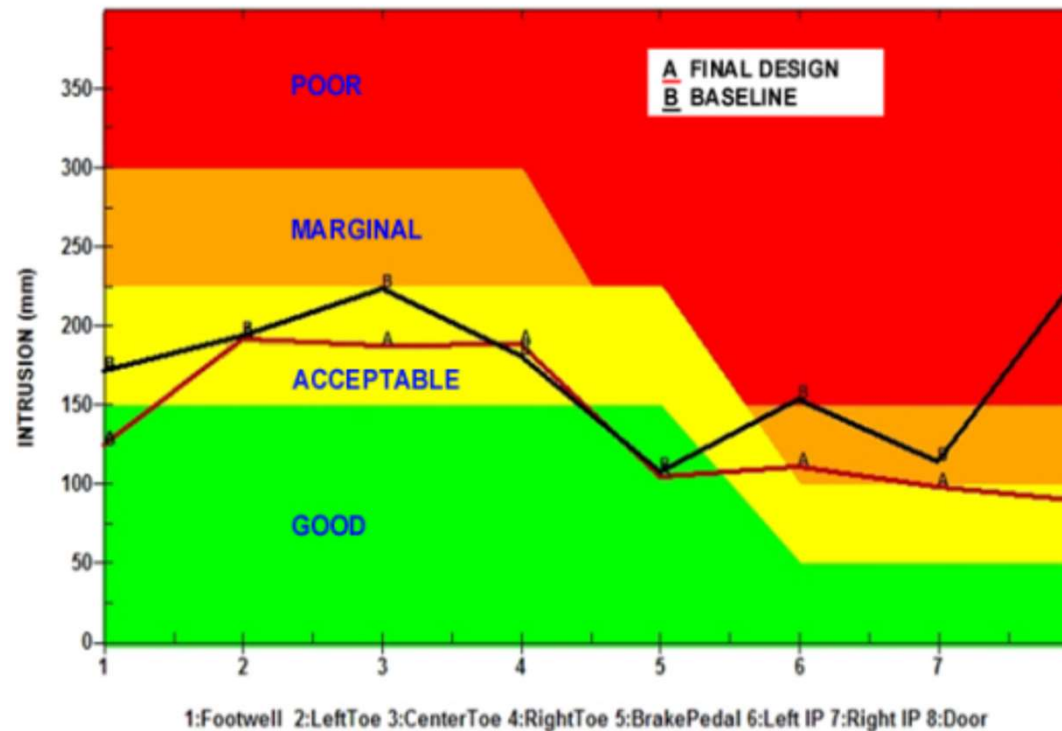
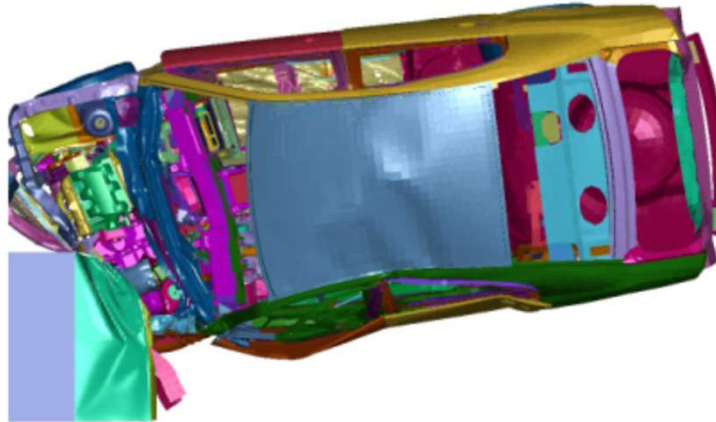
## Left Hand Side Acceleration Pulse



## Right Hand Side Acceleration Pulse

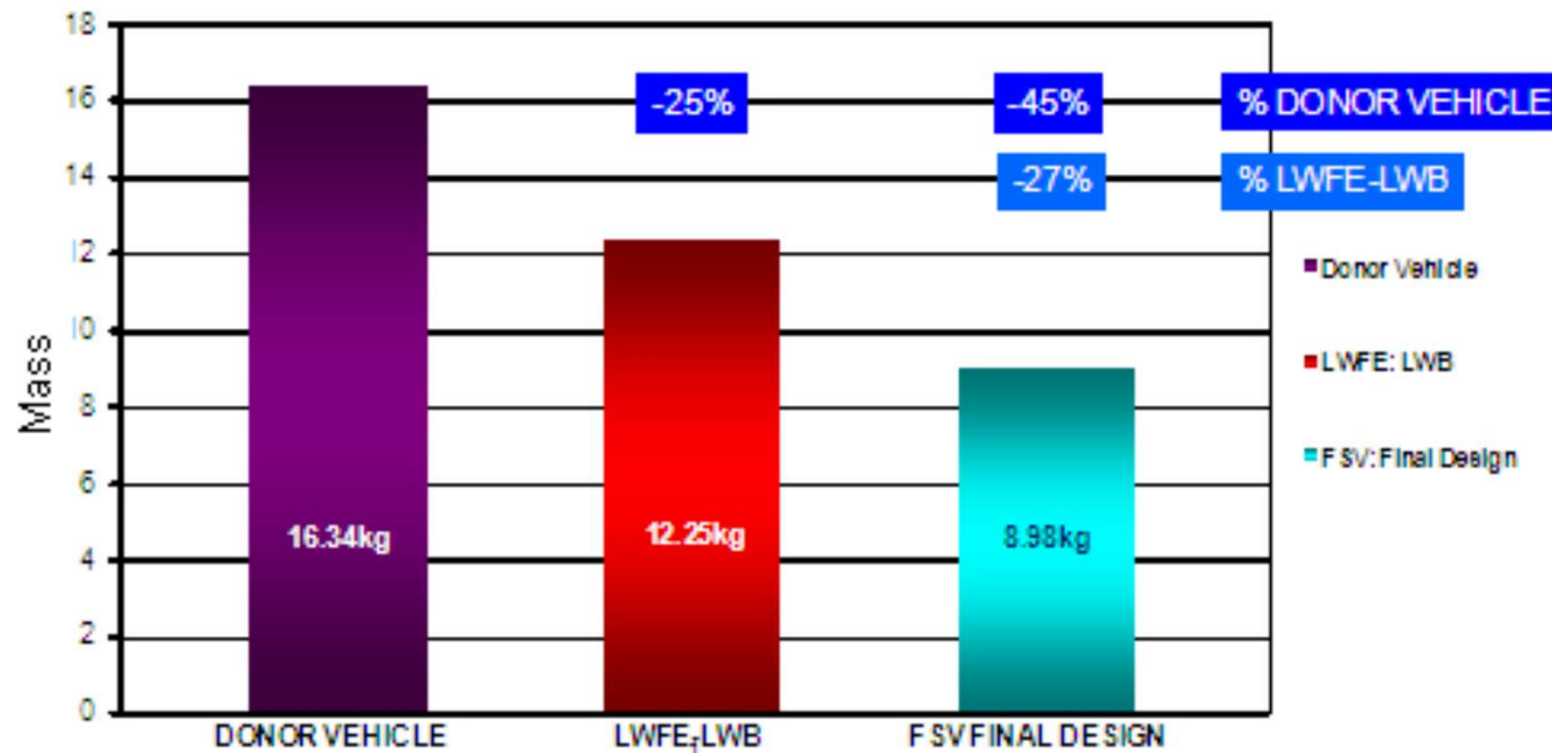


# IIHS Front Crash 40% ODB



# Comparison

- Static Stiffness
  - Torsion(Nm/deg): 17,094  $\leftarrow$  17,788
  - Bending(N/mm): 11,870  $\leftarrow$  12,122





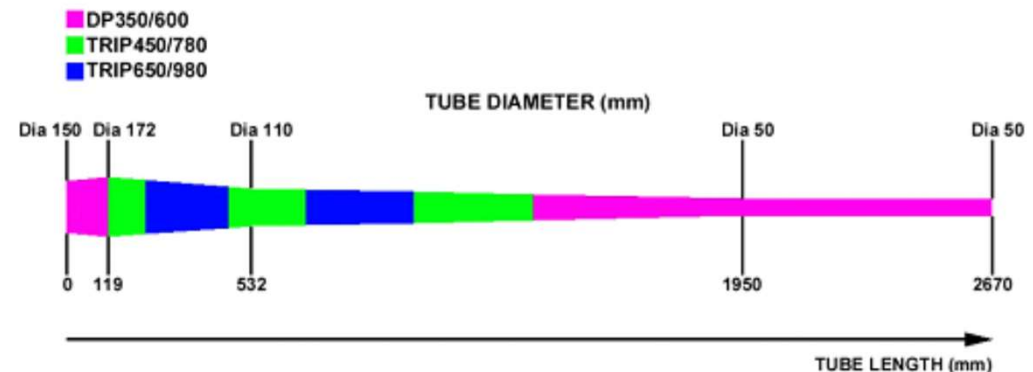
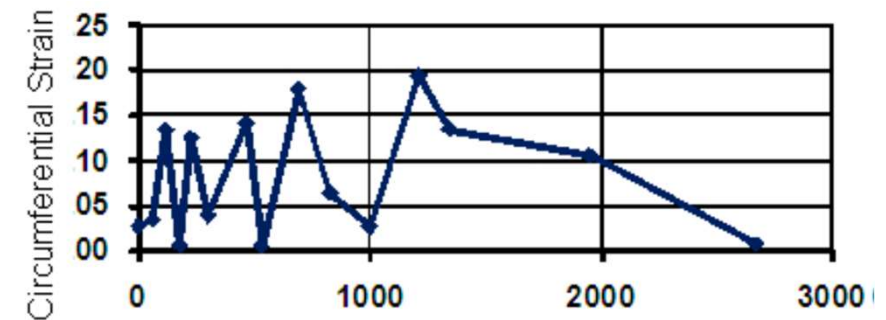
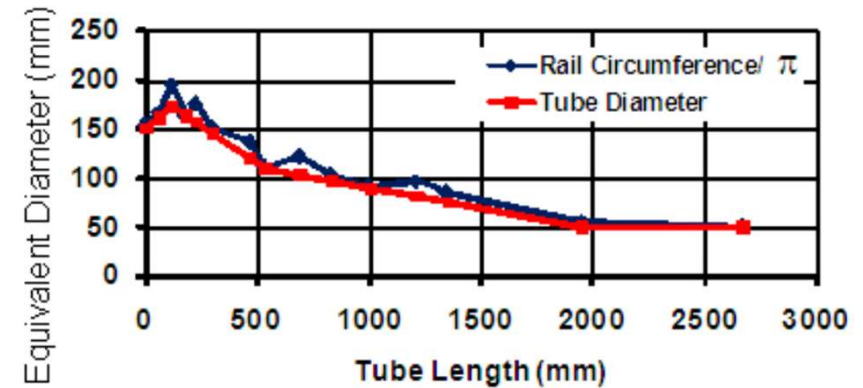
# Manufacturability

- hydro-formed tube concept
  - DP500/800→TRIP450/780
  - DP700/1000→TRIP650/980

CROSS-SECTION	PERIMETER		SECTION-DISTANCE [mm]
	[mm]	[% Change]	
1	483.5	-	
2	522.5	8%	61
3	612.3	17%	58
4	514.7	-16%	60
5	550.8	7%	47
6	471.2	-14%	76
7	429.2	-9%	165
8	347.1	-19%	65
9	382.4	10%	159
10	325.4	-15%	138
11	290.4	-11%	172
12	304.5	5%	212
13	269.1	-12%	134
14	173.6	-35%	603
15	158	-9%	720

\* % change in perimeter from previous cross-section

\*\* Distance between section centroids



# HEEDS Search Algorithm

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- Hybrid
  - Blend of 'methods' used simultaneously, not sequentially
  - Multiple optimization methodologies used; evolutionary methods, simulated annealing, response surface methods, gradient methods & more
  - Takes advantage of best attributes of each approach
  - Global & local search performed together
- Adaptive
  - Each 'method' adapts itself to the design space
  - Master controller determines the contribution of each 'method' to the search process
  - Efficiently learns about design space & effectively searches even very complicated spaces
- Both single and multi-objective capabilities

# Optimization Process

- reduce the number of design evaluations required
  - Depend on the efficiency of the search methodology
- execute multiple design evaluations simultaneously
  - in parallel
- reduce the runtime of each individual analysis
  - simplifying the model, running the analysis in parallel on multiple CPUs, running the analysis for the shortest possible duration

