

1. (1) 목적함수 5점, 구속조건 5점

(design variables) N = number of tubes, R = radius of each tube (cm)

(objective function) maximize surface area of tubes $N(2\pi R)l$ (cm²)

(constraints) $R \geq 0.5$, $N(\pi R^2) \leq 2000$, $N \geq 0$ (integer)

$$\left. \begin{array}{l} \text{maximize } S = N(2\pi R)l \\ \text{subject to} \\ R \geq 0.5 \\ N(\pi R^2) \leq 2000 \\ N \geq 0 \end{array} \right\} \rightarrow \left\{ \begin{array}{l} \text{minimize } f = -2\pi lNR \\ \text{subject to} \\ g_1 = 0.5 - R \leq 0 \\ g_2 = \pi NR^2 - 2000 \leq 0 \\ g_3 = -N \leq 0 \end{array} \right\}$$

(2)

(design variables) x_1 = product A in kg, x_2 = product B in kg

(objective function) maximize the profit = $10x_1 + 8x_2$

(constraints) $0.4x_1 + 0.5x_2 \leq 100$ (raw material C), $0.6x_1 + 0.5x_2 \leq 80$ (raw material D),

$0 \leq x_1 \leq 70$, $0 \leq x_2 \leq 110$ (limits on products)

(3)

Design variables: x_{ij} = number of items produced at the i -th facility shipped to j -th distribution center

where $i = 1$ to m , $j = 1$ to n

$$\text{Objective function: cost} = \sum_{i=1}^m \sum_{j=1}^n c_{ij} x_{ij} \quad i = 1, \dots, m, j = 1, \dots, n$$

Constraints:

$$\text{(capacity of manufacturing facility)} \quad \sum_{j=1}^n x_{ij} \leq b_i \quad i = 1, \dots, m$$

$$\text{(demand)} \quad \sum_{i=1}^m x_{ij} \geq a_j \quad j = 1, \dots, n$$

$$\text{(side)} \quad x_{ij} \geq 0 \quad \text{for all } i \text{ and } j$$

2.

$$\nabla f = \begin{bmatrix} 3x_1^2 + 4x_1 \\ 3x_2^2 + 8x_2 \end{bmatrix} = 0 \rightarrow (0,0), (0, -\frac{8}{3}), (-\frac{4}{3}, 0), (-\frac{4}{3}, -\frac{8}{3}), \nabla^2 f = \begin{bmatrix} 6x_1 + 4 & 0 \\ 0 & 6x_2 + 8 \end{bmatrix}$$

x	Hessian	nature	$f(x)$
(0, 0)	Positive definite	Local minimum	6
(0, -8/3)	Indefinite	Saddle point	418/27
(-4/3, 0)	Indefinite	Saddle point	194/27
(-4/3, -8/3)	Negative definite	Local maximum	50/3

3.

$$\begin{cases} \text{unscaled problem: } \nabla f + u_u \nabla h = 0 \rightarrow \nabla f = -u_u \nabla h \\ \text{scaled problem: } k_1 \nabla f + u_s k_2 \nabla h = 0 \rightarrow (-u_u k_1 + u_s k_2) \nabla h = 0 \end{cases}$$

assuming that at a solution point $\nabla h \neq 0$, $-u_u k_1 + u_s k_2 = 0 \rightarrow u_s = \frac{k_1}{k_2} u_u$

4. $\mathbf{x}^* = (0, 0)$ is not an optimal point. (10 pts.)

$$L = (x_1 - 1)^2 + x_2^2 + u(x_1 - x_2^2 + s^2)$$

$$x = (0, 0) \rightarrow s = 0$$

(necessary condition)

$$\left. \begin{aligned} \partial L / \partial x_1 &= 2(x_1 - 1) + u = 0 \\ \partial L / \partial x_2 &= 2x_2 - 2ux_2 = 0 \\ x_1 - x_2^2 + s^2 &= 0 \\ us &= 0 \end{aligned} \right\} \rightarrow \begin{cases} u = 2 \geq 0 \\ \text{satisfy!} \end{cases}$$

(sufficient condition)

$$\nabla^2 L = \begin{bmatrix} 2 & 0 \\ 0 & 2 - 2u \end{bmatrix} \rightarrow \nabla^2 L(x^*, u^*) = \begin{bmatrix} 2 & 0 \\ 0 & -2 \end{bmatrix} : \text{indefinite}$$

$$\nabla g(x^*)^T y = 0 \rightarrow \begin{bmatrix} 1 & 0 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \end{bmatrix} = 0 \rightarrow y = \begin{bmatrix} 0 \\ y_2 \end{bmatrix}$$

$$y^T \nabla^2 L y = \begin{bmatrix} 0 & y_2 \end{bmatrix} \begin{bmatrix} 2 & 0 \\ 0 & -2 \end{bmatrix} \begin{bmatrix} 0 \\ y_2 \end{bmatrix} = -2y_2^2 < 0 : \text{NOT satisfy!}$$

5.

(1) problem formulation

$$\text{Minimize } f = 400(0.5\pi D^2 + \pi DH)$$

$$\text{subject to } h_1 = \frac{\pi D^2 H}{4} - 250\pi = 0$$

$$g_1 = H - 8D \leq 0$$

(2) check for convexity: nonlinear equality constraint $\rightarrow$ nonconvex

$$\nabla f = \begin{bmatrix} 400\pi D + 400\pi H \\ 400\pi D \end{bmatrix}, \quad \nabla^2 f = \begin{bmatrix} 400\pi & 400\pi \\ 400\pi & 0 \end{bmatrix}$$

since Hessian of the objective function is NOT positive definite,
this is NOT a convex programming problem.

(3) KT necessary conditions

$$L = 400(0.5\pi D^2 + \pi DH) + v_1 \left(\frac{\pi D^2 H}{4} - 250\pi \right) + u_1 (H - 8D)$$

$$\frac{\partial L}{\partial D} = 400\pi D + 400\pi H + v_1 \frac{\pi DH}{2} + u_1 (-8) = 0$$

$$\frac{\partial L}{\partial H} = 400\pi D + v_1 \frac{\pi D^2}{4} + u_1 = 0$$

$$h_1 = 0$$

$$g_1 \leq 0, \quad u_1 g_1 = 0, \quad u_1 \geq 0$$

(4) solve the KT conditions

$$i) g_1 = 0 \rightarrow H = 8D \rightarrow D = 5, H = 40, v_1 = -226.7, u_1 = -1832.5 < 0 (\times)$$

$$ii) u_1 = 0 \rightarrow D = H = 10, v_1 = -160, g_1 = H - 8D = -70 < 0 \rightarrow f^* = 60000\pi$$

sufficiency check:

$$\nabla^2 L = \nabla^2 f + v_1 \nabla^2 h_1 = \begin{bmatrix} 400\pi & 400\pi \\ 400\pi & 0 \end{bmatrix} - 160 \begin{bmatrix} 0.5\pi H & 0.5\pi D \\ 0.5\pi D & 0 \end{bmatrix} = \begin{bmatrix} 400\pi - 80\pi H & 400\pi - 80\pi D \\ 400\pi - 80\pi D & 0 \end{bmatrix}$$

$$\nabla^2 L(\mathbf{x}^*) = \begin{bmatrix} -400\pi & -400\pi \\ -400\pi & 0 \end{bmatrix} : \text{NOT positive definite!}$$

$$\nabla h_1(\mathbf{x}^*)^T \mathbf{d} = 25\pi \begin{bmatrix} 2 & 1 \end{bmatrix} \begin{bmatrix} d_1 \\ d_2 \end{bmatrix} = 0 \rightarrow \mathbf{d} = c \begin{bmatrix} 1 & -2 \end{bmatrix}^T$$

$$\mathbf{d}^T \nabla^2 L(\mathbf{x}^*) \mathbf{d} = -400\pi c^2 \begin{bmatrix} 1 & -2 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ -2 \end{bmatrix} = 1200\pi c^2 > 0 \rightarrow \text{isolated local minimum}$$

(5) post-optimality analysis

$$h_1 : 250\pi \rightarrow 255\pi$$

$$\Delta f = -v_1 \Delta b = -(-160)(255\pi - 250\pi) = 800\pi$$

