

# MATLAB PDE Solving

Boundary Value Problems

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HANYANG UNIVERSITY



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- **Boundary Value Problems for PDE**
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# LAPLACE EQUATION

– PDE  $\rightarrow$  algebraic difference equation

$$\frac{\partial^2 T}{\partial x^2} + \frac{\partial^2 T}{\partial y^2} = 0 \leftarrow \begin{cases} \frac{\partial^2 T}{\partial x^2} = \frac{T_{i+1,j} - 2T_{i,j} + T_{i-1,j}}{\Delta x^2} \\ \frac{\partial^2 T}{\partial y^2} = \frac{T_{i,j+1} - 2T_{i,j} + T_{i,j-1}}{\Delta y^2} \end{cases}$$

$$\rightarrow \frac{T_{i+1,j} - 2T_{i,j} + T_{i-1,j}}{\Delta x^2} + \frac{T_{i,j+1} - 2T_{i,j} + T_{i,j-1}}{\Delta y^2} = 0$$

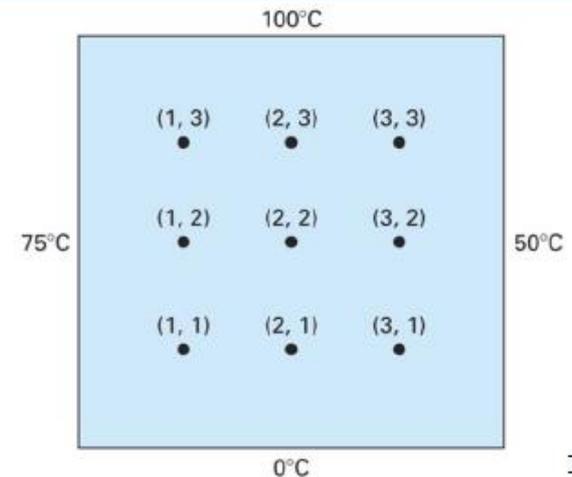
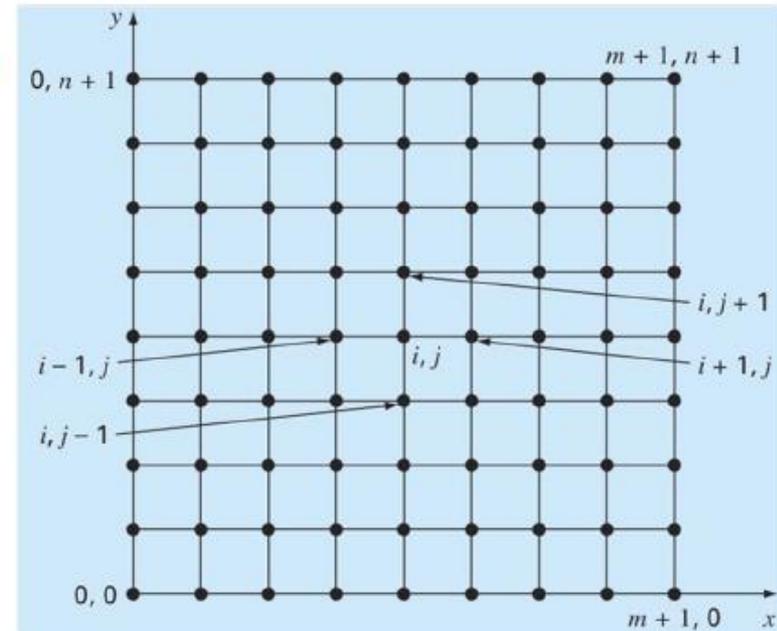
$$\xrightarrow{\Delta x = \Delta y} T_{i+1,j} + T_{i-1,j} + T_{i,j+1} + T_{i,j-1} - 4T_{i,j} = 0$$

apply boundary conditions (fixed/Dirichlet)

$$\begin{aligned} @ (1,1): T_{21} + \underbrace{T_{01}}_{75^\circ\text{C}} + T_{12} + \underbrace{T_{10}}_{0^\circ\text{C}} - 4T_{11} &= 0 \rightarrow 4T_{11} - T_{21} - T_{12} = 75 \\ @ (2,1): T_{31} + T_{11} + T_{22} + \underbrace{T_{20}}_{0^\circ\text{C}} - 4T_{21} &= 0 \rightarrow -T_{11} + 4T_{21} - T_{31} - T_{22} = 0 \\ @ (3,1): \underbrace{T_{41}}_{50^\circ\text{C}} + T_{21} + T_{32} + \underbrace{T_{30}}_{0^\circ\text{C}} - 4T_{31} &= 0 \rightarrow -T_{21} + 4T_{31} - T_{32} = 50 \\ &\vdots \\ &9 \text{ equations} \end{aligned}$$

$$[K_{ij}] \{T_i\} = \{f_i\}$$

$[K_{ij}]$ : coefficient matrix,  $\{T_i\}$ : solution vector,  $\{f_i\}$ : force vector



# MATLAB CODE

```

1 -   clc; clear all;
2 -   T_left = 75; T_right = 50; T_bottom = 0; T_upper = 100;
3 -   nx = 3; ny = 3;
4 -   T_numbering = [];
5 -   iter = 0;
6 -   i = [1:nx]';
7 -   j = ones(nx,1);
8 -   for k = 1:ny
9 -       T_numbering = [T_numbering;i,j+k];
10 -   end
11 -   f = zeros(nx+ny,1);
12 -   for j = 1:ny
13 -       for i = 1:nx
14 -           T_numbering(:,3) = zeros(nx+ny,1);
15 -           a = find(T_numbering(:,1) == i+1 & T_numbering(:,2) == j);
16 -           b = find(T_numbering(:,1) == i-1 & T_numbering(:,2) == j);
17 -           c = find(T_numbering(:,1) == i & T_numbering(:,2) == j+1);
18 -           d = find(T_numbering(:,1) == i & T_numbering(:,2) == j-1);
19 -           e = find(T_numbering(:,1) == i & T_numbering(:,2) == j);
20 -           T_numbering(a,3) = -1;
21 -           T_numbering(b,3) = -1;
22 -           T_numbering(c,3) = -1;
23 -           T_numbering(d,3) = -1;
24 -           T_numbering(e,3) = 4;
25 -           iter = iter + 1;
26 -           K(iter,:) = T_numbering(:,3)';
27 -           if length(a) == 0
28 -               f(iter) = f(iter) + T_right;
29 -           end

```

```

30 -           if length(b) == 0
31 -               f(iter) = f(iter) + T_left;
32 -           end
33 -           if length(c) == 0
34 -               f(iter) = f(iter) + T_upper;
35 -           end
36 -           if length(d) == 0
37 -               f(iter) = f(iter) + T_bottom;
38 -           end
39 -       end
40 -   end
41 -   Temp_temp1 = K\wf;
42 -   iter = 0;
43 -   for i = ny:-1:1
44 -       for j = 1:nx
45 -           iter = iter + 1;
46 -           Temp_temp2(i,j) = Temp_temp1(iter,1);
47 -       end
48 -   end
49 -   Temp = zeros(ny+2,nx+2);
50 -   Temp(:,1) = T_left;
51 -   Temp(:,nx+2) = T_right;
52 -   Temp(1,:) = T_upper;
53 -   Temp(ny+2,:) = T_bottom;
54 -   Temp(2:ny+1,2:nx+1) = Temp_temp2;
55 -   x=[0:1:nx+1]; y=[ny+1:-1:0];
56 -   surf(x,y,Temp)
57 -   xlabel('x'); ylabel('y'); zlabel('Temp'); colorbar

```

# INITIALIZATION

```
clc; clear all;
```

```
T_left = 75; T_right = 50; T_bottom = 0; T_upper = 100;
```

```
nx = 3; ny = 3;
```



```
T_numbering = [];
iter = 0;
```

```
i = [1:nx]';
j = ones(nx,1);
```

```
for k = 1:ny
    T_numbering = [T_numbering;i,j*k];
end
```

```
f = zeros(nx*ny,1);
```



	1	2
1	1	1
2	2	1
3	3	1
4	1	2
5	2	2
6	3	2
7	1	3
8	2	3
9	3	3

numbering



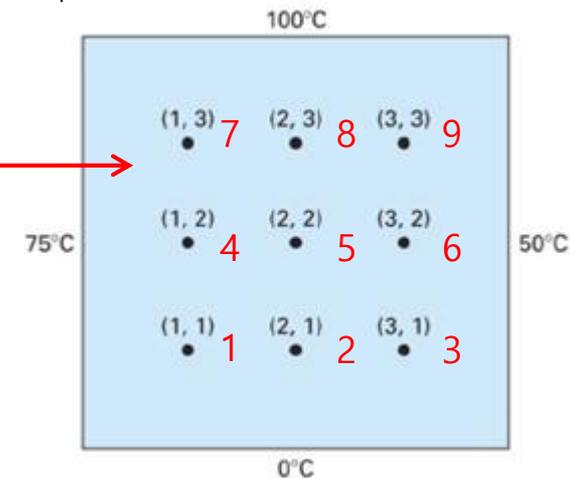
경계조건 선언



경계를 제외한 node 개수 선언



매트릭스를 구성하기 위한 정보를 저장



# COEFFICIENT MATRIX

```
for j = 1:ny
for i = 1:nx
```

```
    T_numbering(:,3) = zeros(nx*ny,1);
    a = find(T_numbering(:,1) == i+1 & T_numbering(:,2) == j);
    b = find(T_numbering(:,1) == i-1 & T_numbering(:,2) == j);
    c = find(T_numbering(:,1) == i & T_numbering(:,2) == j+1);
    d = find(T_numbering(:,1) == i & T_numbering(:,2) == j-1);
    e = find(T_numbering(:,1) == i & T_numbering(:,2) == j);
    T_numbering(a,3) = -1;
    T_numbering(b,3) = -1;
    T_numbering(c,3) = -1;
    T_numbering(d,3) = -1;
    T_numbering(e,3) = 4;
    iter = iter + 1;
```

```
1 K(iter,:) = T_numbering(:,3)';
```



K 매트릭스 생성

$$[K_{ij}]\{T_i\} = \{f_i\}$$



nx = 3, ny = 3 일 때의 매트릭스 요소 정보

numbering

	1	2
1	1	1
2	2	1
3	3	1
4	1	2
5	2	2
6	3	2
7	1	3
8	2	3
9	3	3

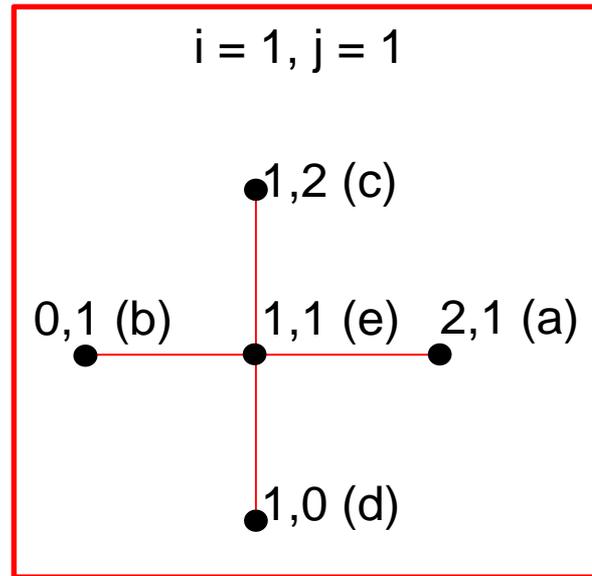
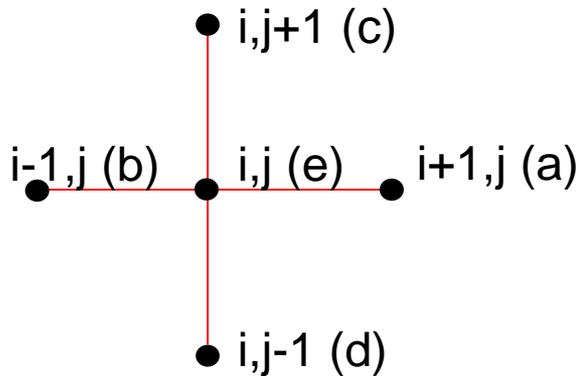
	2	3	4	5	6	7	8	9
1	4	-1	0	-1	0	0	0	0
2	-1	4	-1	0	-1	0	0	0
3	0	-1	4	0	-1	0	0	0
4	-1	0	0	4	-1	0	-1	0
5	0	-1	0	-1	4	-1	0	-1
6	0	0	-1	0	-1	4	0	-1
7	0	0	0	-1	0	0	4	-1
8	0	0	0	0	-1	0	-1	4
9	0	0	0	0	0	-1	0	-1

# COEFFICIENT MATRIX

```

a = find(T_numbering(:,1) == i+1 & T_numbering(:,2) == j);
b = find(T_numbering(:,1) == i-1 & T_numbering(:,2) == j);
c = find(T_numbering(:,1) == i & T_numbering(:,2) == j+1);
d = find(T_numbering(:,1) == i & T_numbering(:,2) == j-1);
e = find(T_numbering(:,1) == i & T_numbering(:,2) == j);

```



find 는 벡터 혹은 매트릭스  
내 요소 중 같은 값을 갖는  
요소의 위치정보를 저장하  
는 명령어

$i = 1, j = 1$  일 때  
T\_numbering 벡터의 위치  
정보를 저장

	1	2	
e	1	1	1
a	2	2	1
	3	3	1
c	4	1	2
	5	2	2
	6	3	2
	7	1	3
	8	2	3
	9	3	3

a=2  
b=[]  
c=4  
d=[]  
e=1

# COEFFICIENT MATRIX

$T\_numbering(a,3) = -1;$   
 $T\_numbering(b,3) = -1;$   
 $T\_numbering(c,3) = -1;$   
 $T\_numbering(d,3) = -1;$   
 $T\_numbering(e,3) = 4;$



	1	2	3
1	1	1	4
2	2	1	-1
3	3	1	0
4	1	2	-1
5	2	2	0
6	3	2	0
7	1	3	0
8	2	3	0
9	3	3	0



위치 정보를 이용하여 계수 값을  $T\_numbering$  내에 입력



입력된 3번째 벡터를 coefficient matrix 의 첫 번째 열로 저장

$$@ (1,1): T_{21} + \frac{T_{01}}{75^{\circ}\text{C}} + T_{12} + \frac{T_{10}}{0^{\circ}\text{C}} - 4T_{11} = 0 \rightarrow 4T_{11} - T_{21} - T_{12} = 75$$

$$@ (2,1): T_{31} + T_{11} + T_{22} + \frac{T_{20}}{0^{\circ}\text{C}} - 4T_{21} = 0 \rightarrow -T_{11} + 4T_{21} - T_{31} - T_{22} = 0$$

$$@ (3,1): \frac{T_{41}}{50^{\circ}\text{C}} + T_{21} + T_{32} + \frac{T_{30}}{0^{\circ}\text{C}} - 4T_{31} = 0 \rightarrow -T_{21} + 4T_{31} - T_{32} = 50$$

⋮

9 equations

$K(\text{iter},:) = T\_numbering(:,3)'$



	1	2	3	4	5	6	7	8	9
1	4	-1	0	-1	0	0	0	0	0

$$\begin{bmatrix} k_{11} & k_{12} & \cdots & k_{12N} \\ k_{21} & k_{22} & & k_{22N} \\ \vdots & & \ddots & \\ k_{2N1} & k_{2N2} & & k_{2N2N} \end{bmatrix} \begin{bmatrix} u_1^{(1)} \\ u_2^{(1)} \\ \vdots \\ u_2^{(N)} \end{bmatrix} = \begin{bmatrix} r_1 \\ r_2 \\ \vdots \\ r_4 \end{bmatrix}$$

# FORCE VECTOR

```

if length(a) == 0
    f(iter) = f(iter) + T_right;
end
if length(b) == 0
    f(iter) = f(iter) + T_left;
end
if length(c) == 0
    f(iter) = f(iter) + T_upper;
end
if length(d) == 0
    f(iter) = f(iter) + T_bottom;
end
    
```

※ example

a=2  
b=[]  
c=4  
d=[]  
e=1

if length(a) == 0  
If isempty(a)

0  
1  
0  
1  
0



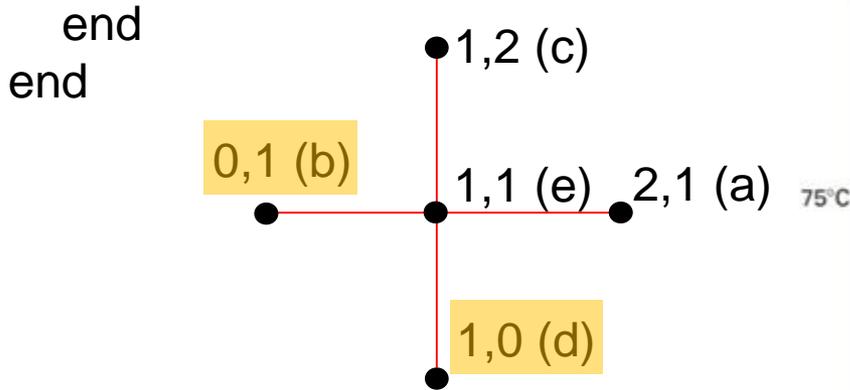
경계조건을 입력할 번호를 구분, length 명령어를 이용하여 값이 0 일 경우 경계에 존재하는 번호 (또는 isempty 함수사용)

a 가 경계일 경우 항상 오른쪽 경계  
마찬가지 논리로 입력할 경계 위치를 결정

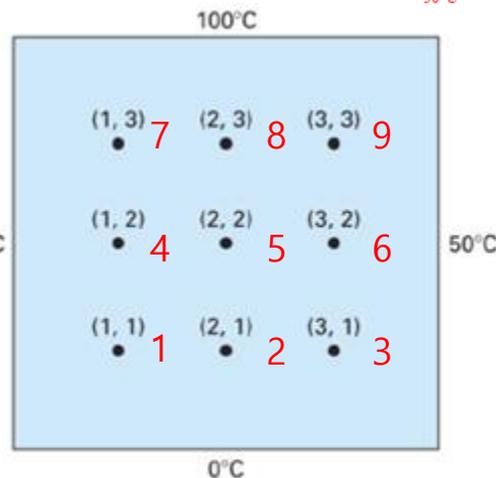
$$@(1,1): T_{21} + \frac{T_{01}}{75^\circ\text{C}} + T_{12} + \frac{T_{10}}{0^\circ\text{C}} - 4T_{11} = 0 \rightarrow 4T_{11} - T_{21} - T_{12} = 75$$

$$@(2,1): T_{31} + T_{11} + T_{22} + \frac{T_{20}}{0^\circ\text{C}} - 4T_{21} = 0 \rightarrow -T_{11} + 4T_{21} - T_{31} - T_{22} = 0$$

$$@(3,1): \frac{T_{41}}{50^\circ\text{C}} + T_{21} + T_{32} + \frac{T_{30}}{0^\circ\text{C}} - 4T_{31} = 0 \rightarrow -T_{21} + 4T_{31} - T_{32} = 50$$



경계조건이 입력될 부분



1	
1	75
2	0
3	50
4	75
5	0
6	50
7	175
8	100
9	150

# POST-PROCESSING

```
Temp_temp1 = K\f;
```



$$[K_{ij}]\{T_i\} = \{f_i\} \rightarrow \{T_i\} = [K_{ij}]^{-1} \{f_i\}$$



solve

```
iter = 0;
for i = ny:-1:1
    for j = 1:nx
        iter = iter + 1;
        Temp_temp2(i,j) = Temp_temp1(iter,1);
    end
end
```



솔루션 매트릭스 재배열

재배열을 하는 것은 온도분포가 1열 벡터로 출력되기 때문

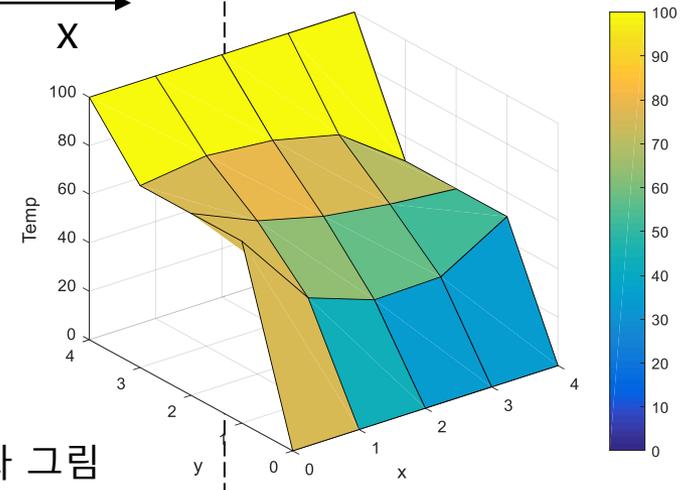
surf 명령어로 후처리를 할 예정이므로 매트릭스로 재배열이 필요

```
Temp = zeros(ny+2,nx+2);
Temp(:,1) = T_left;
Temp(:,nx+2) = T_right;
Temp(1,:) = T_upper;
Temp(ny+2,:) = T_bottom;
Temp(2:ny+1,2:nx+1) = Temp_temp2;
x=[0:1:nx+1]; y=[ny+1:-1:0];
surf(x,y,Temp)
xlabel('x'); ylabel('y'); zlabel('Temp'); colorbar
```

	1	2	3	4	5
1	100	100	100	100	100
2	75	78.5714	76.1161	69.6429	50
3	75	63.1696	56.2500	52.4554	50
4	75	42.8571	33.2589	33.9286	50
5	0	0	0	0	0



후처리



결과 그림

# ASSIGNMENT

918

CHAP. 21 Numerics for ODEs and PDEs

## EXAMPLE 1 Mixed Boundary Value Problem for a Poisson Equation

Solve the mixed boundary value problem for the Poisson equation

$$\nabla^2 u = u_{xx} + u_{yy} = f(x, y) = 12xy$$

shown in Fig. 457a.

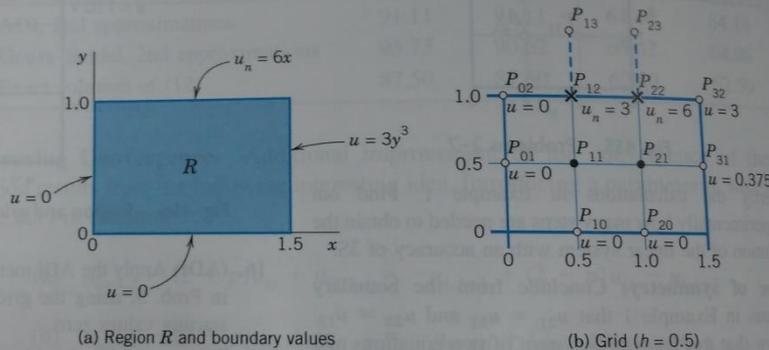


Fig. 457. Mixed boundary value problem in Example 1

$$(3) \begin{bmatrix} -4 & 1 & 1 & 0 \\ 1 & -4 & 0 & 1 \\ 2 & 0 & -4 & 1 \\ 0 & 2 & 1 & -4 \end{bmatrix} \begin{bmatrix} u_{11} \\ u_{21} \\ u_{12} \\ u_{22} \end{bmatrix} = \begin{bmatrix} 0.75 \\ 1.125 \\ 1.5 - 3 \\ 0 - 6 \end{bmatrix} = \begin{bmatrix} 0.75 \\ 1.125 \\ -1.5 \\ -6 \end{bmatrix}$$

(The entries 2 come from  $u_{13}$  and  $u_{23}$ , and so do  $-3$  and  $-6$  on the right). The solution of (3) (obtained by Gauss elimination) is as follows; the exact values of the problem are given in parentheses.

$$\begin{aligned} u_{12} &= 0.866 \quad (\text{exact } 1) & u_{22} &= 1.812 \quad (\text{exact } 2) \\ u_{11} &= 0.077 \quad (\text{exact } 0.125) & u_{21} &= 0.191 \quad (\text{exact } 0.25). \end{aligned}$$

$$u_{xx} + u_{yy} = f(x, y) = 12xy$$

Dirichet B.C

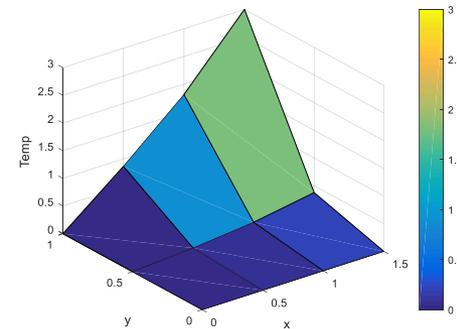
$$u(0, y) = u(y, 0) = 0, \quad u(1.5, y) = 3y^3$$

Neumann B.C

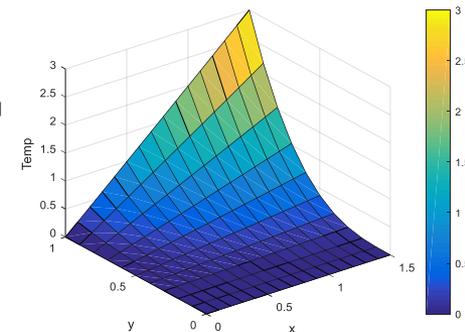
$$u_y(x, 1) = 6x$$

1)  $h = 0.5$ 

$$\begin{aligned} u_{12} &= 0.8665 & u_{22} &= 1.8121 \\ u_{11} &= 0.0769 & u_{21} &= 0.1910 \end{aligned}$$

2)  $h = 0.1$ 

$$\begin{aligned} u_{12} &= 0.9941 & u_{22} &= 1.9910 \\ u_{11} &= 0.1229 & u_{21} &= 0.2474 \end{aligned}$$

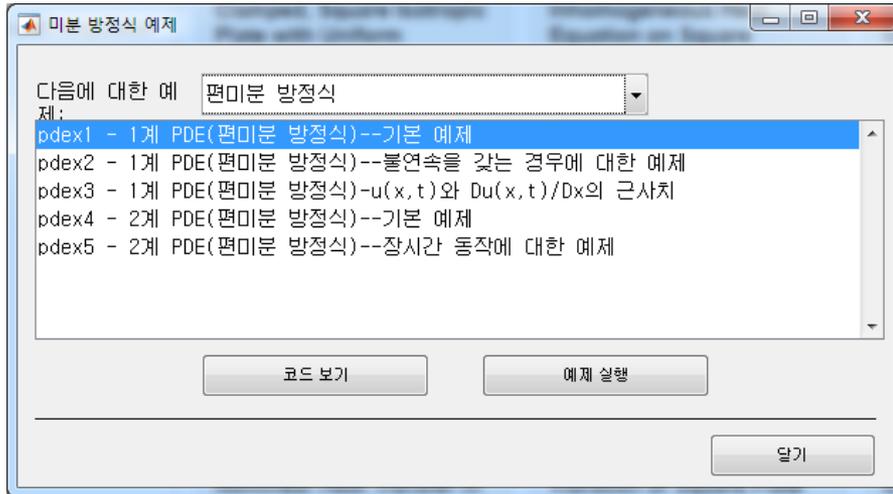


Ref. : Advanced Engineering Mathematics, 9<sup>th</sup> edition, Chap. 21, pp918-919

# ODEEXAMPLES

명령 창

```
fx >> odeexamples
```



```
sol = pdepe(m,@pdex1pde,@pdex1ic,@pdex1bc,x,t);
```

## pdepe

Solve initial-boundary value problems for parabolic-elliptic PDEs in 1-D

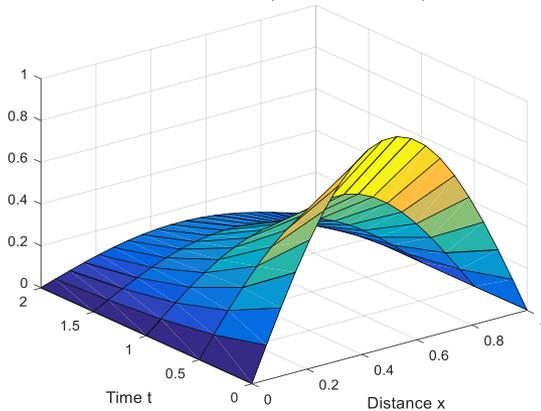
pdepe solves PDEs of the form:

$$c\left(x,t,u,\frac{\partial u}{\partial x}\right)\frac{\partial u}{\partial t} = x^{-m}\frac{\partial}{\partial x}\left(x^m f\left(x,t,u,\frac{\partial u}{\partial x}\right)\right) + s\left(x,t,u,\frac{\partial u}{\partial x}\right)$$

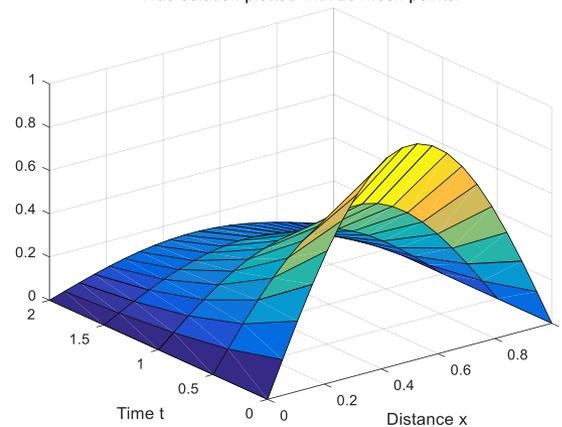
```
function [c,f,s] = pdex1pde(x,t,u,DuDx)
c = pi^2;
f = DuDx;
s = 0;
```

$$\pi^2 \frac{\partial u}{\partial t} = \frac{\partial}{\partial x} \left( \frac{\partial u}{\partial x} \right)$$

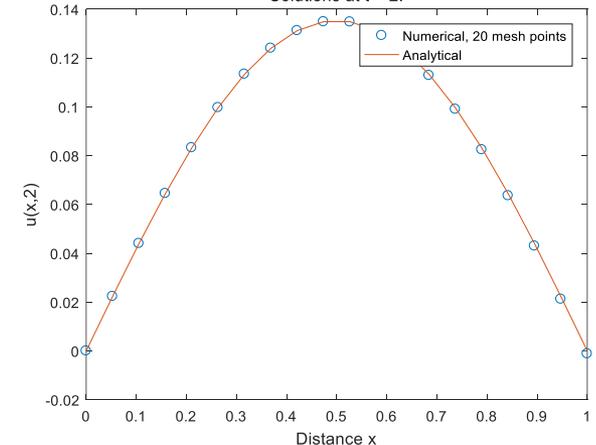
Numerical solution computed with 20 mesh points.



True solution plotted with 20 mesh points.



Solutions at t = 2.



# PDE TOOLBOX IN MATLAB

## MATLAB Examples

 Examples ▾ 

≡ CATEGORY

Close

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- < MATLAB Family
- < Math, Statistics, and Optimization

### Partial Differential Equation Toolbox

Getting Started with Partial Differential Equation Toolbox

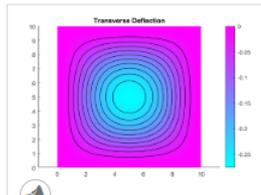
#### Applications

PDE Problem Setup

Solution Visualization and Interpolation

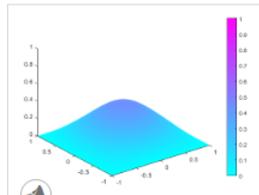
Other

## Applications



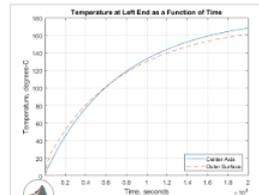
### Clamped, Square Isotropic Plate with Uniform Pressure Load

Calculate the deflection of a structural plate acted on by a pressure loading.



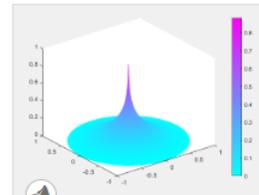
### Inhomogeneous Heat Equation on Square Domain

Solve the heat equation with a source term.



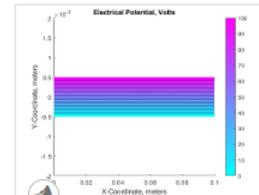
### Heat Distribution in Circular Cylindrical Rod

Analyze a 3-D axisymmetric model by using a 2-D model.



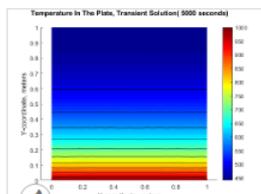
### Poisson's Equation with Point Source and Adaptive Mesh Refinement

Solve a Poisson's equation with a delta-function point source on the unit disk using the adaptmesh function.



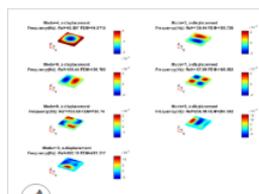
### Deflection of Piezoelectric Actuator

Solve a coupled elasticity-electrostatics problem.



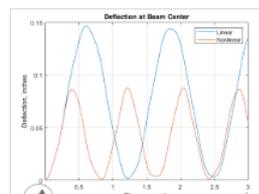
### Nonlinear Heat Transfer in Thin Plate

Perform a heat transfer analysis of a thin plate.



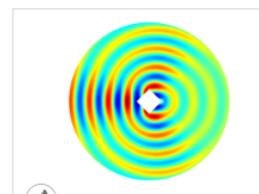
### Vibration of Square Plate

Calculate the vibration modes and frequencies of a 3-D simply supported, square, elastic plate.



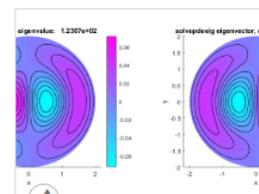
### Dynamic Analysis of Clamped Beam

Analyze the dynamic behavior of a beam clamped at both ends and loaded with a uniform pressure load.



### Helmholtz's Equation on Unit Disk with Square Hole

Solve a Helmholtz equation using the solvepde function.



### Vibration of Circular Membrane

Calculate the vibration modes of a circular membrane by using the MATLAB eig function.

# APPENDIX

- **MATLAB GUI implementation**
  - ✓ **GUI**
  - ✓ **Example**

# START



home – New – APP –  
GUIDE 클릭

MATLAB R2016a - academic use

홈 플롯 앱 편집기 퍼블리시 보기

새 스크립트 새로 만들기 열기 비교 데이터 가져오기 작업 공간 저장 변수 새 변수 변수 열기 코드 분석 실행 시간 측정 명령 지우기 Simulink 레이아웃

CAE\_자료 > 5th week m-file

편집기 - E:\WCAE실습\WCAE\_자료\5th week m-file\assignment.m

assignment.m x dydxn.m x heat\_nlin\_test.m x laplace\_ex

```

28 - e = find(T_numbering(:,1) == i & T_numbering(:,2)
29 -       T_numbering(a,3) = 1;
30 -       T_numbering(b,3) = 1;
31 -       T_numbering(c,3) = 1;
32 -       T_numbering(d,3) = 1;
33 -       T_numbering(e,3) = -4;
34 -       iter = iter + 1;
35 -       T(iter,:) = T_numbering(:,3)';

```

**GUIDE**  
완전한 2차원 그래픽스와 3차원 그래픽스 지원을 통해 Figure 기반 앱을 빌드합니다.

**App Designer**  
새로운 구성요소와 제한된 2차원 그래픽스를 통해 uifigure 기반 App을 빌드합니다.

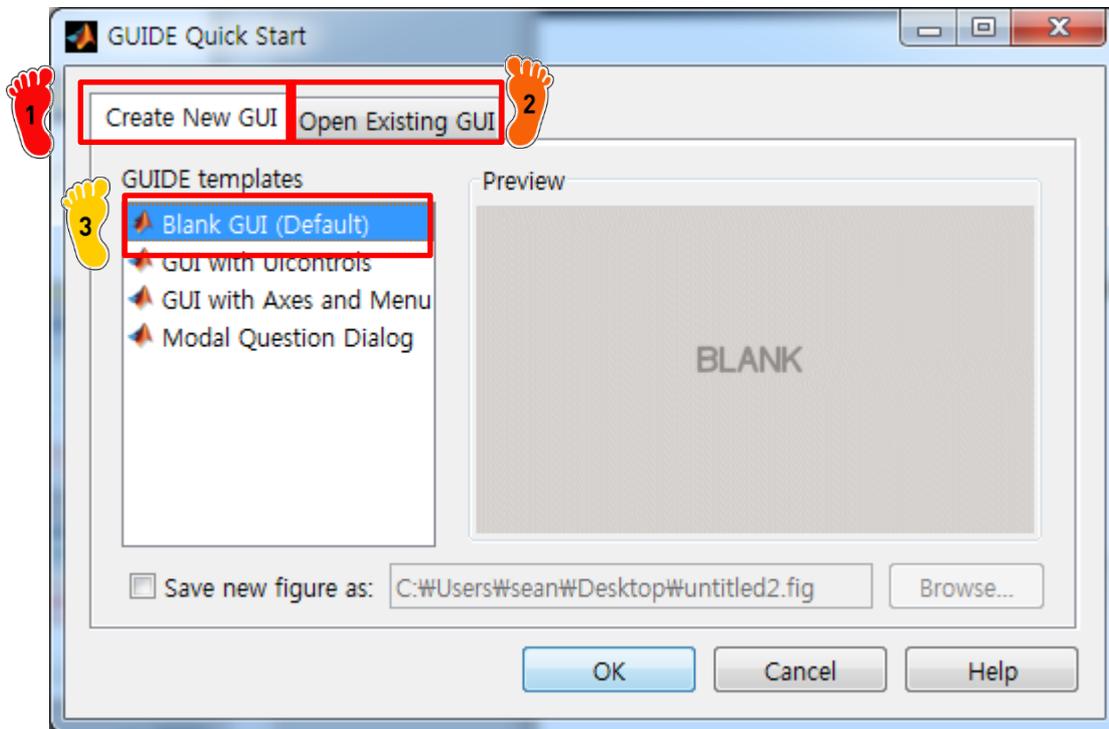
명령 창

MATLAB을 처음 사용한다면 [시작하기](#)를 참조하십시오.

0.0769

untitled.m

# GUI SETTING WINDOW

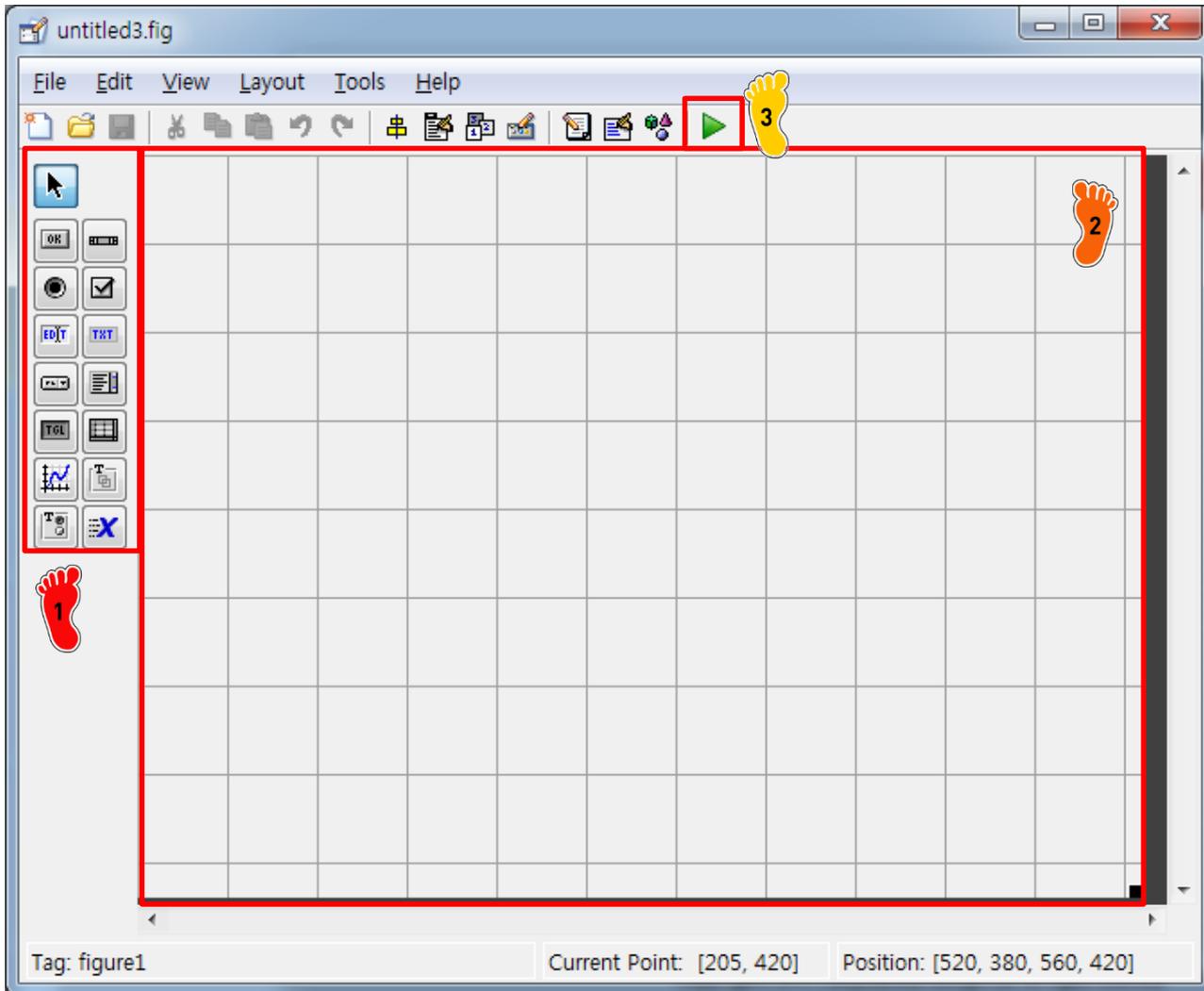


1 새로운 GUI 를 만드는 탭 메뉴

2 기존 GUI 파일을 불러오는 탭 메뉴

3 빈 GUI 창 생성(기본)  
그 아래 메뉴는 예제

# GUI WINDOW

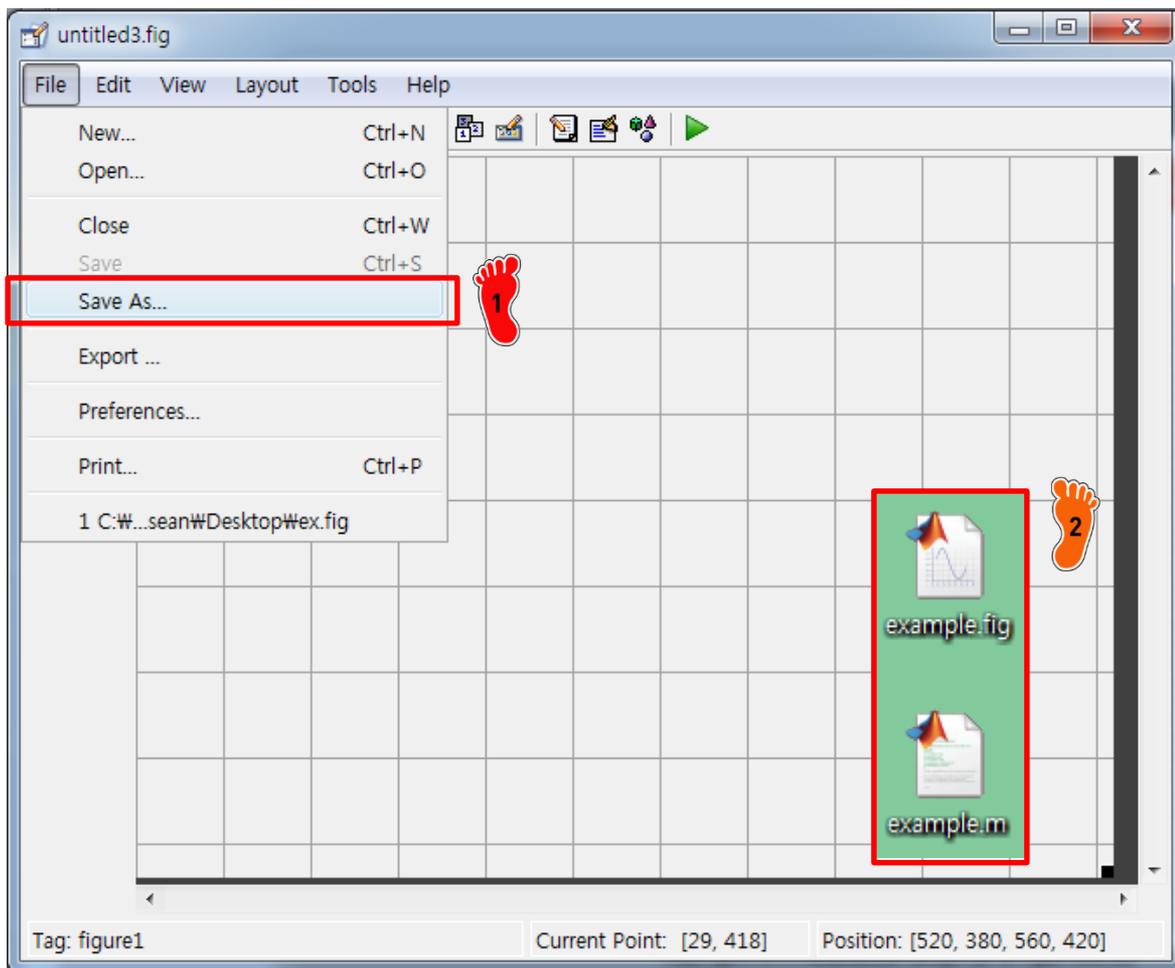


1 GUI 아이콘

2 GUI 아이콘을 배치하는 창

3 GUI 실행 아이콘

# GUI FILES



1 현재 GUI 창을 저장

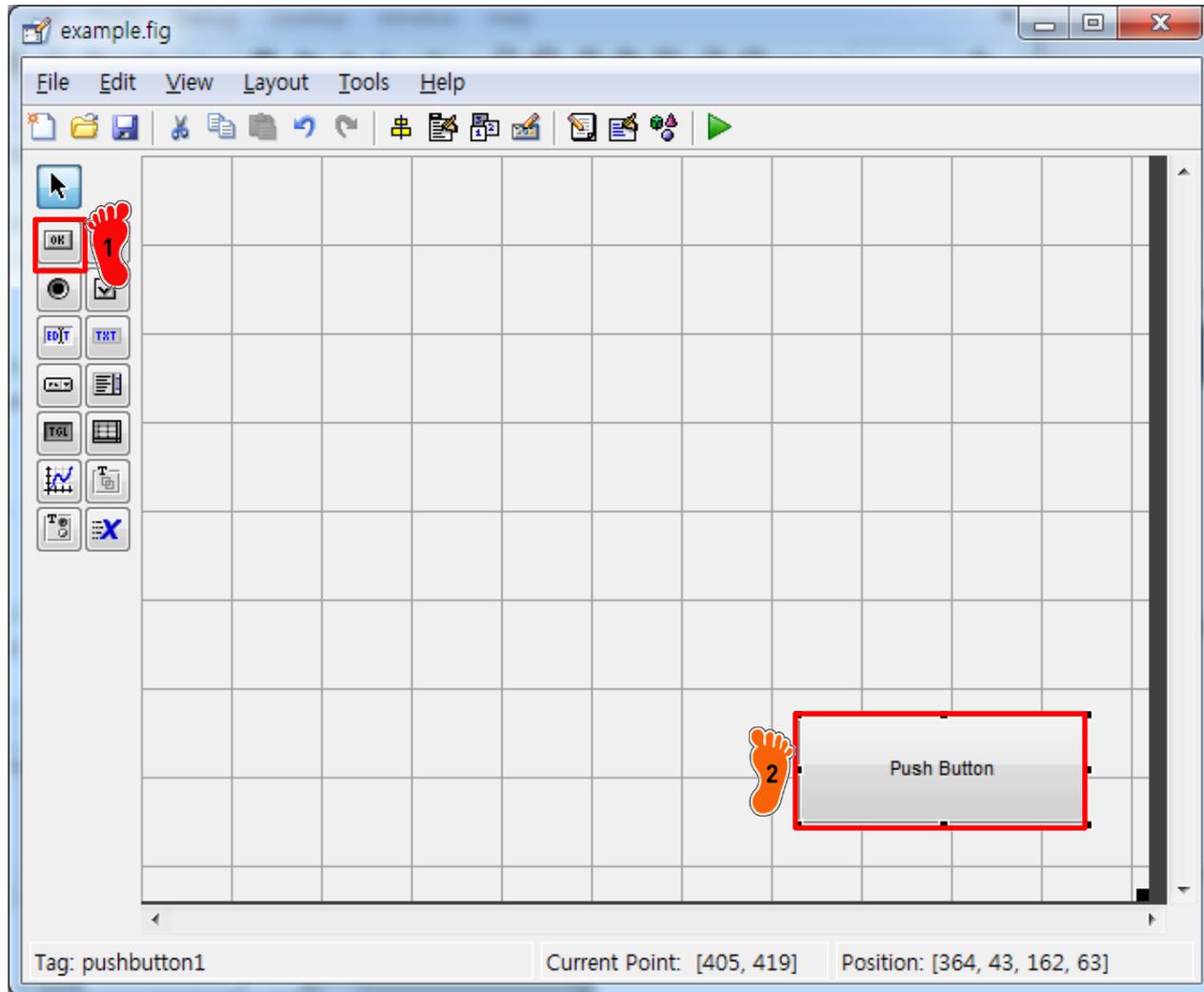
2 저장하면 \*.fig 파일과 \*.m 파일이 동시에 생성됨



# APPENDIX

- **MATLAB GUI implementation**
  - ✓ **GUI**
  - ✓ **Example (Prob.27-27에 참고)**
    - ✓ **ODE 문제를 입력하여 다양한 방법으로 수치해를 구하고 비교할 수 있는 GUI 구축**

# PUSH BUTTON

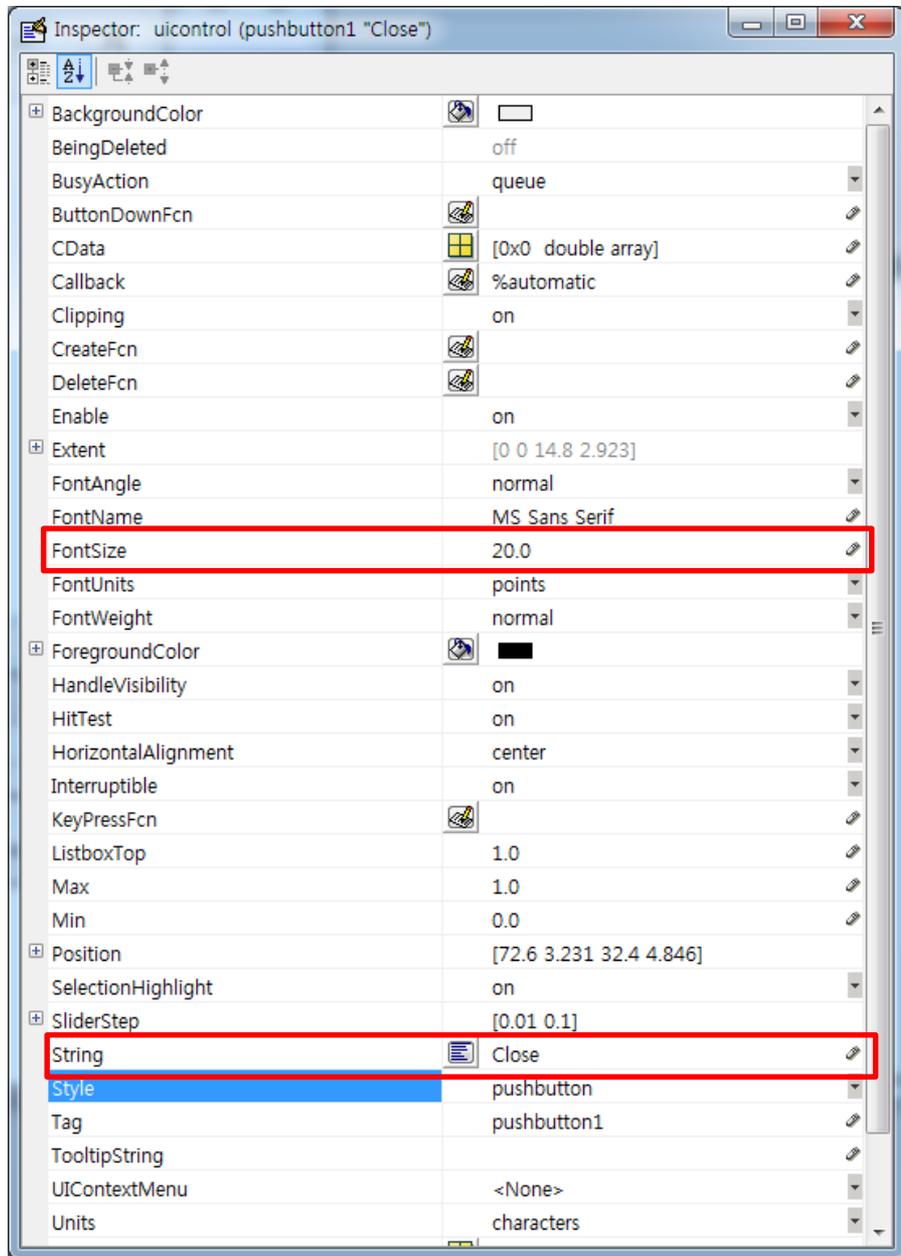


1 Push Button 아이콘 클릭

2 마우스를 드래그해서 Push Button 아이콘 생성

그 후 아이콘 더블 클릭

# PUSH BUTTON: INSPECTOR



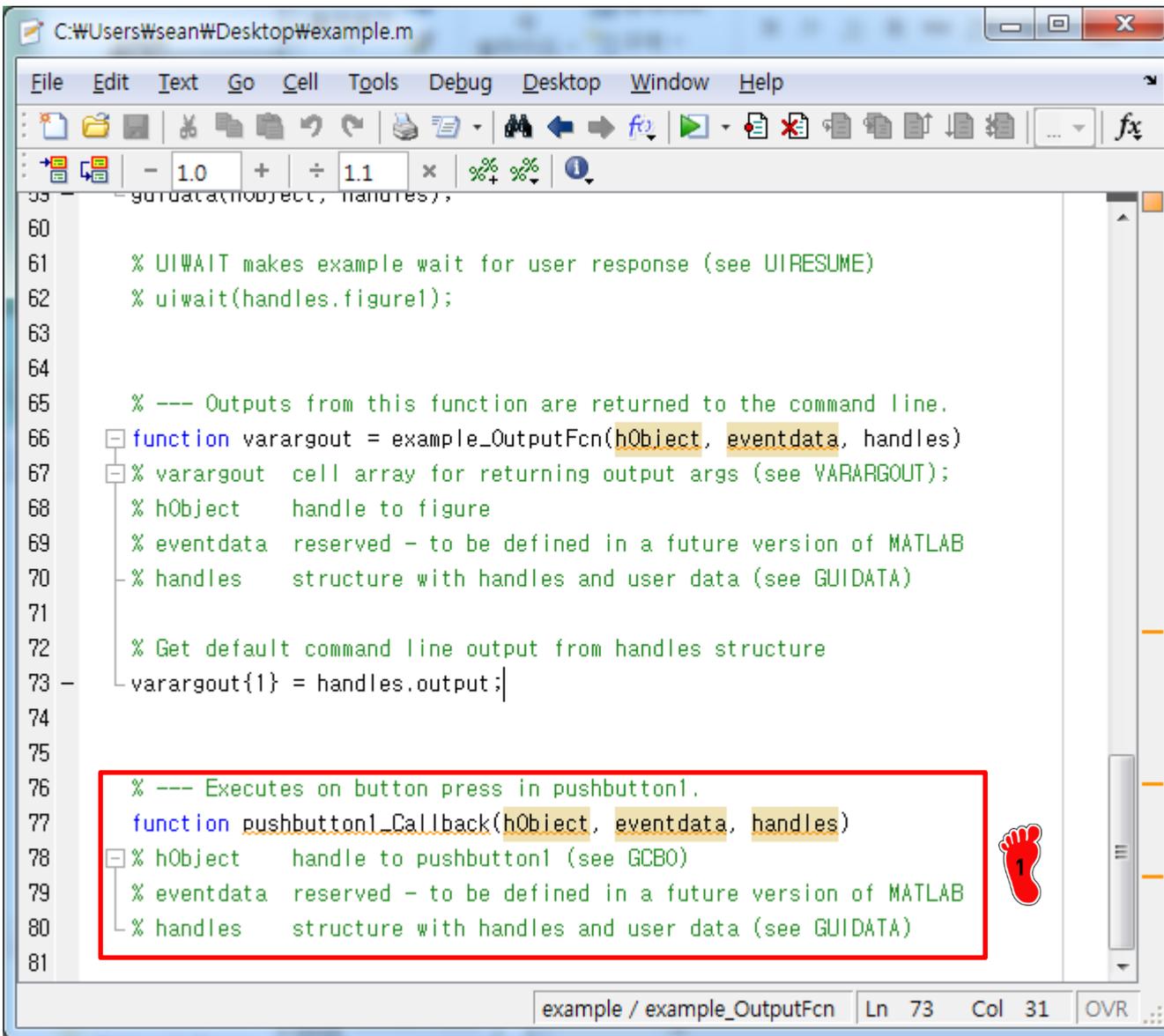
String 을 Close 로 변경



FontSize 20 으로 변경



# PUSH BUTTON: M-FILE



```

55 guidata(hObject, handles);
60
61 % UIWAIT makes example wait for user response (see UIRESUME)
62 % uiwait(handles.figure1);
63
64
65 % --- Outputs from this function are returned to the command line.
66 function varargout = example_OutputFcn(hObject, eventdata, handles)
67 % varargout cell array for returning output args (see VARARGOUT);
68 % hObject    handle to figure
69 % eventdata  reserved - to be defined in a future version of MATLAB
70 % handles    structure with handles and user data (see GUIDATA)
71
72 % Get default command line output from handles structure
73 varargout{1} = handles.output;
74
75
76 % --- Executes on button press in pushbutton1.
77 function pushbutton1_Callback(hObject, eventdata, handles)
78 % hObject    handle to pushbutton1 (see GCBO)
79 % eventdata  reserved - to be defined in a future version of MATLAB
80 % handles    structure with handles and user data (see GUIDATA)
81
  
```

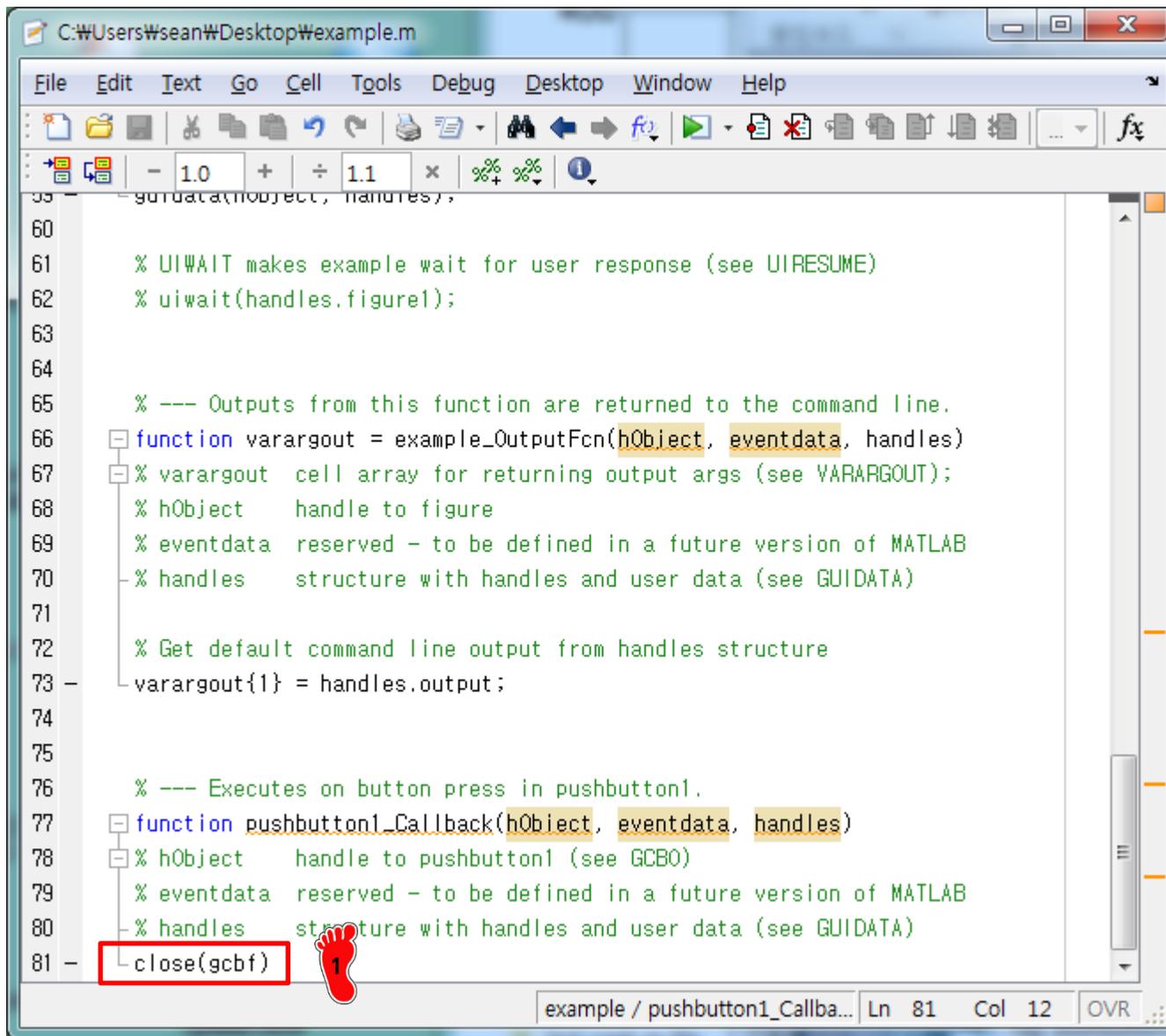


M-file 에  
pushbutton1\_Callback 함수  
가 생성됨

이 함수 밑에 m-file 명령어  
를 입력하고 저장하면  
pushbutton 을 클릭했을 때  
실행됨



# PUSH BUTTON: M-FILE



```

55 guidata(hObject, handles);
60
61 % UIWAIT makes example wait for user response (see UIRESUME)
62 % uiwait(handles.figure1);
63
64
65 % --- Outputs from this function are returned to the command line.
66 function varargout = example_OutputFcn(hObject, eventdata, handles)
67 % varargout cell array for returning output args (see VARARGOUT);
68 % hObject    handle to figure
69 % eventdata  reserved - to be defined in a future version of MATLAB
70 % handles    structure with handles and user data (see GUIDATA)
71
72 % Get default command line output from handles structure
73 varargout{1} = handles.output;
74
75
76 % --- Executes on button press in pushbutton1.
77 function pushbutton1_Callback(hObject, eventdata, handles)
78 % hObject    handle to pushbutton1 (see GCBO)
79 % eventdata  reserved - to be defined in a future version of MATLAB
80 % handles    structure with handles and user data (see GUIDATA)
81 close(gcf)

```



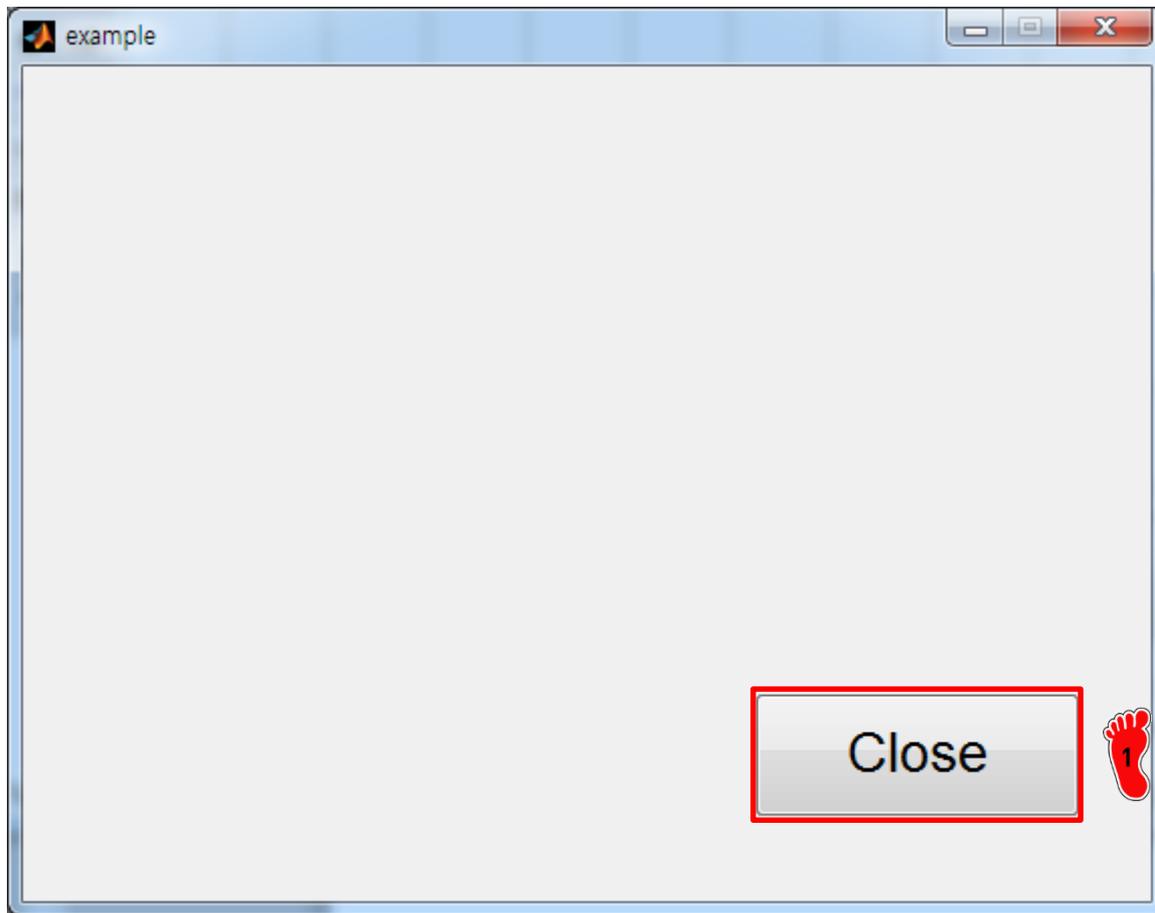
close(gcf) 입력

이 명령어는 현재 GUI 창을 닫는 명령어

# PUSH BUTTON: GUI



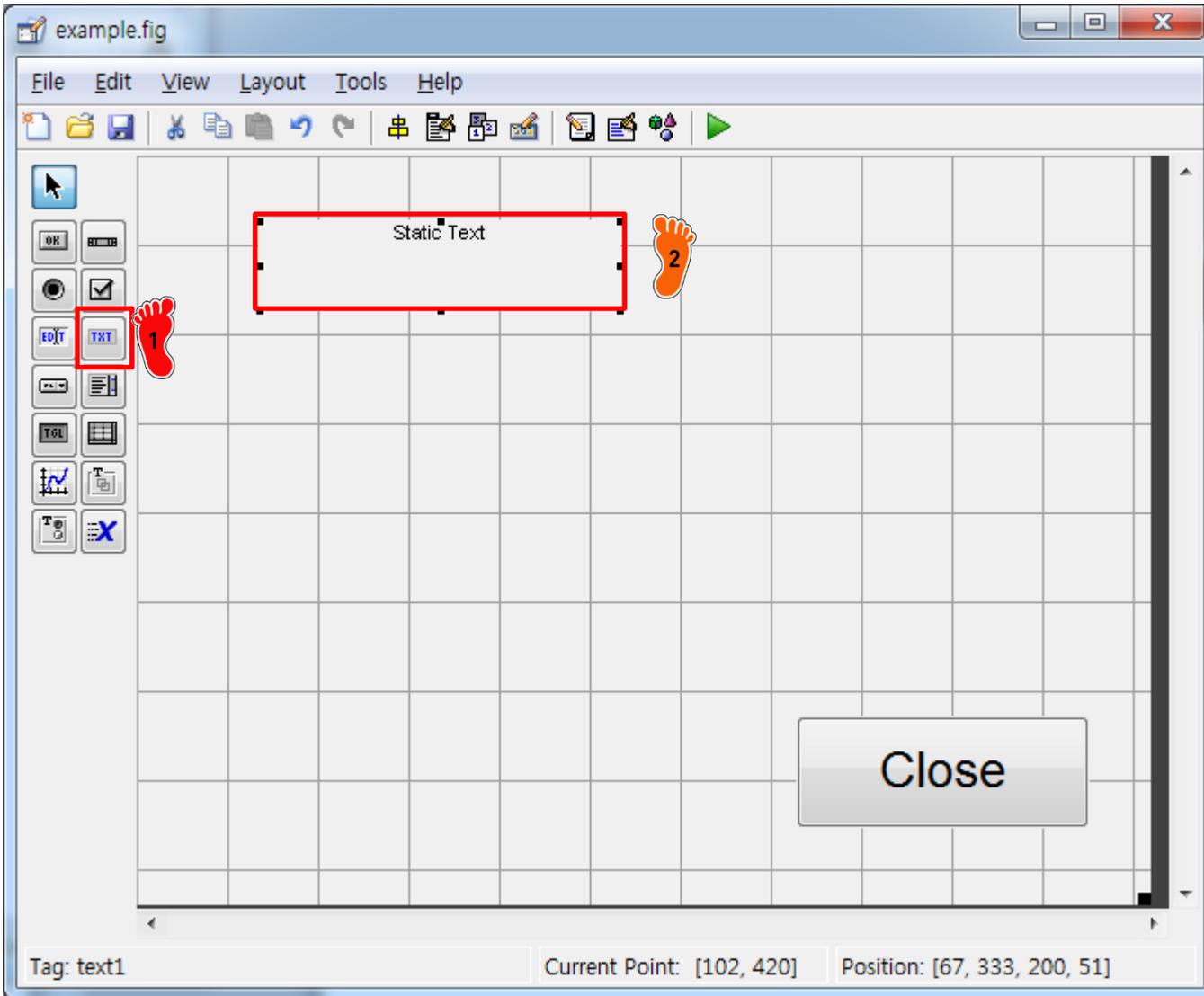
GUI 창을 실행시켜 Close  
pushbutton 을 클릭하면 창  
이 닫힘



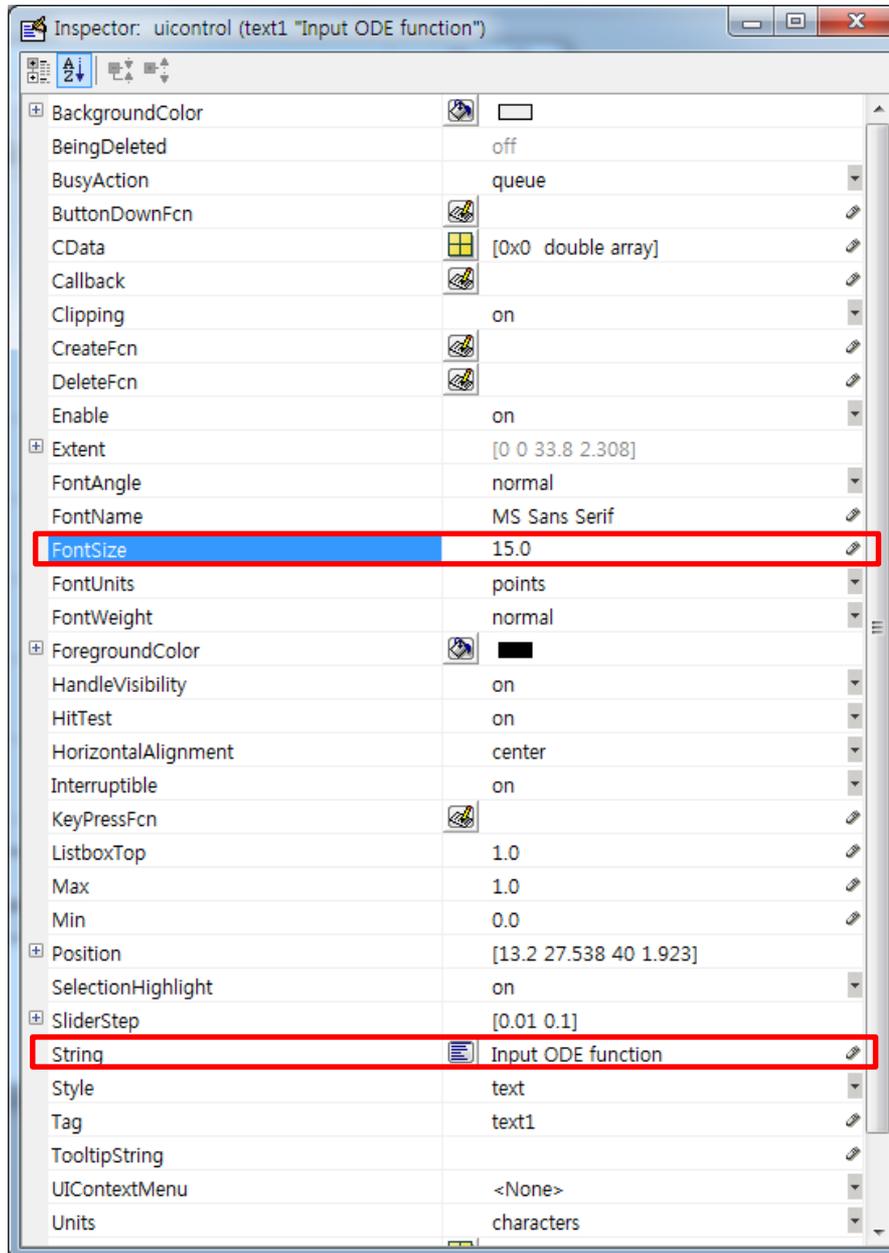
# STATIC TEXT BOX

1 static text 아이콘 클릭

2 static text box 생성  
더블 클릭



# STATIC TEXT BOX: INSPECTOR



String 을 Input ODE function 으로 변경



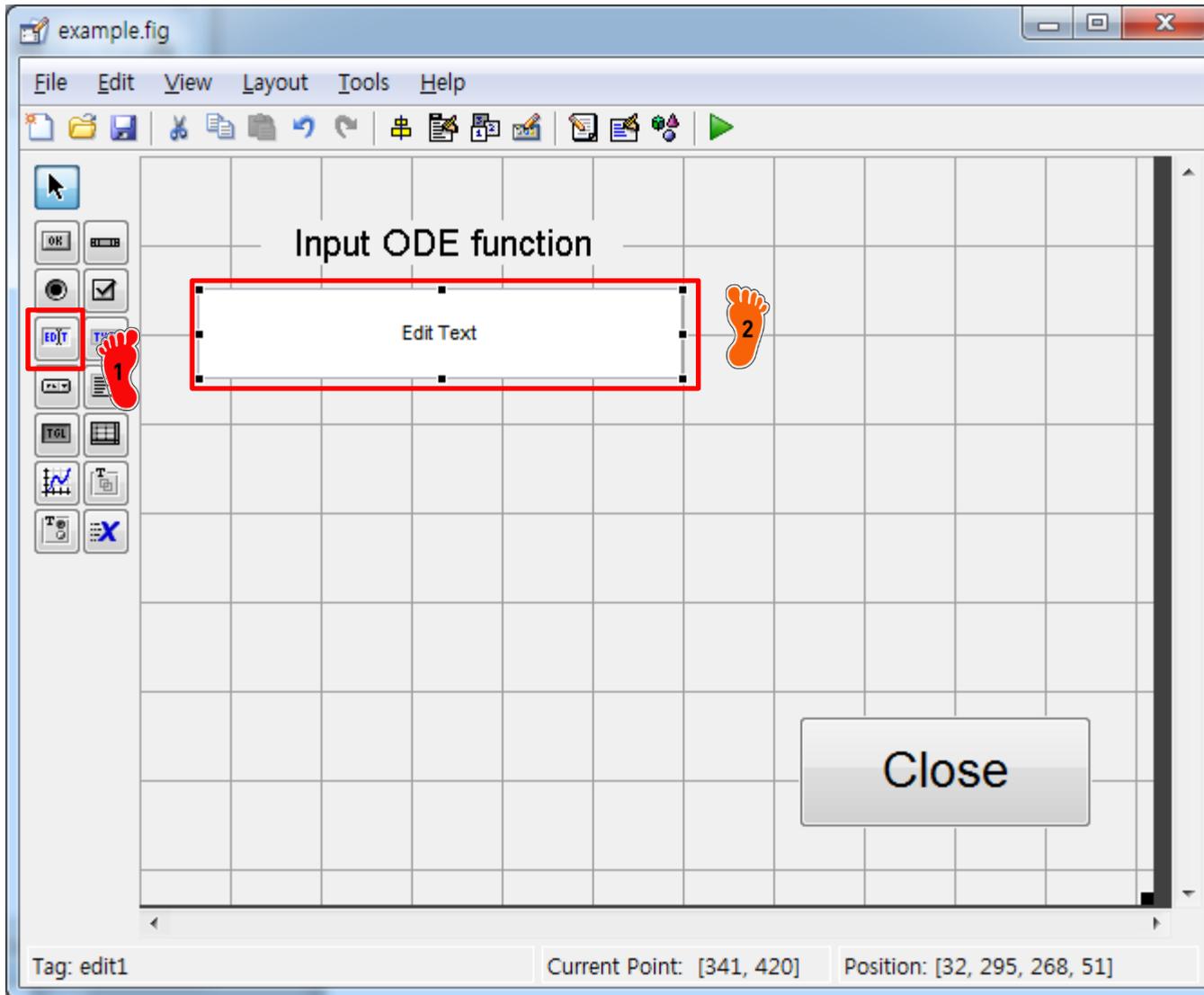
FontSize 15로 변경



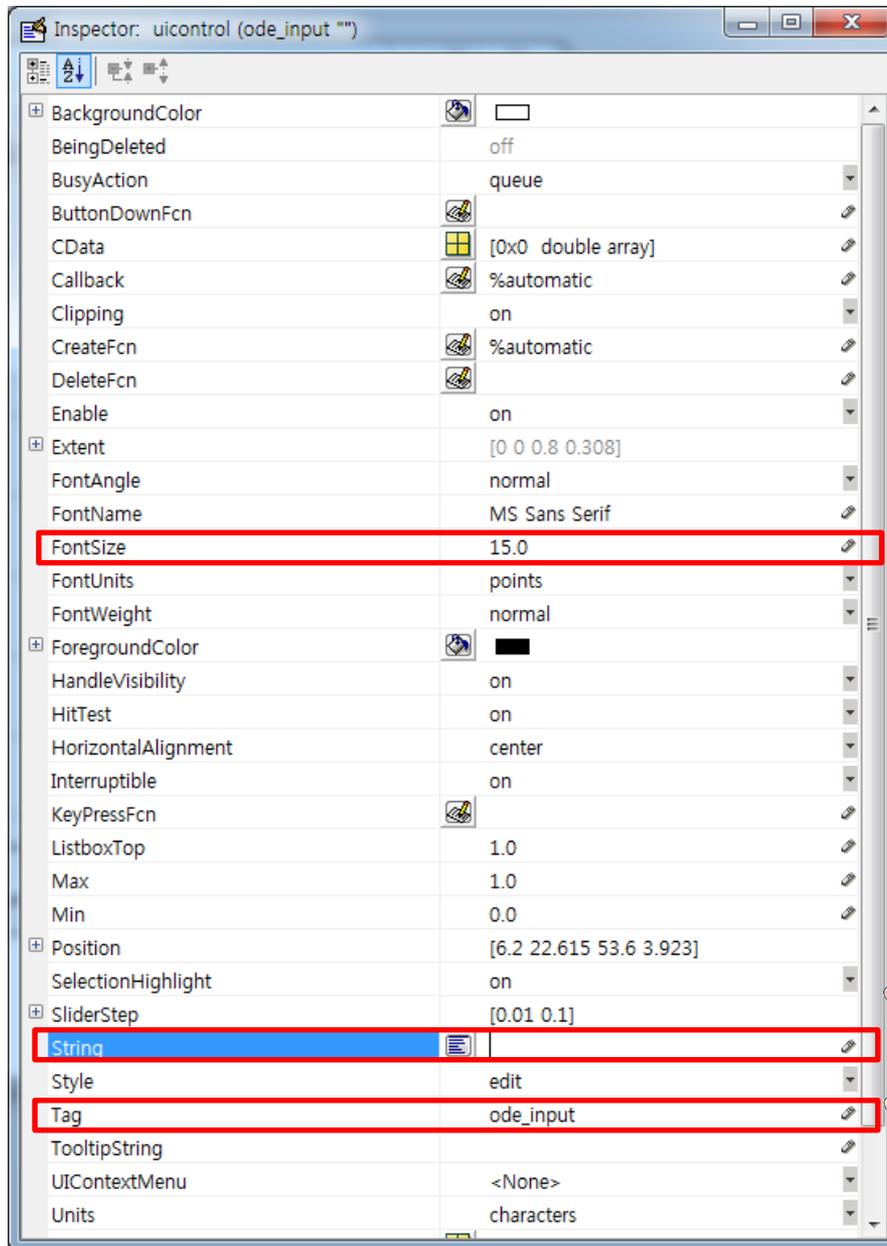
# EDIT TEXT BOX

1 edit text 아이콘 클릭

2 edit text box 생성  
더블 클릭



# EDIT TEXT BOX: INSPECTOR

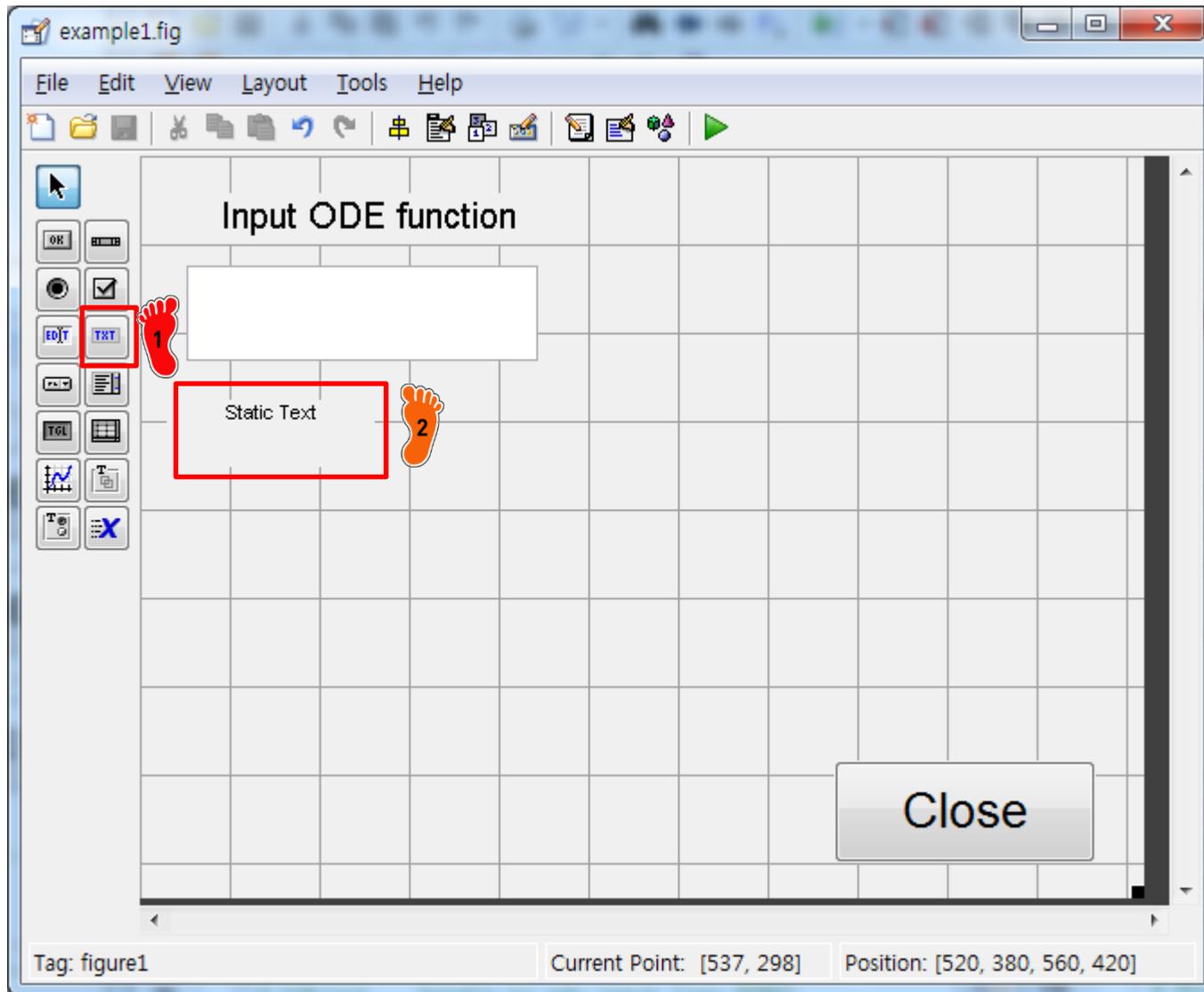


1 String 빈칸으로 변경

2 FontSize 15로 변경

3 Tag 를 ode\_input 으로 변경

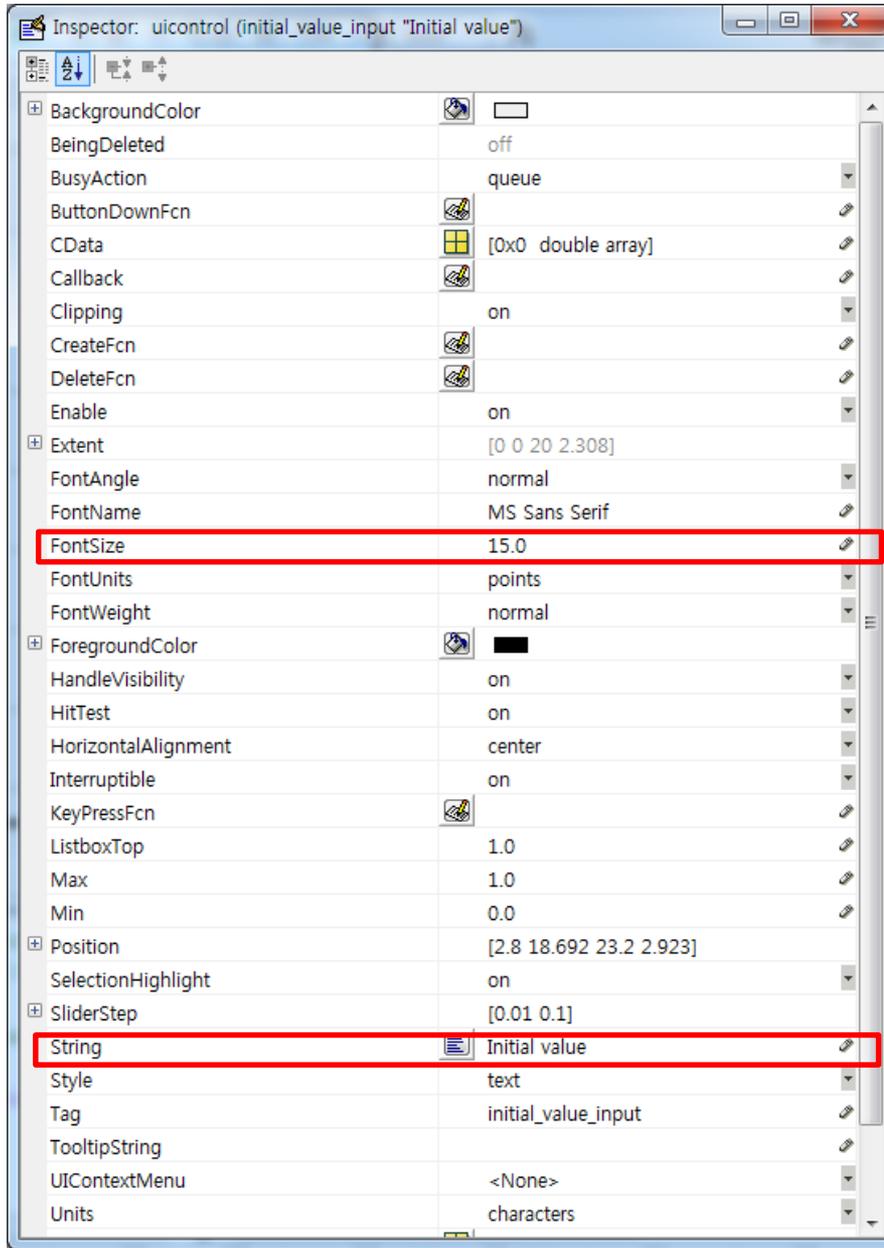
# STATIC TEXT BOX



1 static text 아이콘 클릭

2 static text box 생성  
더블 클릭

# STATIC TEXT BOX: INSPECTOR



String 을 Initial value 로 변경



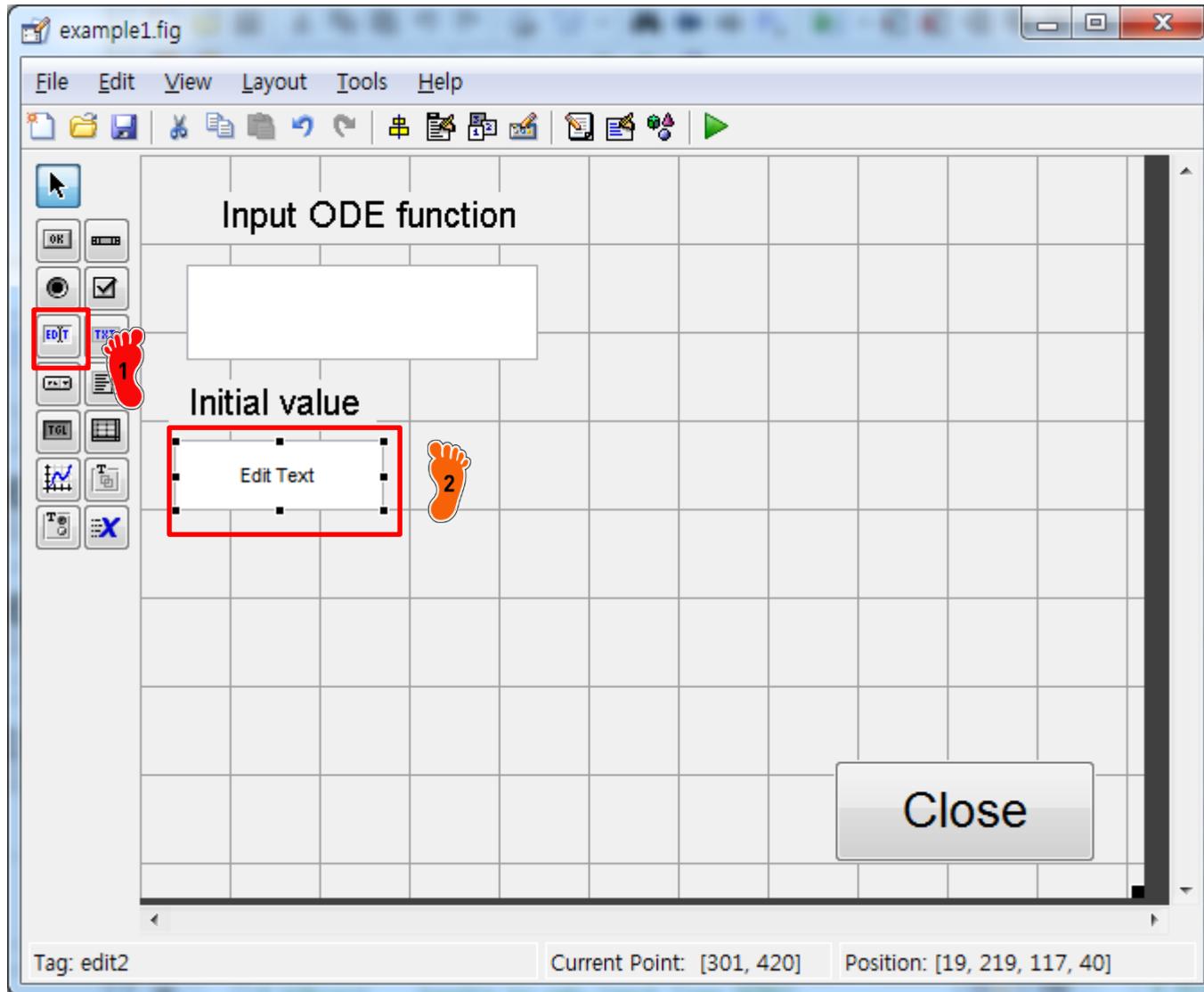
FontSize 15로 변경



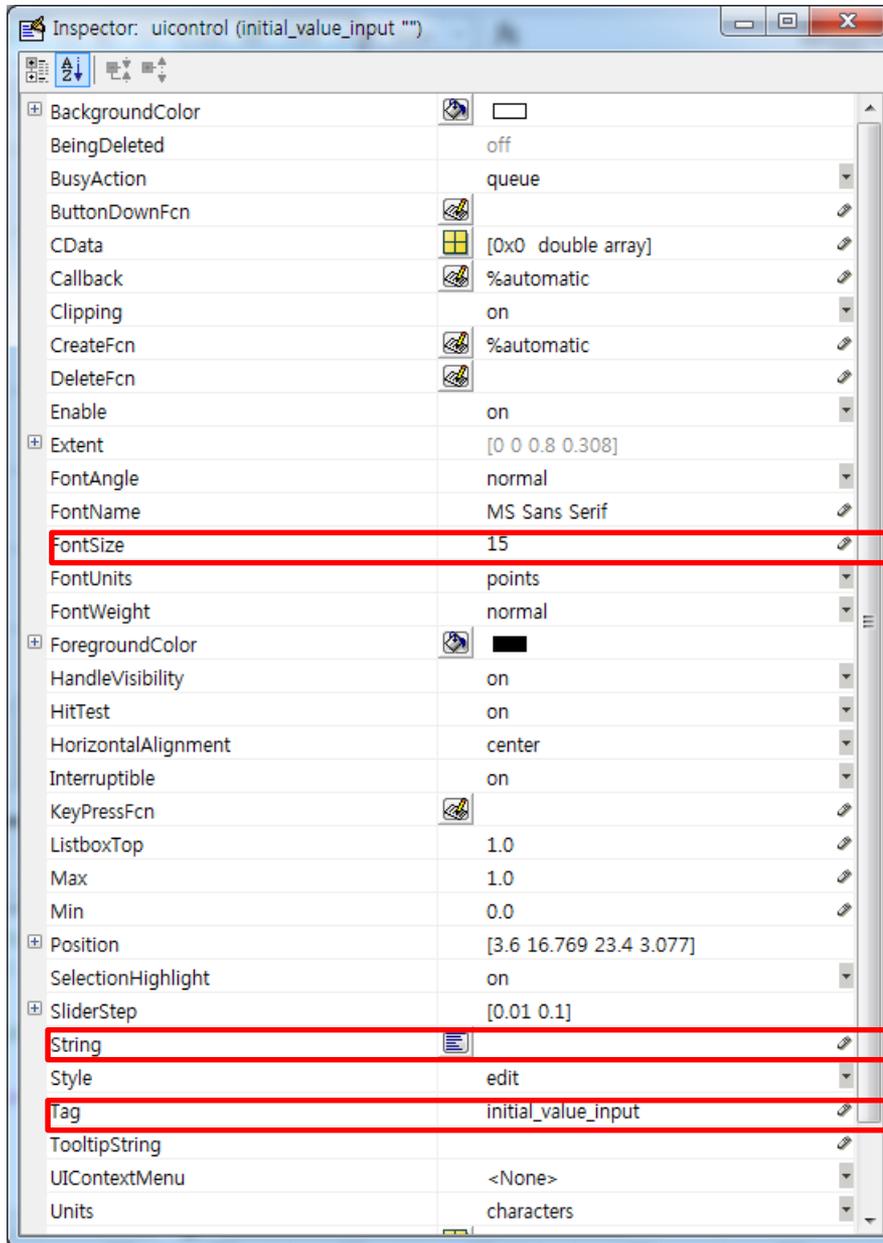
# EDIT TEXT BOX

1 edit text 아이콘 클릭

2 edit text box 생성  
더블 클릭



# EDIT TEXT BOX: INSPECTOR

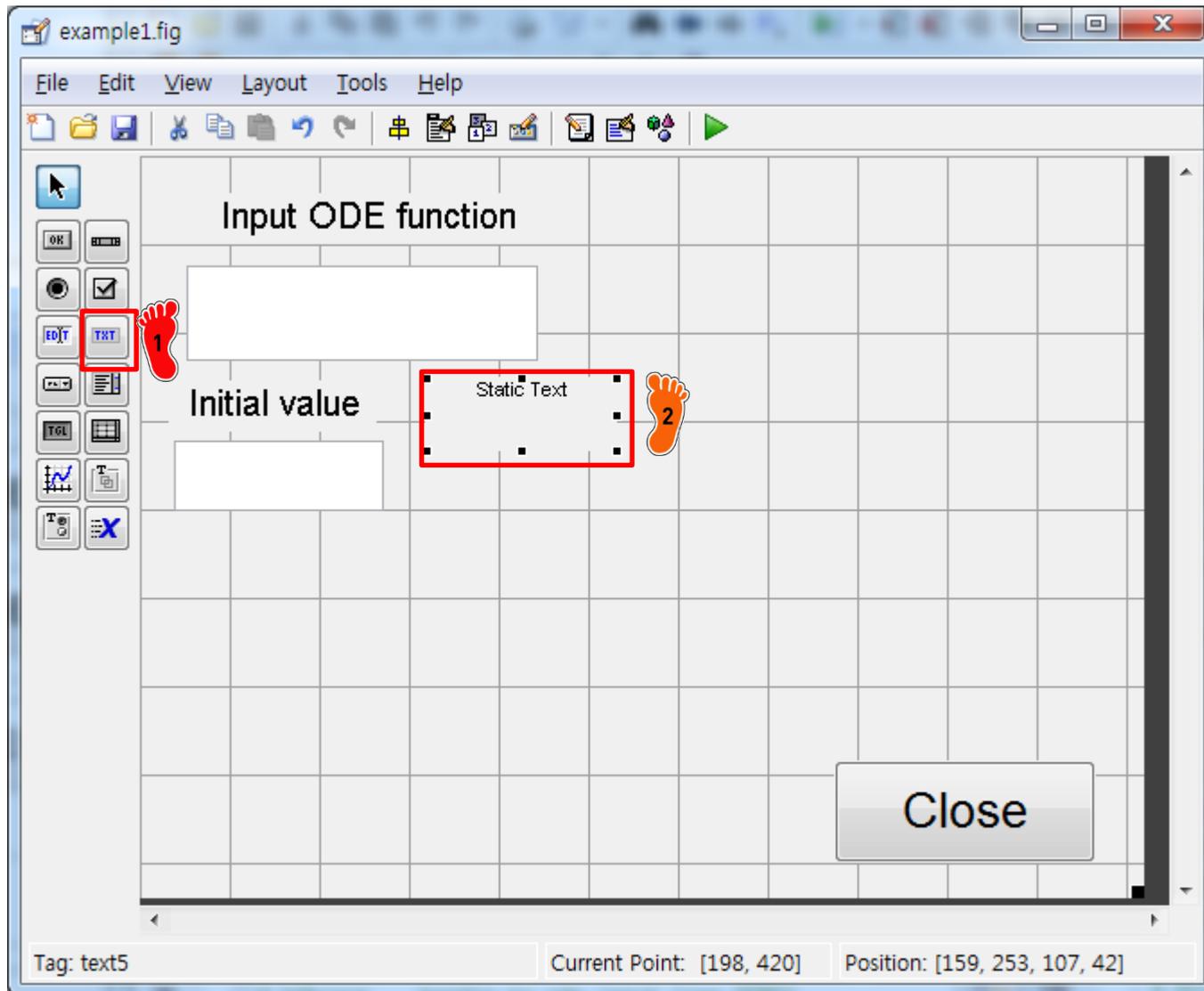


1 String 빈칸으로 변경

2 FontSize 15로 변경

3 Tag 를 initial\_value\_input  
으로 변경

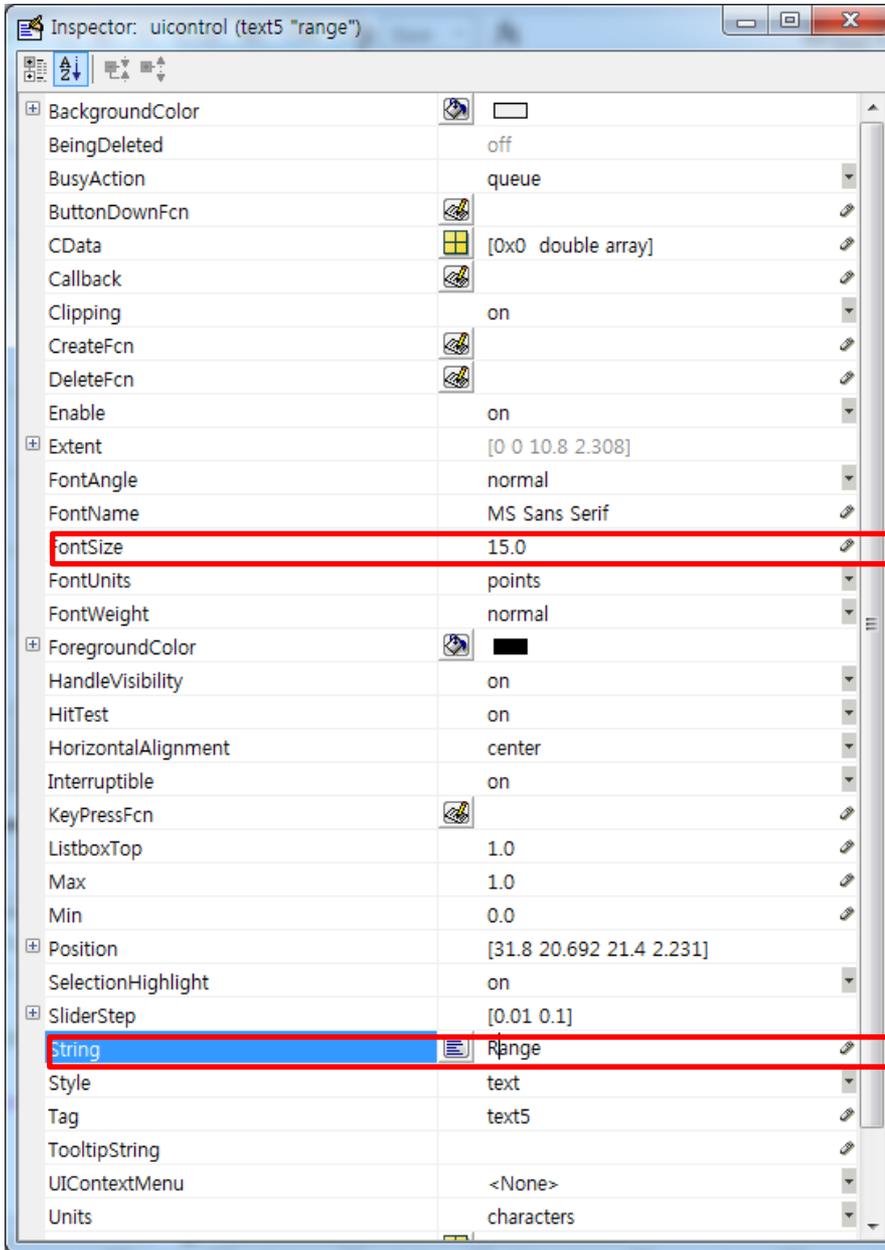
# STATIC TEXT BOX



1 static text 아이콘 클릭

2 static text box 생성  
더블 클릭

# STATIC TEXT BOX: INSPECTOR



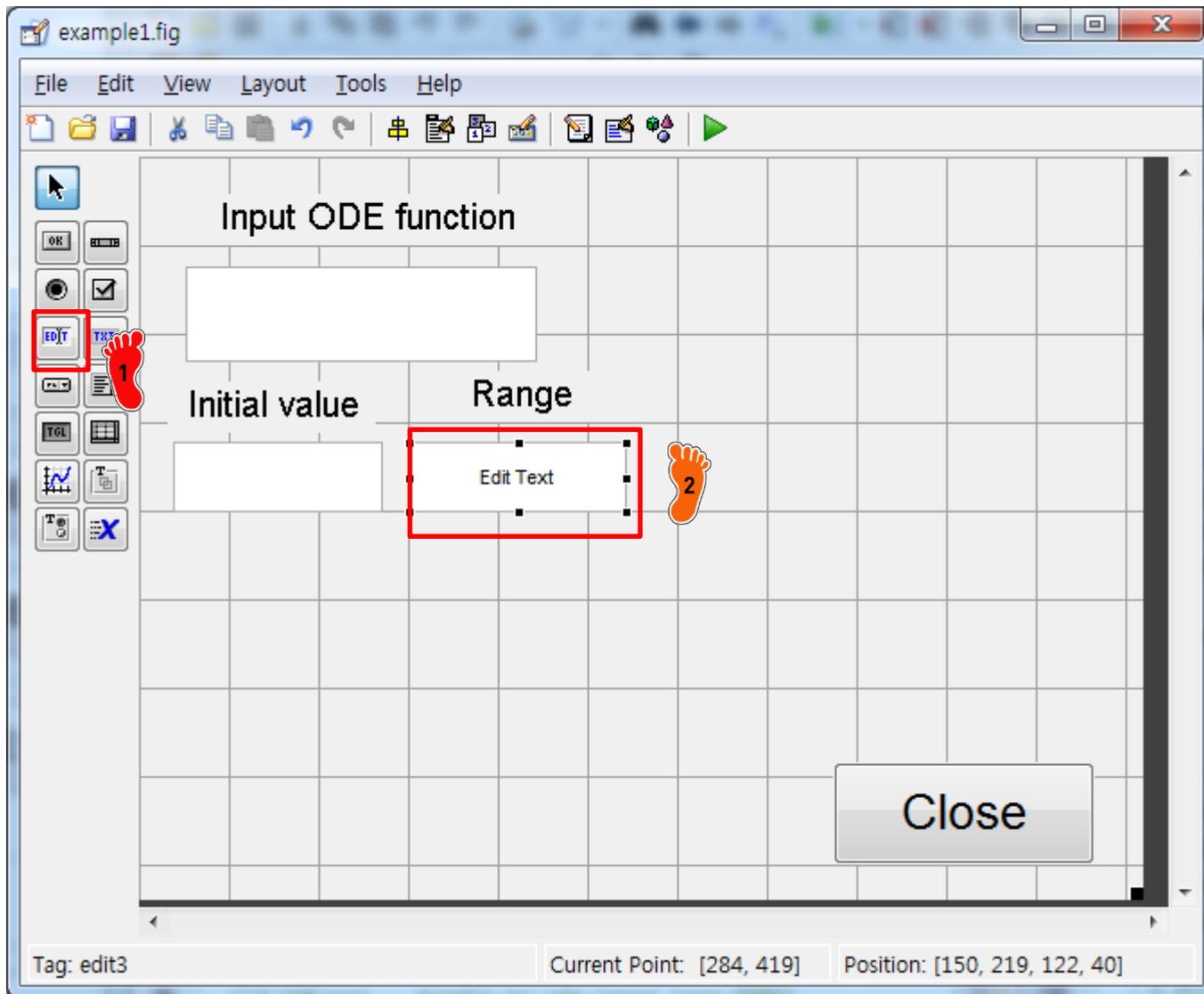
String 을 Range 로 변경



FontSize 15로 변경



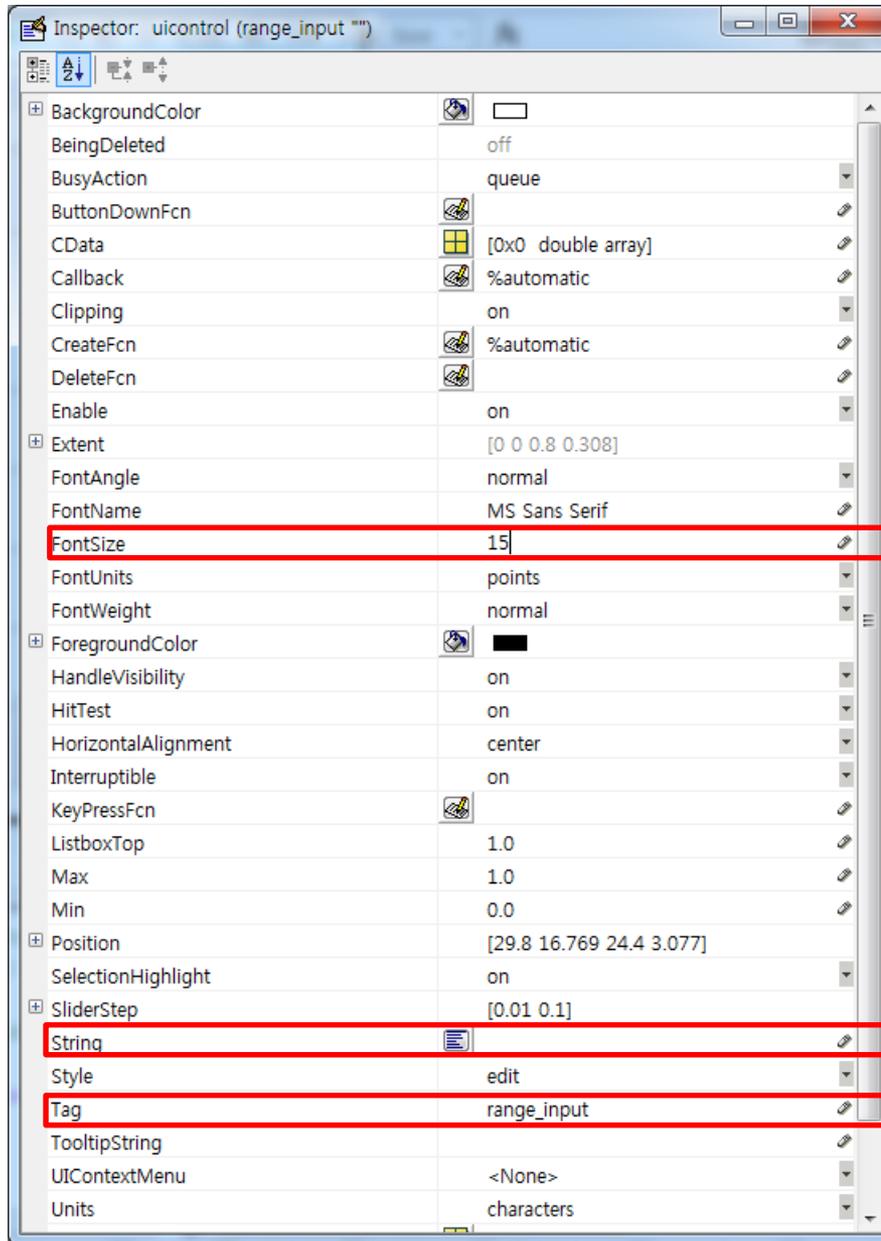
# EDIT TEXT BOX



1 edit text 아이콘 클릭

2 edit text box 생성  
더블 클릭

# EDIT TEXT BOX: INSPECTOR



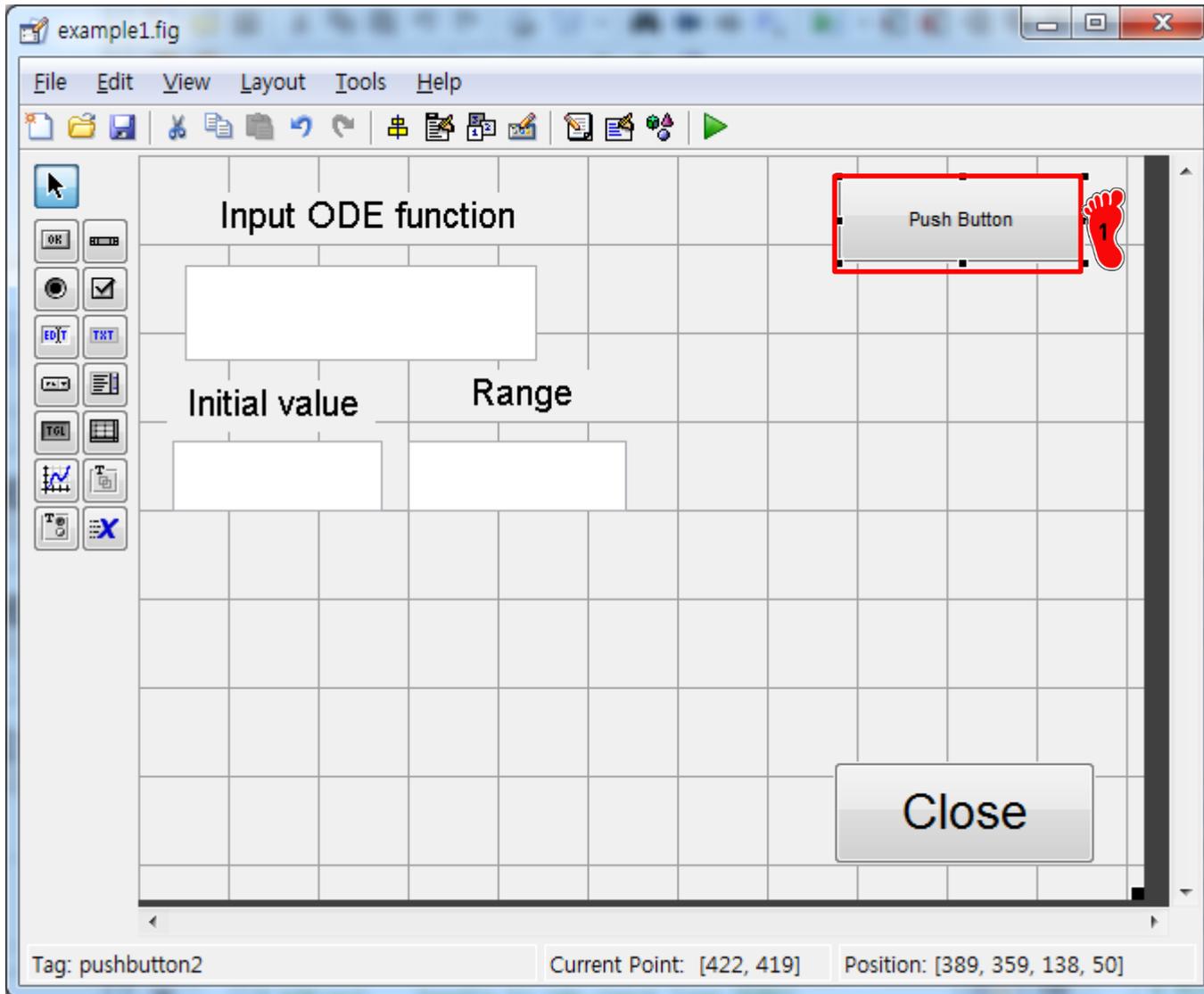
1 String 빈칸으로 변경

2 FontSize 15로 변경

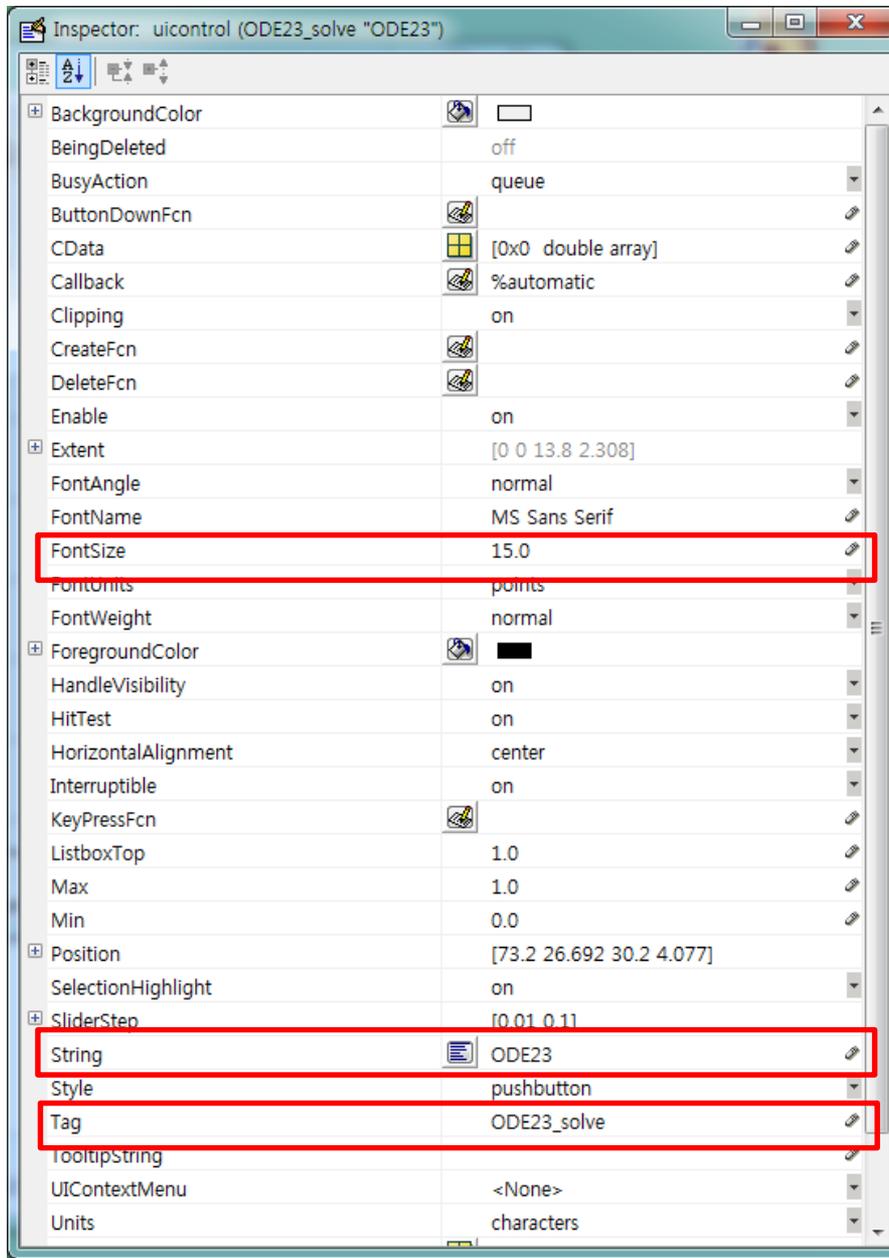
3 Tag 를 range\_input 으로 변경

# ODE23 PUSH BUTTON

 pushbutton 생성



# ODE23 PUSH BUTTON: INSPECTOR



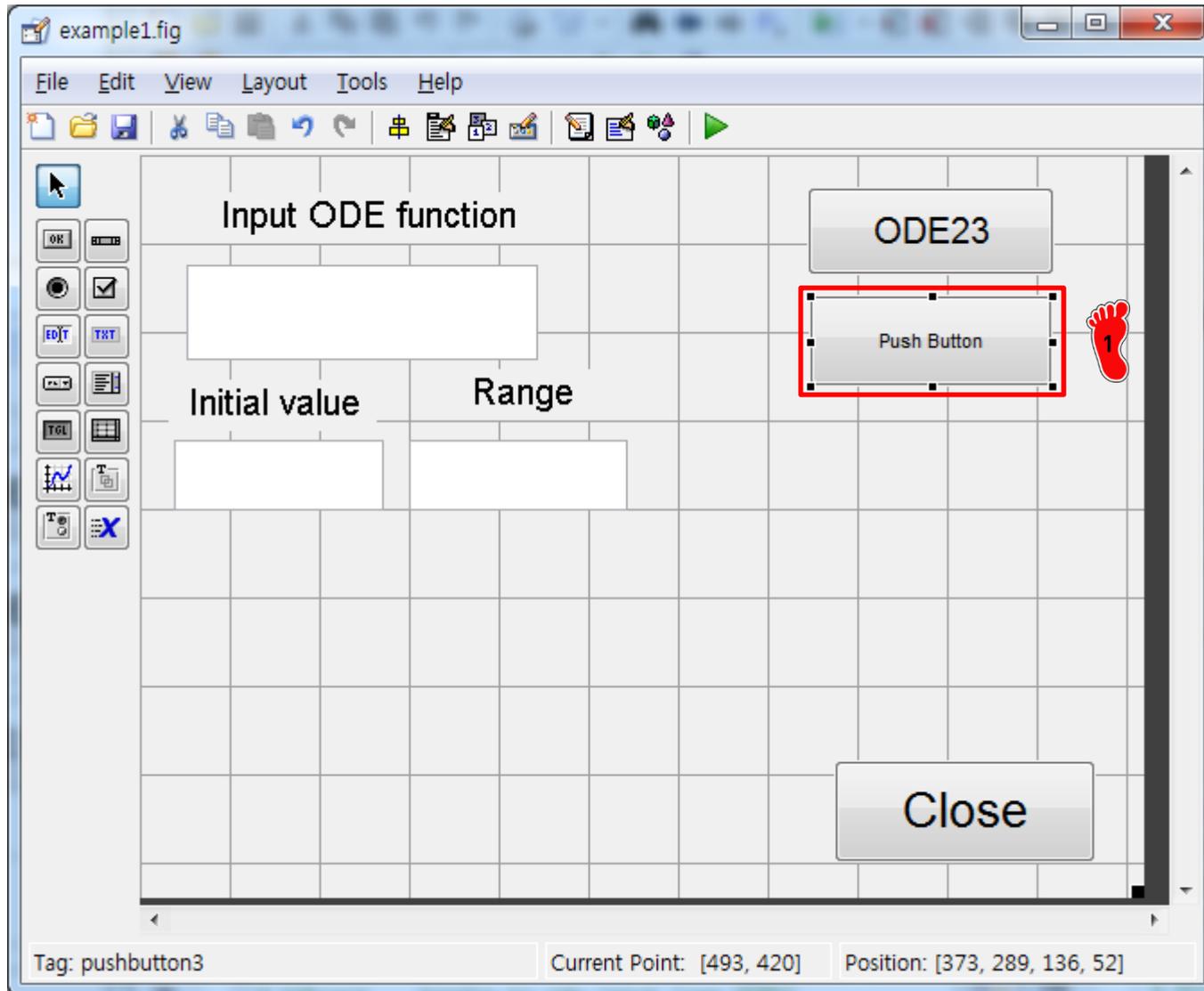
1 String ODE23으로 변경

2 FontSize 15로 변경

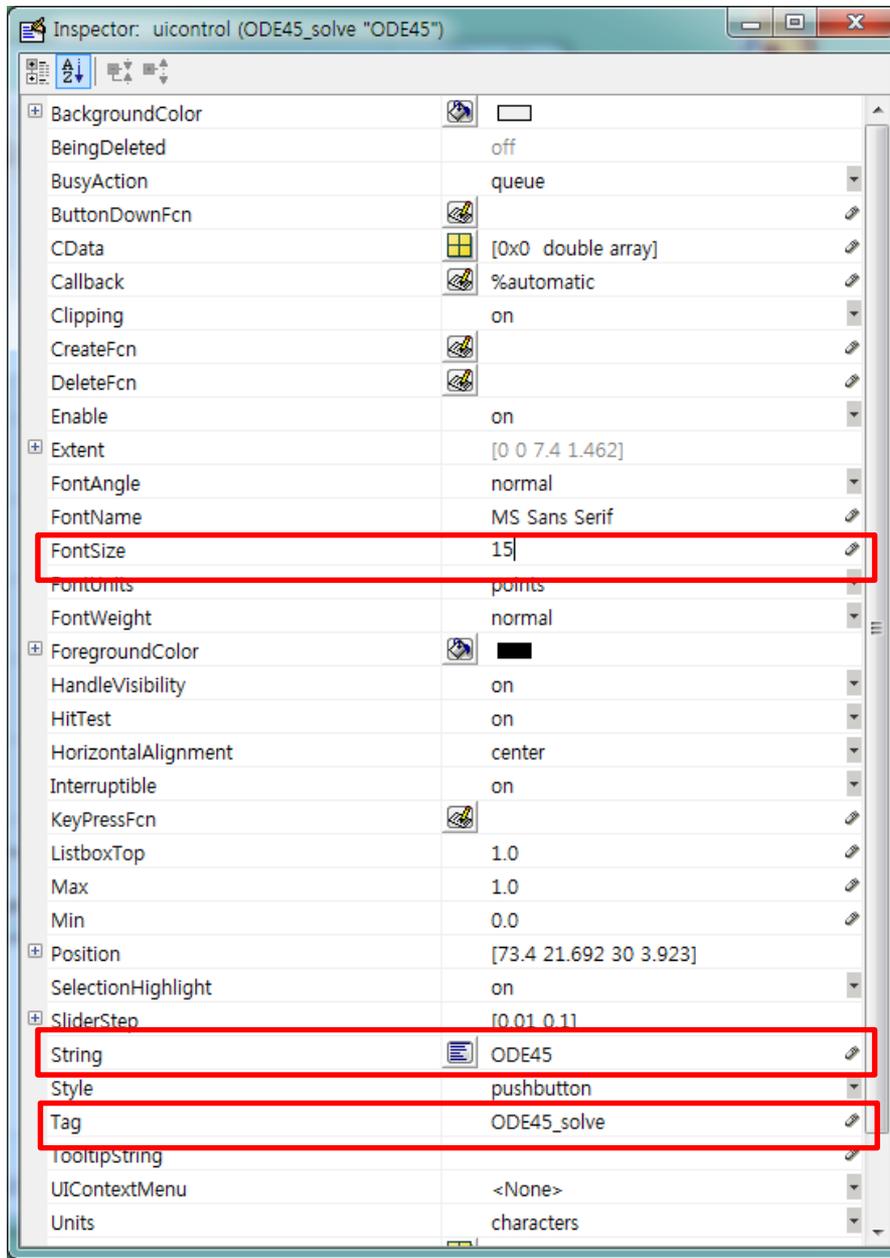
3 Tag 를 ODE23\_solve 로 변경

# ODE45 PUSH BUTTON

1 pushbutton 생성



# ODE45 PUSH BUTTON: INSPECTOR



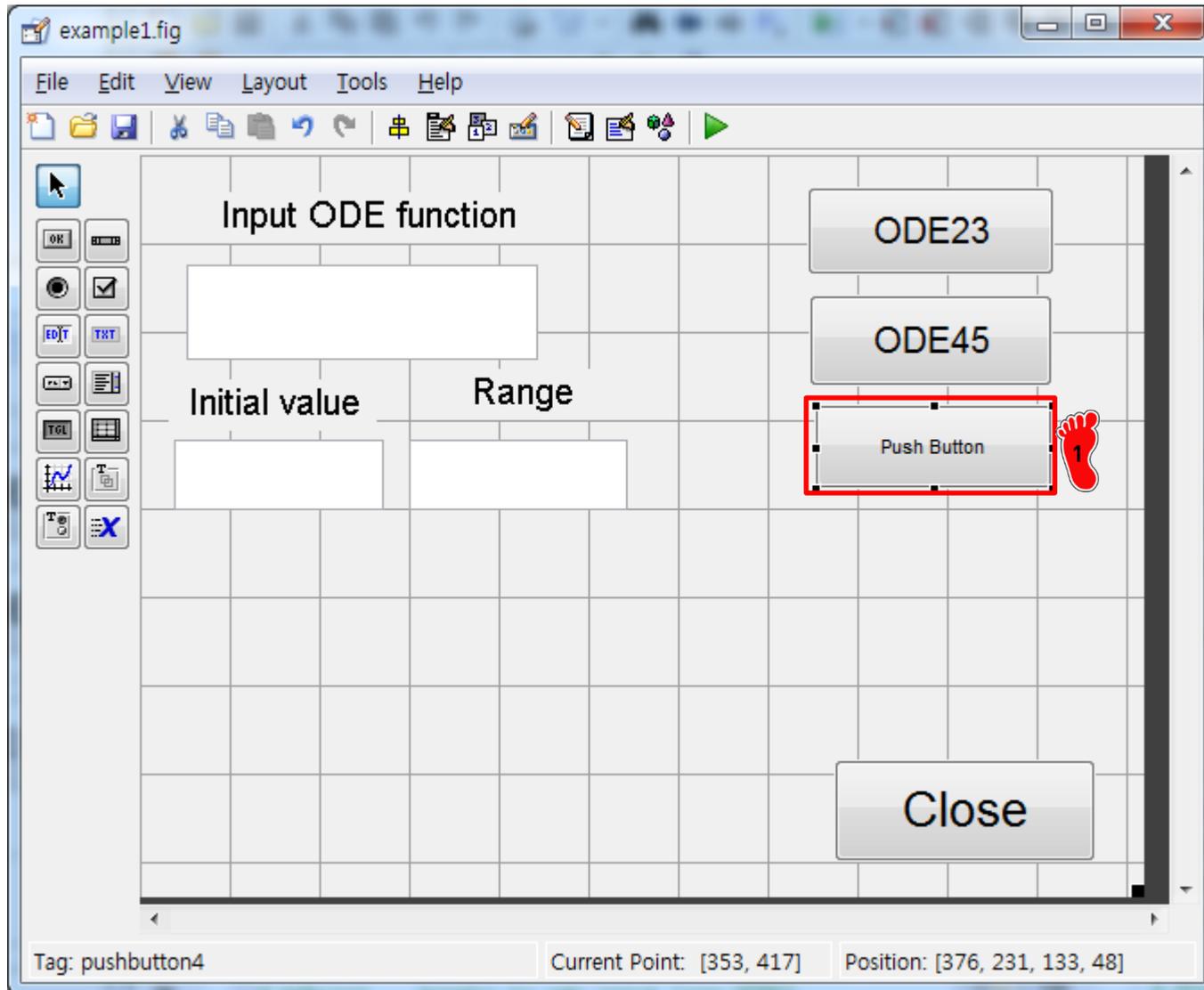
1 String ODE45 로 변경

2 FontSize 15 로 변경

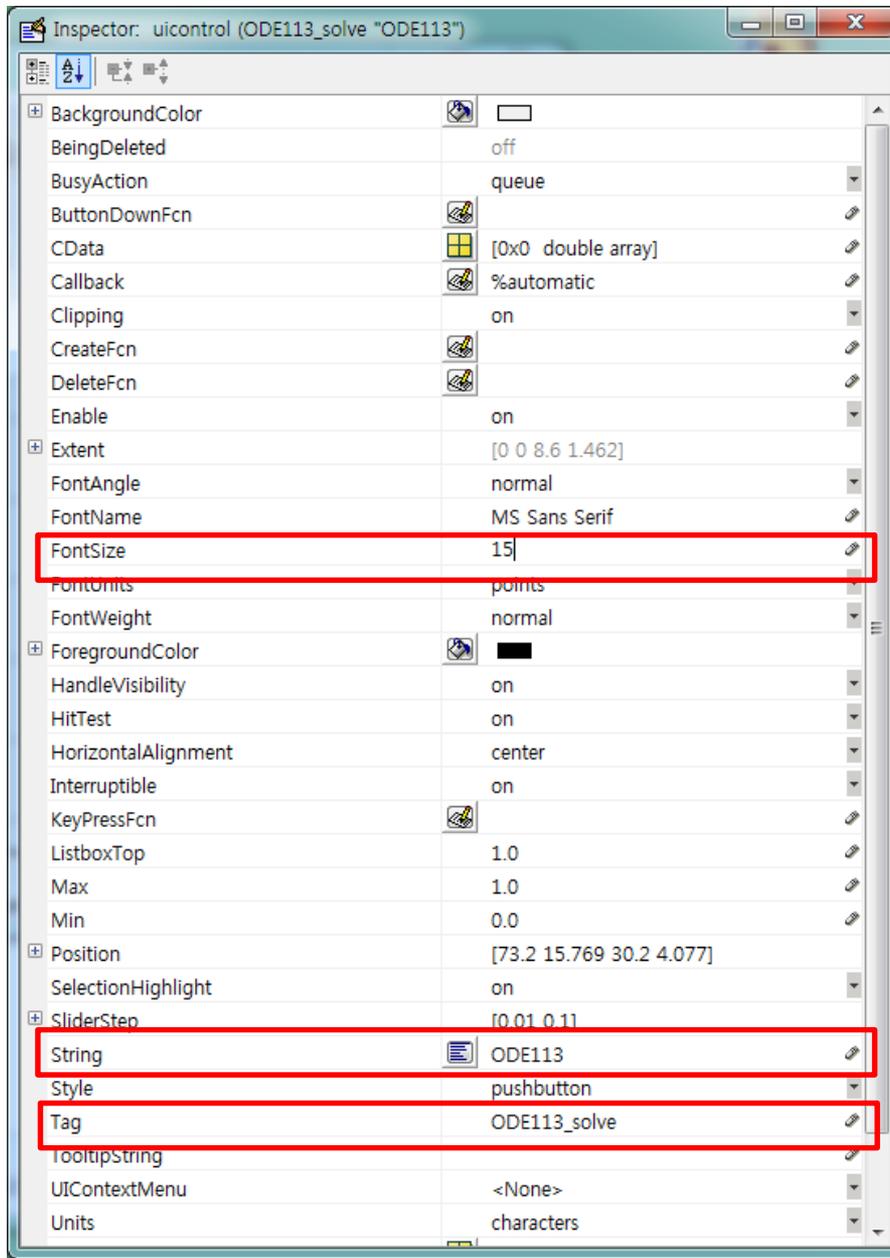
3 Tag 를 ODE45\_solve 로 변경

# ODE113 PUSH BUTTON

pushbutton 생성



# ODE113 PUSH BUTTON: INSPECTOR



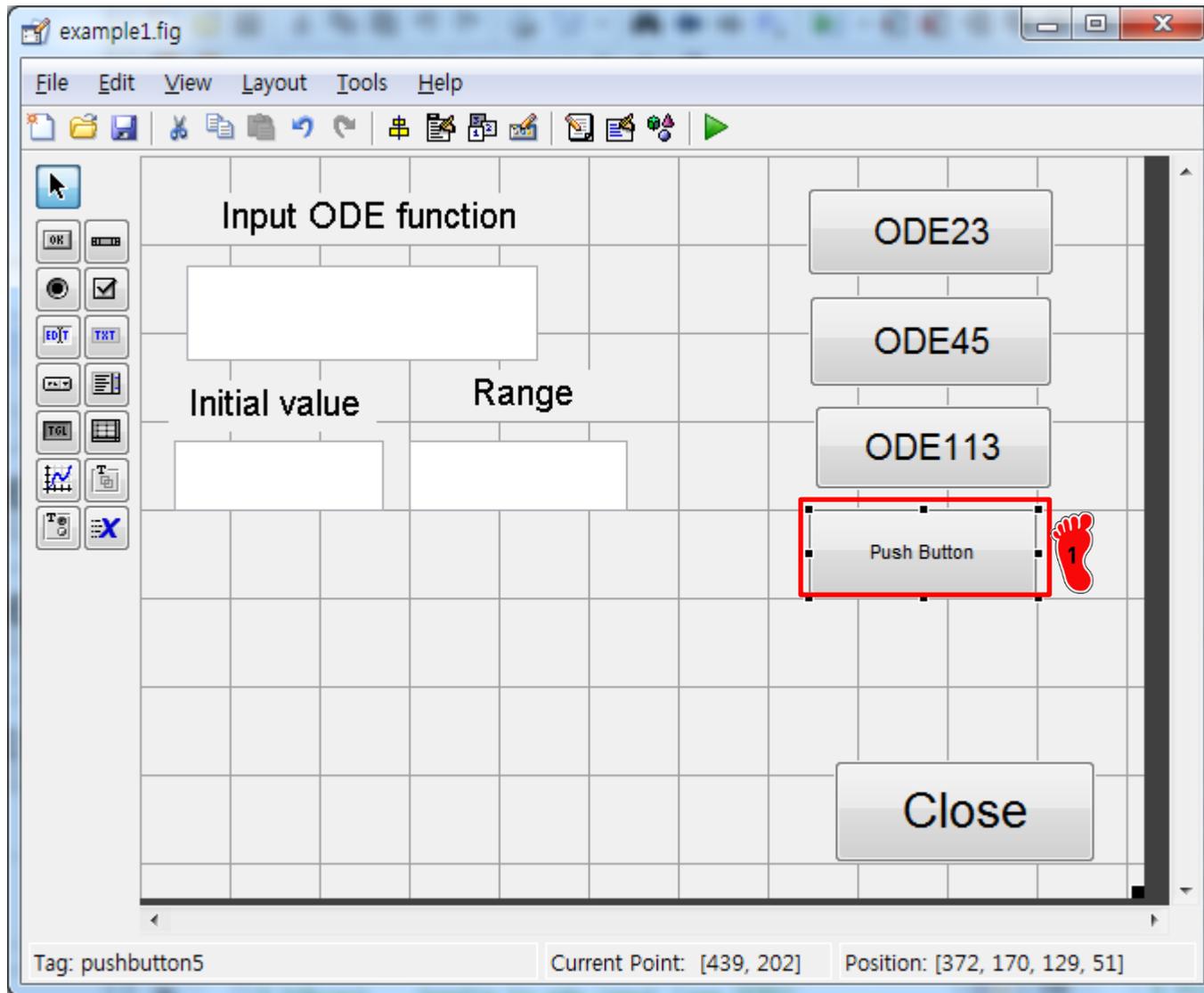
1 String ODE113 으로 변경

2 FontSize 15 로 변경

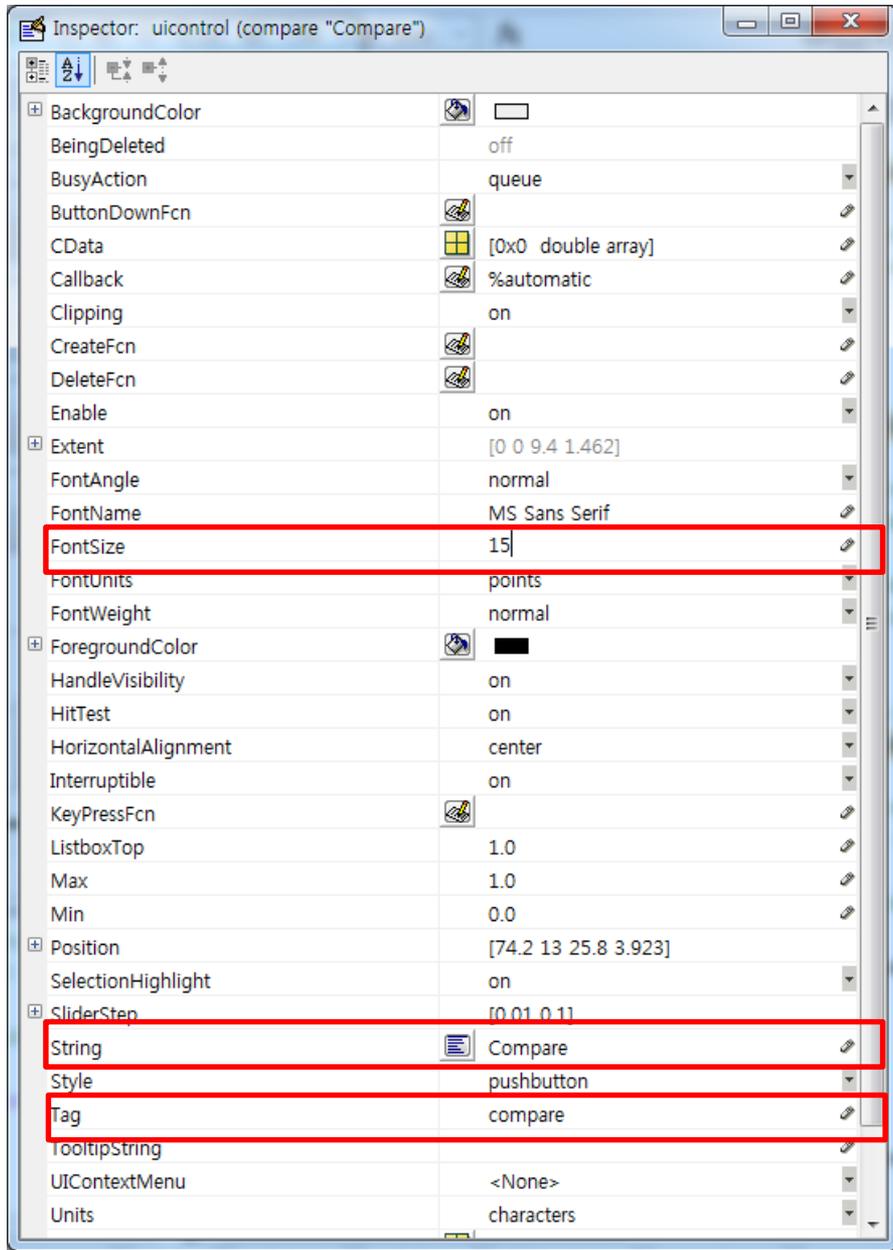
3 Tag 를 ODE113\_solve 로 변경

# COMPARE PUSH BUTTON

1 pushbutton 생성



# COMPARE PUSH BUTTON: INSPECTOR



1 String Compare 으로 변경

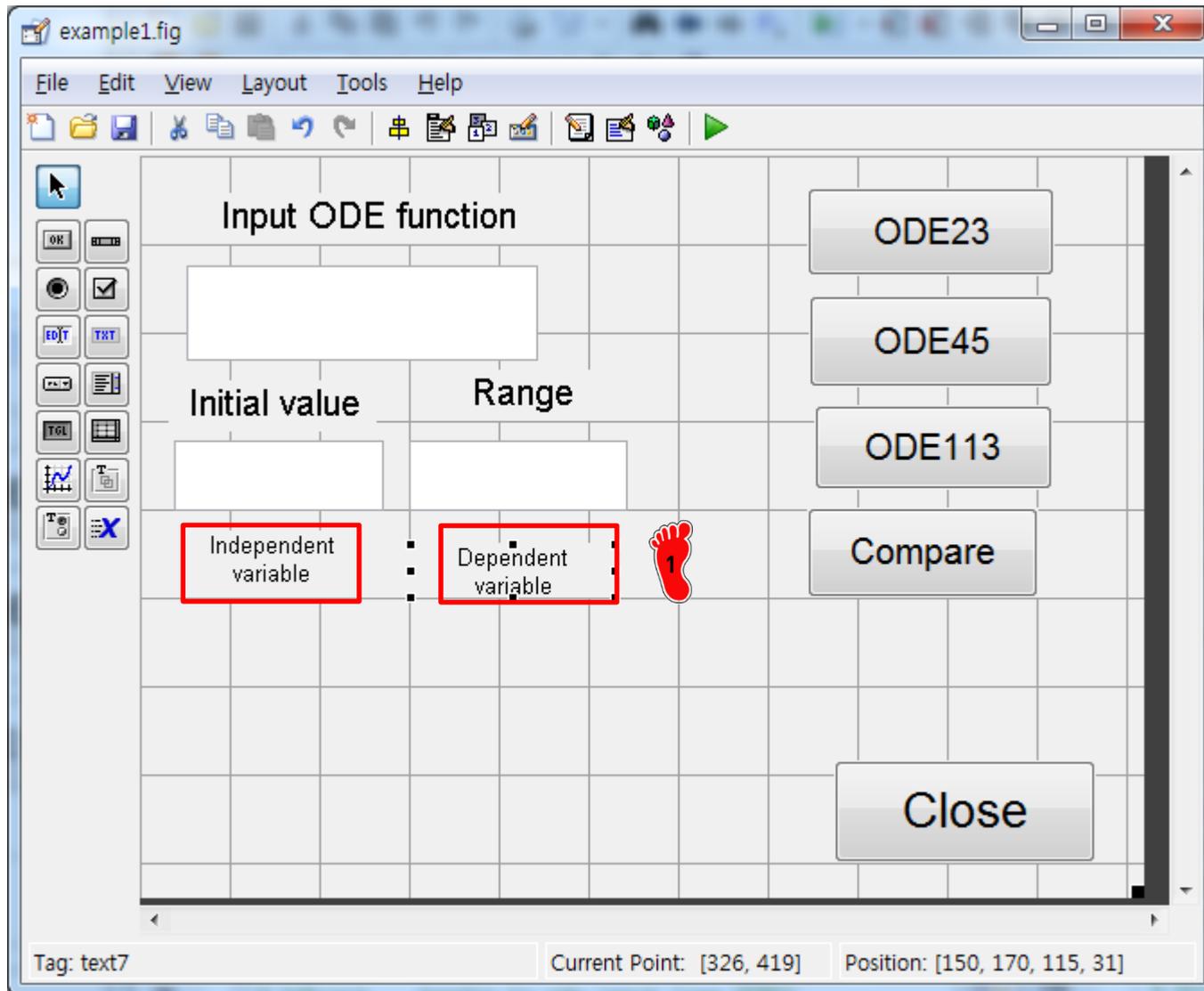
2 FontSize 15 로 변경

3 Tag 를 compare 로 변경

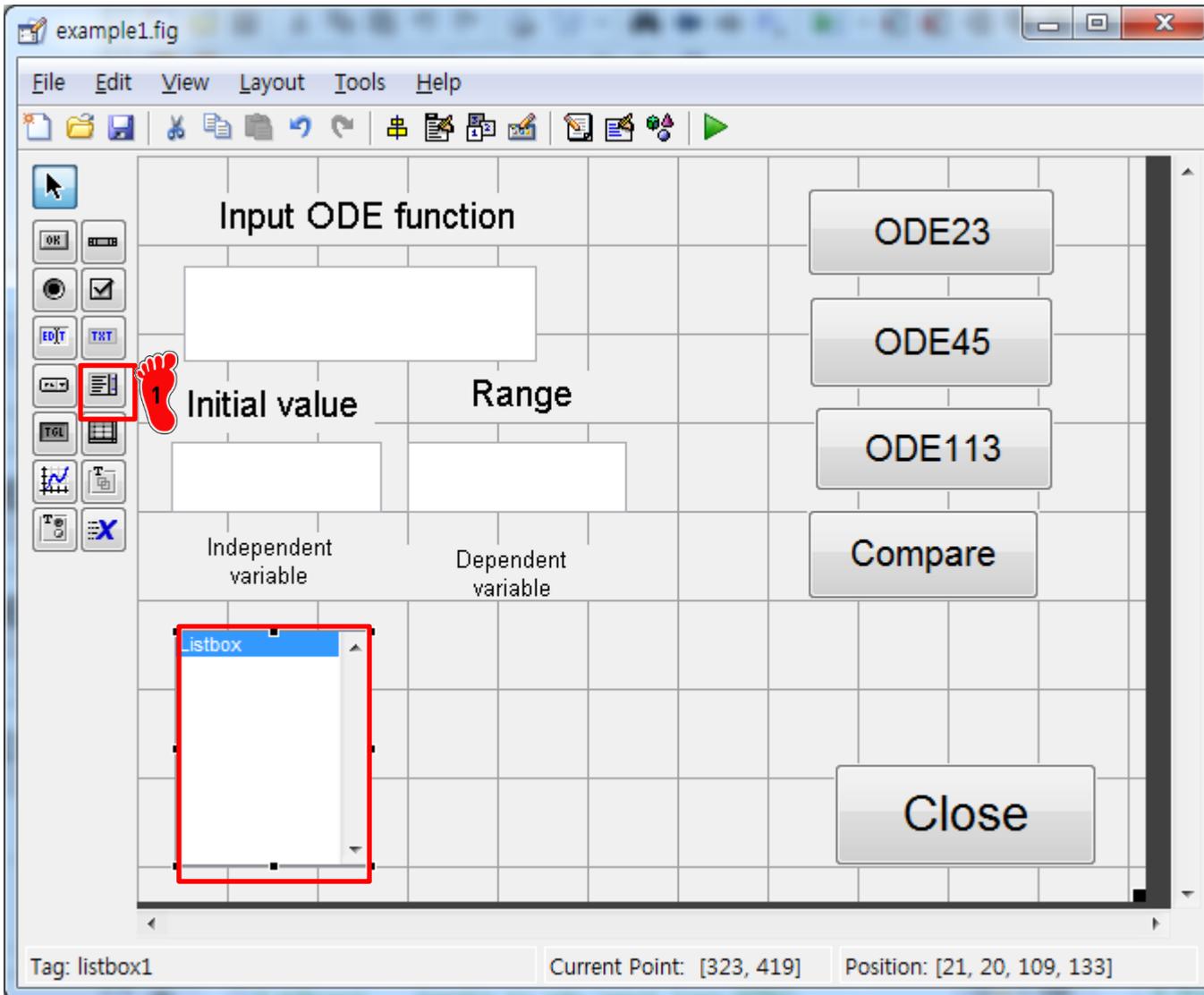
# STATIC TEXT BOX



Independent variable 과  
Dependent variable 이름을  
가득 static text box 2개 생  
성



# LIST BOX

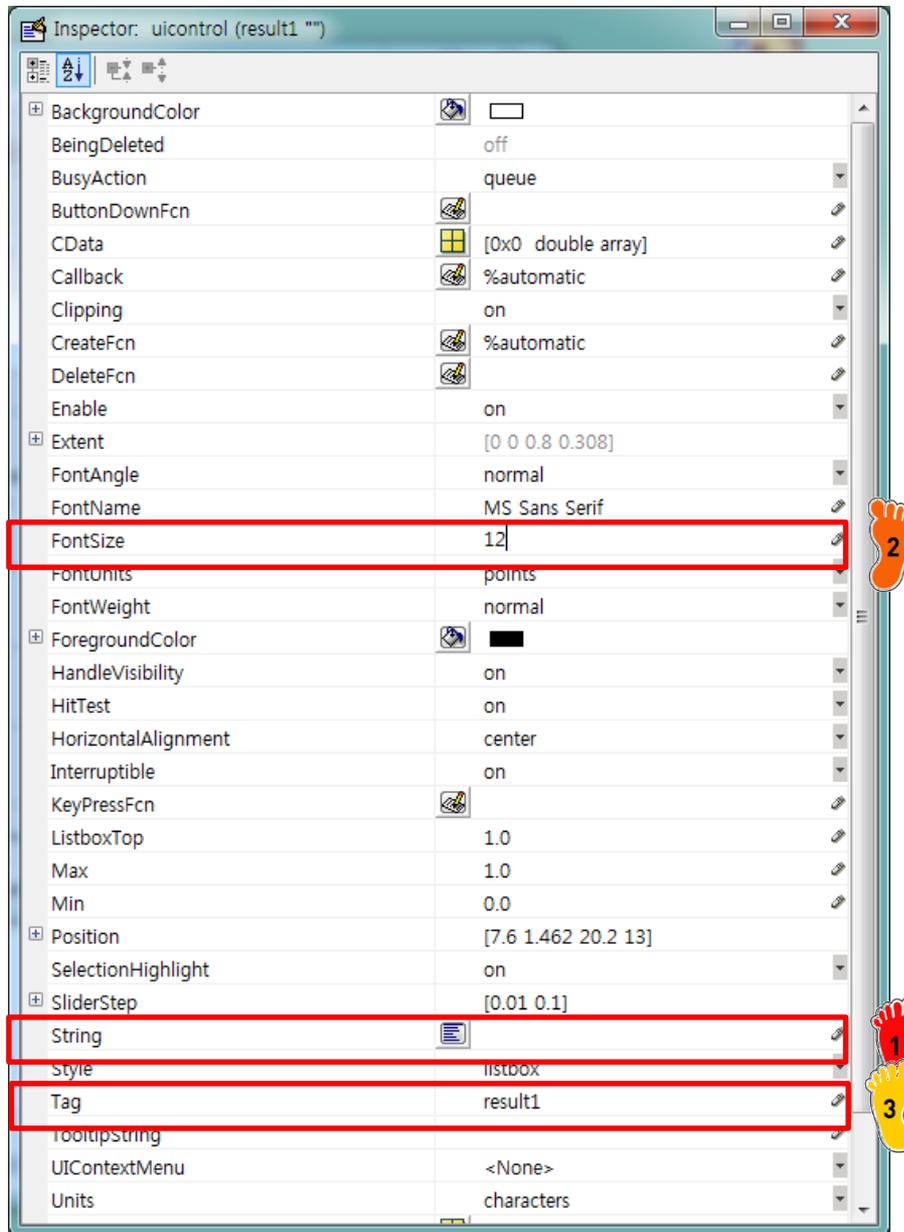


List box icon 클릭



List box 생성

# LIST BOX: INSPECTOR



1 String 빈칸으로 변경

2 FontSize 12 로 변경

3 Tag 를 result1 으로 변경

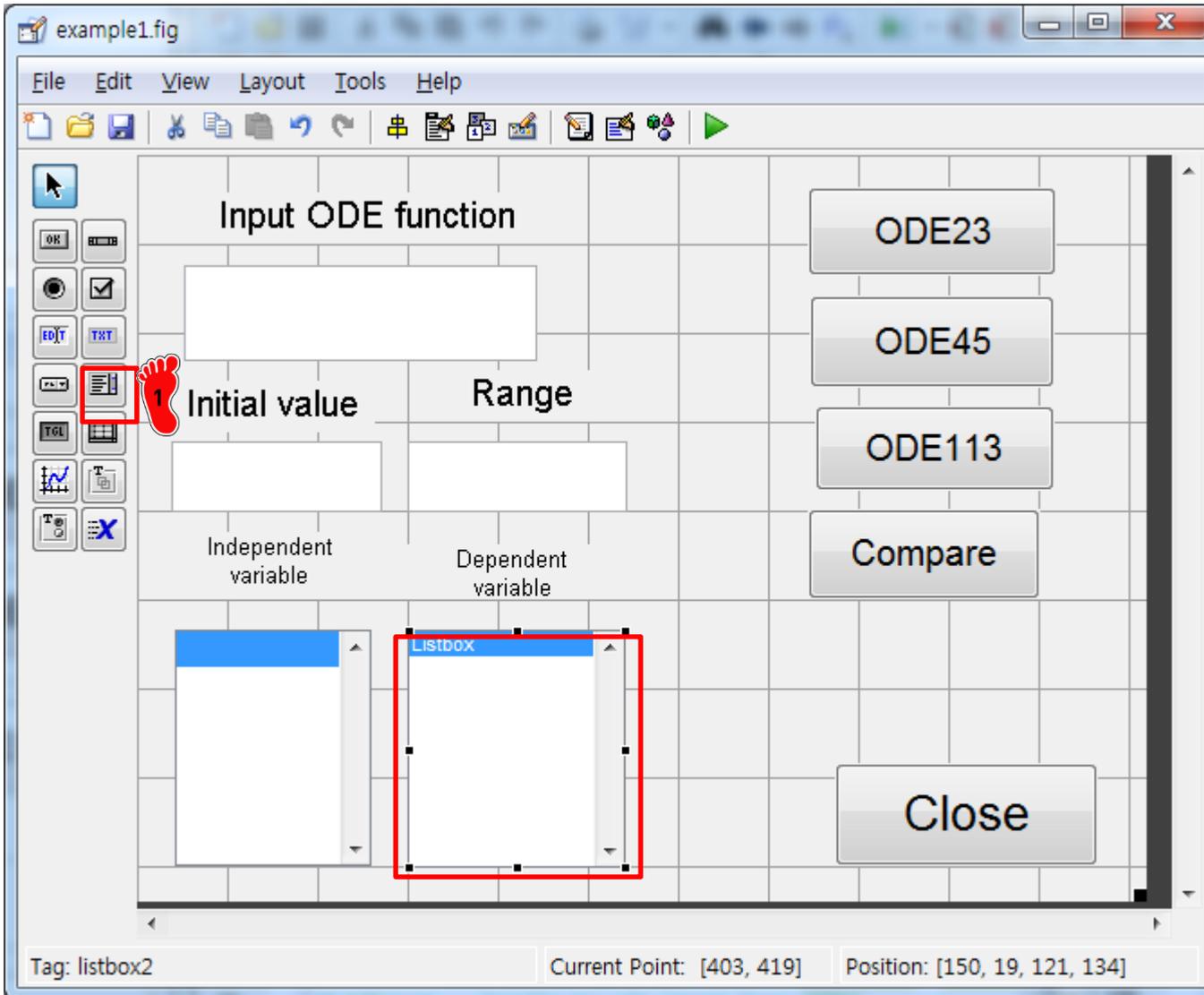
# LIST BOX



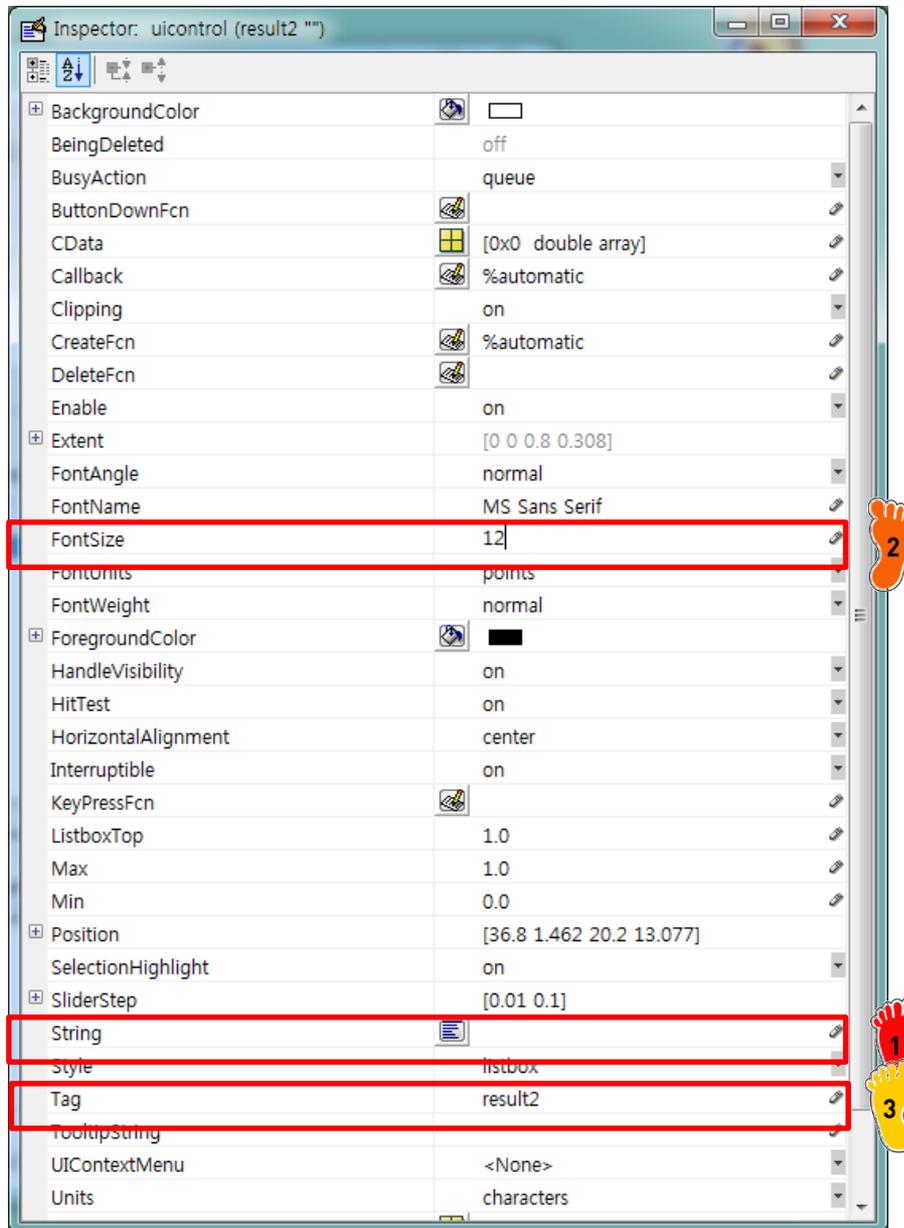
List box icon 클릭



List box 생성



# LIST BOX: INSPECTOR



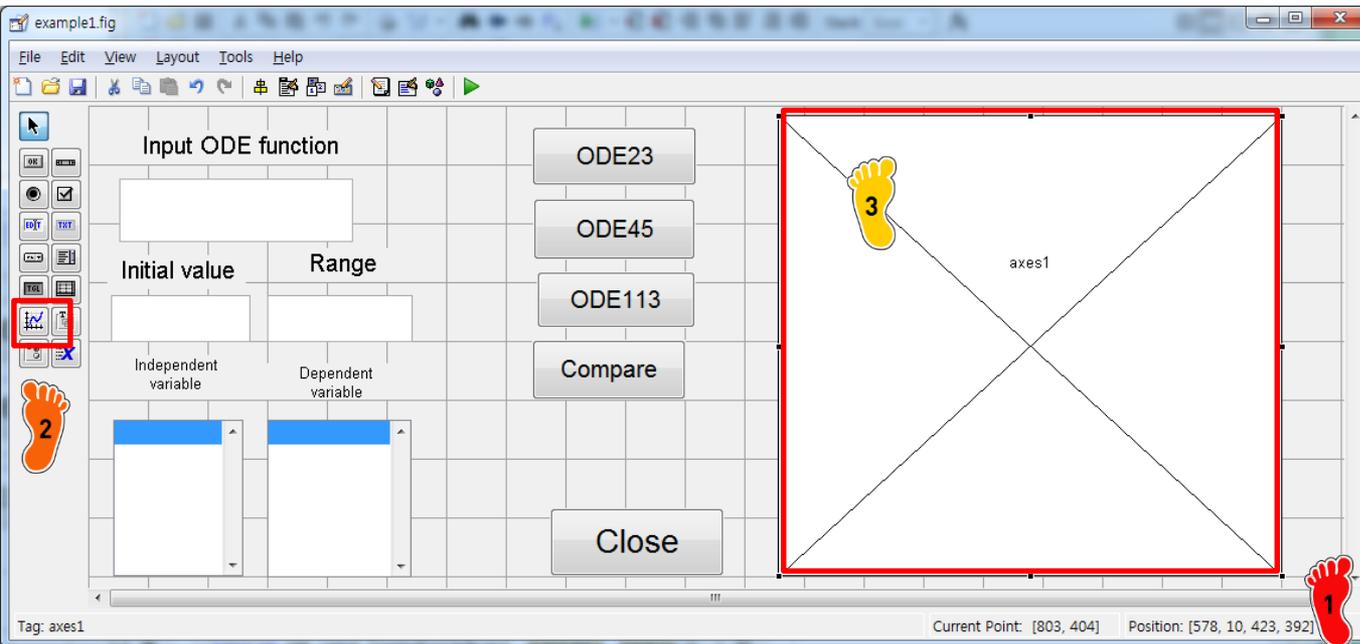
- 1 String 빈칸으로 변경
- 2 FontSize 12 로 변경
- 3 Tag 를 result2 로 변경

# GRAPH WINDOW

1 GUI window 창을 마우스 드래그 하여 늘림

2 axes 아이콘 클릭

3 graph 를 표시해주는 창 생성



# ODE23 PUSHBUTTON CODING

```

Editor - C:\Users\sean\Desktop\example1.m
File Edit Text Go Cell Tools Debug Desktop Window Help
153 % --- Executes on button press in ODE23_solve.
154 function ODE23_solve_Callback(hObject, eventdata, handles)
155 % hObject    handle to ODE23_solve (see GCBO)
156 % eventdata  reserved - to be defined in a future version of MATLAB
157 % handles    structure with handles and user data (see GUIDATA)
158 fun = get(handles.ode_input,'string');
159 initial_temp = get(handles.initial_value_input,'string');
160 range_temp = get(handles.range_input,'string');
161 initial = str2num(initial_temp);
162 range = str2num(range_temp);
163
164 dydt = inline(fun,'t','y');
165 [t,y] = ode23(dydt,range,initial);
166
167 blank={};
168 set(handles.result1,'String',blank);
169 set(handles.result2,'String',blank);
170
171 ResultsStr1 = t;
172 ResultsStr2 = y;
173
174 set(handles.result1,'String',ResultsStr1);
175 set(handles.result2,'String',ResultsStr2);
176
177 plot(t,y)
178
assignment6.m x ex.m x heatfun.m x ex1.m x dydxn.m x res.m x ex2_1.m x
example1 / ODE23_solve_Call... Ln 158 Col 39 OVR

```

1 ODE23\_solve 태그로 이동  
ode\_input 태그로 지정된 edit box 입력 값을 get 함수로 호출

initial 과 range 값은 숫자로 입력 해야 하기 때문에 str2num 명령어를 이용하여 숫자로 변경 후 저장

2 호출한 함수를 inline 명령어를 이용하여 함수로 지정  
ode23 함수로 실행

3 result1 과 result2 의 태그로 지정된 listbox 내용을 clear

4 결과 저장

5 결과를 listbox에 출력

6 그래프 출력

# ODE45&113 PUSHBUTTON CODING

```

Editor - C:\Users\sean\Desktop\example1.m
File Edit Text Go Cell Tools Debug Desktop Window Help
% --- Executes on button press in ODE45_solve.
180 function ODE45_solve_Callback(hObject, eventdata, handles)
181 % hObject    handle to ODE45_solve (see GCBO)
182 % eventdata  reserved - to be defined in a future version of MATLAB
183 % handles    structure with handles and user data (see GUIDATA)
184 fun = get(handles.ode_input,'string');
185 initial_temp = get(handles.initial_value_input,'string');
186 range_temp = get(handles.range_input,'string');
187 initial = str2num(initial_temp);
188 range = str2num(range_temp);
189
190 dydt = inline(fun,'t','y');
191 [t,y] = ode45(dydt,range,initial);
192
193 blank={};
194 set(handles.result1,'String',blank);
195 set(handles.result2,'String',blank);
196
197 ResultsStr1 = t;
198 ResultsStr2 = y;
199
200 set(handles.result1,'String',ResultsStr1);
201 set(handles.result2,'String',ResultsStr2);
202
203 plot(t,y)
204

```



ode함수 명령어만 변경 후  
나머지는 동일한 코드로 입력





# RESULT



함수 및 초기값과 range 입력 후 실행 버튼을 클릭하여 결과 확인

$$\frac{dy}{dx} = f(x, y) = 4e^{0.8x} - 0.5y$$

with  $y(0) = 2$  from  $x = 0 \sim 4$

