

# Two-phase Simplex Method (1)

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- How to handle “ $\geq$  type” or “equality” constraints ?
  - Initial basic feasible solution: not available  $\rightarrow$  artificial variables
  - New expanded space  $\rightarrow$  original space
  - Artificial variables: basic  $\rightarrow$  nonbasic
- To eliminate artificial variables
  - Artificial cost function: sum of all the artificial variables
- Phase I: to obtain the initial basic feasible solution

$$\begin{aligned} \text{Minimize } w &= \sum_{i=1}^m x_{n+i} \\ \text{subject to } \sum_{j=1}^n a_{ij}x_j + x_{n+i} &= b_i; \quad i = 1, \dots, m \\ x_j &\geq 0; \quad j = 1, \dots, n \end{aligned}$$

# Two-phase Simplex Method (2)

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- Not suitable form for the Simplex method
  - Artificial cost function: expressed in terms of nonbasic variables

$$\underbrace{w = \sum_{i=1}^m x_{n+i}}_{\text{in terms of basic variables}} = \sum_{i=1}^m \left( b_i - \sum_{j=1}^n a_{ij} x_j \right) = \sum_{i=1}^m b_i - \sum_{j=1}^n \sum_{i=1}^m a_{ij} x_j = \underbrace{\sum_{i=1}^m b_i + \sum_{j=1}^n c'_j x_j}_{\text{in terms of nonbasic variables}}$$

$$c'_j = -\sum_{i=1}^m a_{ij}; \quad j = 1, \dots, n$$

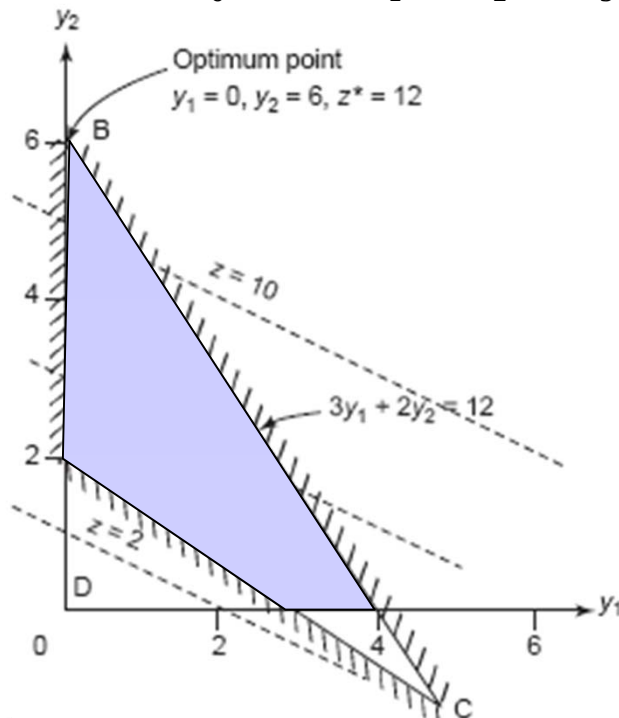
original cost function  $\rightarrow$  treated as a constraint

$$\begin{cases} w = 0: \text{ end of Phase I} \\ w \neq 0: \text{ infeasible problem} \end{cases}$$

# Example 8.14 (“ $\geq$ type”)

$$\left. \begin{array}{l} \text{Maximize } z = y_1 + 2y_2 \\ \text{subject to } 3y_1 + 2y_2 \leq 12 \\ 2y_1 + 3y_2 \geq 6 \\ y_1 \geq 0, y_2 \text{ unsigned} \end{array} \right\} \rightarrow \left\{ \begin{array}{l} \text{Minimize } f = -x_1 - 2x_2 + 2x_3 \\ \text{subject to } 3x_1 + 2x_2 - 2x_3 + x_4 = 12 \\ 2x_1 + 3x_2 - 3x_3 - x_5 + \boxed{x_6} = 6 \\ x_i \geq 0; \quad i = 1, \dots, 6 \end{array} \right.$$

$$w = x_6 = 6 - 2x_1 - 3x_2 + 3x_3 + x_5$$

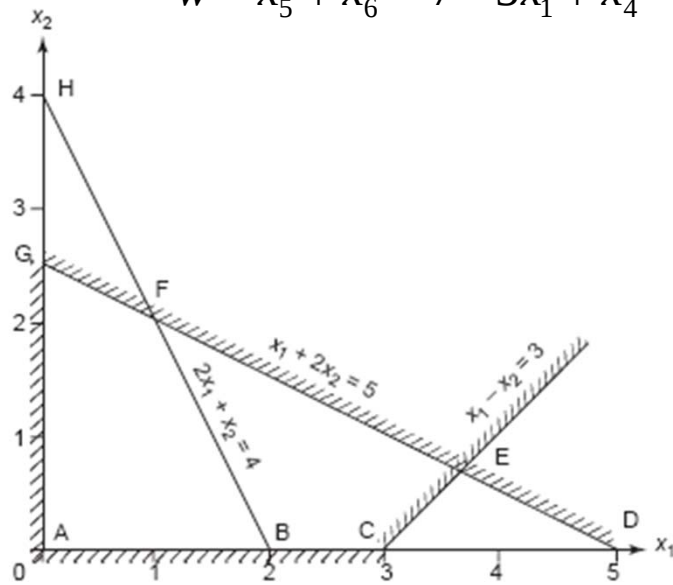


| Basic<br>↓                  | $x_1$         | $x_2$     | $x_3$ | $x_4$         | $x_5$          | $x_6$          | $b$      |                                              |
|-----------------------------|---------------|-----------|-------|---------------|----------------|----------------|----------|----------------------------------------------|
| $x_6$ out $\rightarrow x_4$ | 3             | 2         | -2    | 1             | 0              | 0              | 12       | Phase I: initial<br>tableau, pivot: $a_{22}$ |
| $x_2$ in $\rightarrow x_6$  | 2             | <u>3</u>  | -3    | 0             | -1             | 1              | 6        |                                              |
| Cost                        | -1            | -2        | 2     | 0             | 0              | 0              | $f - 0$  |                                              |
| Artificial cost             | -2            | <u>-3</u> | 3     | 0             | 1              | 0              | $w - 6$  |                                              |
| $x_4$ out $\rightarrow x_4$ | $\frac{5}{3}$ | 0         | 0     | 1             | $\frac{2}{3}$  | $-\frac{2}{3}$ | 8        | Second tableau<br>pivot: $a_{15}$            |
| $x_5$ in $\rightarrow x_2$  | $\frac{2}{3}$ | 1         | -1    | 0             | $-\frac{1}{3}$ | $\frac{1}{3}$  | 2        |                                              |
| Cost                        | $\frac{1}{3}$ | 0         | 0     | 0             | $-\frac{2}{3}$ | $\frac{2}{3}$  | $f + 4$  |                                              |
| Artificial cost             | 0             | 0         | 0     | 0             | 0              | 1              | $w - 0$  | End of Phase I                               |
| $x_5$                       | $\frac{5}{2}$ | 0         | 0     | $\frac{3}{2}$ | 1              | -1             | 12       | Third tableau:<br>optimum solution           |
| $x_2$                       | $\frac{3}{2}$ | 1         | -1    | $\frac{1}{2}$ | 0              | 0              | 6        |                                              |
| Cost                        | 2             | 0         | 0     | 1             | 0              | 0              | $f + 12$ | End of Phase II                              |

# Example 8.15 (“equality”)

$$\left. \begin{array}{l} \text{Maximize } z = x_1 + 4x_2 \\ \text{subject to } x_1 + 2x_2 \leq 5 \\ 2x_1 + x_2 = 4 \\ x_1 - x_2 \geq 3 \\ x_1, x_2 \geq 0 \end{array} \right\} \rightarrow \left\{ \begin{array}{l} \text{Minimize } f = -x_1 - 4x_2 \\ \text{subject to } x_1 + 2x_2 + x_3 = 5 \\ 2x_1 + x_2 + x_5 = 4 \\ x_1 - x_2 - x_4 + x_6 = 3 \\ x_i \geq 0; \quad i = 1, \dots, 6 \end{array} \right.$$

$$w = x_5 + x_6 = 7 - 3x_1 + x_4$$



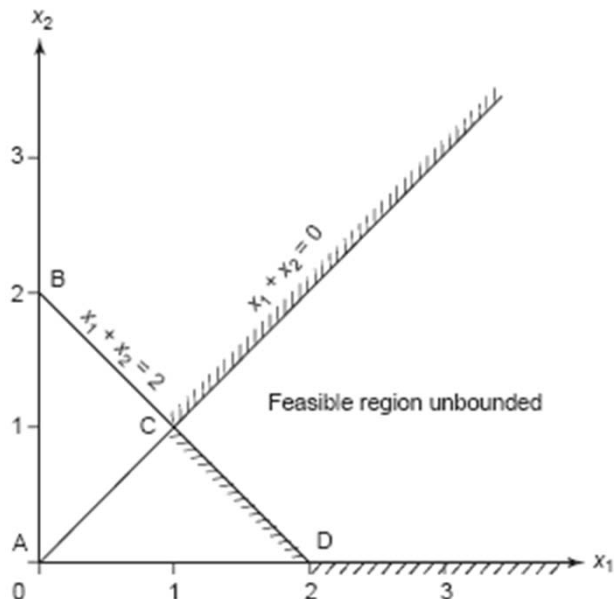
(infeasible problem)

| Basic<br>↓                                             | $x_1$     | $x_2$          | $x_3$ | $x_4$ | $x_5$          | $x_6$ | $b$     |                                    |
|--------------------------------------------------------|-----------|----------------|-------|-------|----------------|-------|---------|------------------------------------|
| $x_5$ out<br>$x_1$ in<br>→ $x_3$<br>→ $x_5$<br>→ $x_6$ | 1         | 2              | 1     | 0     | 0              | 0     | 5       | Initial tableau<br>pivot: $a_{21}$ |
|                                                        | <u>2</u>  | 1              | 0     | 0     | 1              | 0     | 4       |                                    |
|                                                        | 1         | -1             | 0     | -1    | 0              | 1     | 3       |                                    |
| Cost                                                   | -1        | -4             | 0     | 0     | 0              | 0     | $f - 0$ |                                    |
| Artificial cost                                        | <u>-3</u> | 0              | 0     | 1     | 0              | 0     | $w - 7$ |                                    |
| $x_3$                                                  | 0         | $\frac{3}{2}$  | 1     | 0     | $-\frac{1}{2}$ | 0     | 3       | Second tableau                     |
| $x_1$                                                  | 1         | $\frac{1}{2}$  | 0     | 0     | $\frac{1}{2}$  | 0     | 2       |                                    |
| $x_6$                                                  | 0         | $-\frac{3}{2}$ | 0     | -1    | $-\frac{1}{2}$ | 1     | 1       |                                    |
| Cost                                                   | 0         | $-\frac{7}{2}$ | 0     | 0     | $\frac{1}{2}$  | 0     | $f + 2$ |                                    |
| Artificial cost                                        | 0         | $\frac{3}{2}$  | 0     | 1     | $\frac{3}{2}$  | 0     | $w + 1$ | End of Phase I                     |

# Example 8.16 (unbounded)

$$\left. \begin{array}{l} \text{Maximize } z = 3x_1 - 2x_2 \\ \text{subject to } x_1 - x_2 \geq 0 \\ x_1 + x_2 \geq 2 \\ x_1, x_2 \geq 0 \end{array} \right\} \rightarrow \left\{ \begin{array}{l} \text{Minimize } f = -3x_1 + 2x_2 \\ \text{subject to } -x_1 + x_2 + x_3 = 0 \\ x_1 + x_2 - x_4 + x_5 = 2 \\ x_i \geq 0; \quad i = 1, \dots, 5 \end{array} \right.$$

$$w = x_5 = 2 - x_1 - x_2 + x_4$$



| Basic<br>↓                              | $x_1$     | $x_2$ | $x_3$ | $x_4$     | $x_5$ | $b$     |                                     |
|-----------------------------------------|-----------|-------|-------|-----------|-------|---------|-------------------------------------|
| $x_5$ out<br>$x_1$ in $\rightarrow x_3$ | -1        | 1     | 1     | 0         | 0     | 0       | Initial tableau,<br>pivot: $a_{21}$ |
|                                         | <u>1</u>  | 1     | 0     | -1        | 1     | 2       |                                     |
| Cost                                    | -3        | 2     | 0     | 0         | 0     | $f - 0$ |                                     |
| Artificial cost                         | <u>-1</u> | -1    | 0     | 1         | 0     | $w - 2$ |                                     |
| $x_3$                                   | 0         | 2     | 1     | -1        | 1     | 2       | Second tableau                      |
| $x_1$                                   | 1         | 1     | 0     | -1        | 1     | 2       |                                     |
| Cost                                    | 0         | 5     | 0     | <u>-3</u> | 3     | $f + 6$ |                                     |
| Artificial cost                         | 0         | 0     | 0     | 0         | 1     | $w - 0$ |                                     |
| End of Phase I                          |           |       |       |           |       |         | End of Phase II                     |

# Example 8.17

- Degenerate basic feasible solution

$$\left. \begin{array}{l} \text{Maximize } z = x_1 + 4x_2 \\ \text{subject to } x_1 + 2x_2 \leq 5 \\ 2x_1 + x_2 \leq 4 \\ 2x_1 + x_2 \geq 4 \\ x_1 - x_2 \geq 1 \\ x_1, x_2 \geq 0 \end{array} \right\} \rightarrow$$

$$\left\{ \begin{array}{l} \text{Minimize } f = -x_1 - 4x_2 \\ \text{subject to } x_1 + 2x_2 + x_3 = 5 \\ 2x_1 + x_2 + x_4 = 4 \\ 2x_1 + x_2 - x_5 + x_7 = 4 \\ x_1 - x_2 - x_6 + x_8 = 1 \\ x_i \geq 0; \quad i = 1, \dots, 8 \end{array} \right.$$

$$w = x_7 + x_8 = 5 - 3x_1 + x_5 + x_6$$

*Solution for Example 8.17 (degenerate basic feasible solution)*

| Basic<br>↓                    | $x_1$     | $x_2$     | $x_3$ | $x_4$         | $x_5$                            | $x_6$          | $x_7$         | $x_8$          | $b$                |                                                        |
|-------------------------------|-----------|-----------|-------|---------------|----------------------------------|----------------|---------------|----------------|--------------------|--------------------------------------------------------|
| $x_3$                         | 1         | 2         | 1     | 0             | 0                                | 0              | 0             | 0              | 5                  | <i>Initial tableau,<br/>pivot: <math>a_{14}</math></i> |
| $x_4$                         | 2         | 1         | 0     | 1             | 0                                | 0              | 0             | 0              | 4                  |                                                        |
| $x_7$                         | 2         | 1         | 0     | 0             | -1                               | 0              | 1             | 0              | 4                  |                                                        |
| $x_8$ out<br>$x_1$ in → $x_8$ | <u>1</u>  | -1        | 0     | 0             | 0                                | -1             | 0             | 1              | 1                  |                                                        |
| Cost                          | -1        | -4        | 0     | 0             | 0                                | 0              | 0             | 0              | $f - 0$            |                                                        |
| Artificial                    | <u>-3</u> | 0         | 0     | 0             | 1                                | 1              | 0             | 0              | $w - 5$            |                                                        |
| $x_3$                         | 0         | 3         | 1     | 0             | 0                                | 1              | 0             | -1             | 4                  | <i>Second tableau,<br/>pivot: <math>a_{23}</math></i>  |
| $x_4$                         | 0         | 3         | 0     | 1             | 0                                | 2              | 0             | -2             | 2                  |                                                        |
| $x_7$ out<br>$x_2$ in → $x_7$ | 0         | <u>3</u>  | 0     | 0             | -1                               | 2              | 1             | -2             | 2                  |                                                        |
| $x_1$                         | 1         | -1        | 0     | 0             | 0                                | -1             | 0             | 1              | 1                  |                                                        |
| Cost                          | 0         | -5        | 0     | 0             | 0                                | -1             | 0             | 1              | $f + 1$            |                                                        |
| Artificial                    | 0         | <u>-3</u> | 0     | 0             | 1                                | -2             | 0             | 3              | $w - 2$            |                                                        |
| $x_3$                         | 0         | 0         | 1     | 0             | 1                                | -1             | -1            | 1              | 2                  | <i>Third tableau,<br/>pivot: <math>a_{25}</math></i>   |
| $x_4$ out<br>$x_5$ in → $x_4$ | 0         | 0         | 0     | 1             | <u>1</u>                         | 0              | -1            | <u>-2</u>      | <u>0</u>           |                                                        |
| $x_2$                         | 0         | 1         | 0     | 0             | $-\frac{1}{3}$                   | $\frac{2}{3}$  | $\frac{1}{3}$ | $\frac{1}{3}$  | $\frac{4}{3}$      |                                                        |
| $x_1$                         | 1         | 0         | 0     | 0             | $-\frac{1}{3}$                   | $-\frac{1}{3}$ | $\frac{1}{3}$ | 1              | $\frac{5}{3}$      |                                                        |
| Cost                          | 0         | 0         | 0     | 0             | <u><math>-\frac{5}{3}</math></u> | $\frac{7}{3}$  | $\frac{5}{3}$ | 1              | $f + \frac{13}{3}$ |                                                        |
| Artificial                    | 0         | 0         | 0     | 0             | 0                                | 0              | 1             | 3              | $w - 0$            |                                                        |
| <i>End of Phase I</i>         |           |           |       |               |                                  |                |               |                |                    |                                                        |
| $x_3$                         | 0         | 0         | 1     | -1            | 0                                | -1             | 0             | 1              | 2                  | <i>Final tableau</i>                                   |
| $x_5$                         | 0         | 0         | 0     | 1             | 1                                | 0              | -1            | 0              | <u>0</u>           |                                                        |
| $x_2$                         | 0         | 1         | 0     | $\frac{1}{3}$ | 0                                | $\frac{2}{3}$  | 0             | $-\frac{2}{3}$ | $\frac{4}{3}$      |                                                        |
| $x_1$                         | 1         | 0         | 0     | $\frac{1}{3}$ | 0                                | $-\frac{1}{3}$ | 0             | $\frac{1}{3}$  | $\frac{5}{3}$      |                                                        |
| Cost                          | 0         | 0         | 0     | $\frac{5}{3}$ | 0                                | $\frac{7}{3}$  | 0             | $-\frac{7}{3}$ | $f + \frac{13}{3}$ |                                                        |
| <i>End of Phase II</i>        |           |           |       |               |                                  |                |               |                |                    |                                                        |

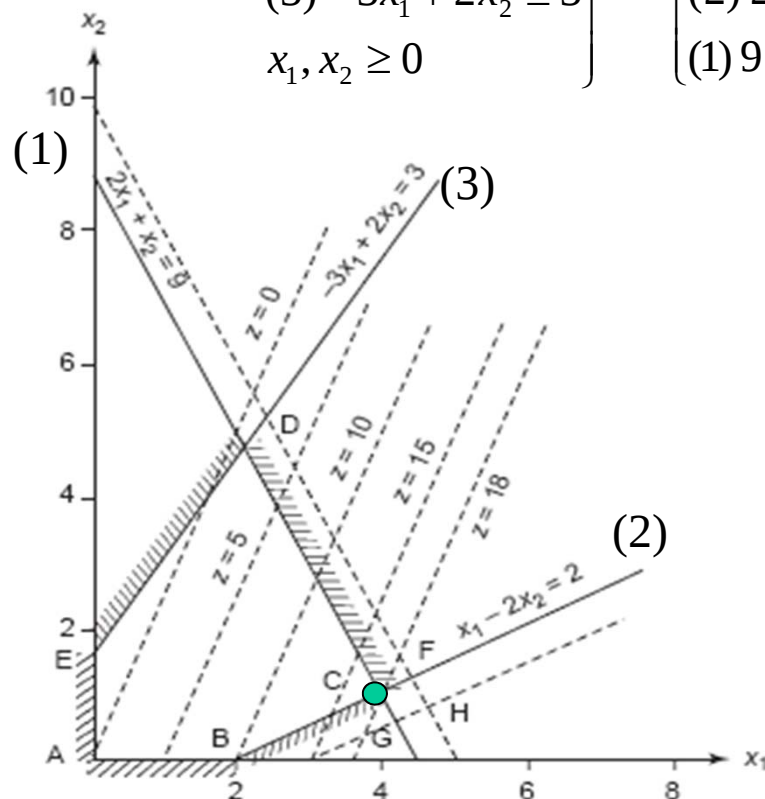
# Post-Optimality Analysis

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- Parameter changes:  $\mathbf{c}, \mathbf{b}, \mathbf{A} \rightarrow$  optimum solution ?
  - Use of the optimum solution of the original problem if changes in the parameters are within certain limits
  - Need information on Lagrange multiplier
- Lagrange multiplier for the  $i$ -th constraint
  - Reduced cost coefficient in the slack or artificial variable column associated w/ the  $i$ -th constraint
    - “ $\leq$  type” : nonnegative (slack variable column)
    - “ $=$  type” : unrestricted in sign (artificial variable column)
    - “ $\geq$  type” : nonpositive (artificial variable column = -surplus variable column)
  - $\frac{\partial f}{\partial e_i} = -y_i$  : minimization problem w/ “ $\leq$  type” or equality constraints

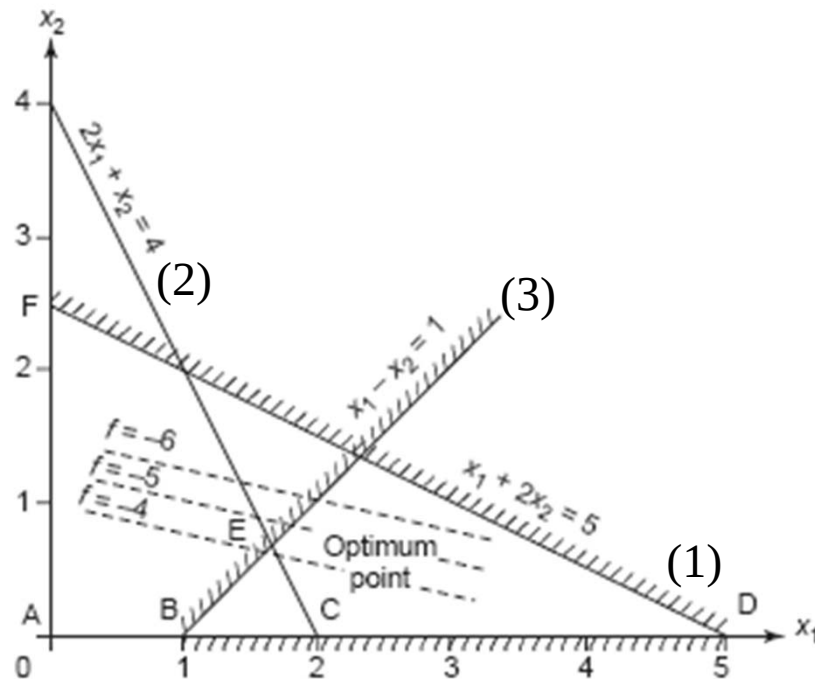
# Example 8.18

$$\left. \begin{array}{l} \text{Maximize } z = 5x_1 - 2x_2 \\ \text{subject to } (1) 2x_1 + x_2 \leq 9 \\ (2) x_1 - 2x_2 \leq 2 \\ (3) -3x_1 + 2x_2 \leq 3 \\ x_1, x_2 \geq 0 \end{array} \right\} \rightarrow \left\{ \begin{array}{l} \frac{\partial f}{\partial e_1} = \quad, \frac{\partial f}{\partial e_2} = \quad, \frac{\partial f}{\partial e_3} = \quad \\ (1) 9 \rightarrow 10, \\ (2) 2 \rightarrow 3, \\ (1) 9 \rightarrow 10 \text{ \& } (2) 2 \rightarrow 3, \end{array} \right.$$



# Example 8.19 ← 8.13

$$\left. \begin{array}{l} \text{Maximize } z = x_1 + 4x_2 \\ \text{subject to } (1) x_1 + 2x_2 \leq 5 \\ (2) 2x_1 + x_2 = 4 \\ (3) x_1 - x_2 \geq 1 \\ x_1, x_2 \geq 0 \end{array} \right\} \rightarrow \left\{ \begin{array}{l} \text{Minimize } f = -x_1 - 4x_2 \\ \text{subject to } x_1 + 2x_2 + x_3 = 5 \\ 2x_1 + x_2 + x_5 = 4 \\ x_1 - x_2 - x_4 + x_6 = 1 \\ x_i \geq 0; \quad i = 1, \dots, 6 \end{array} \right.$$



$$\left\{ \begin{array}{l} \frac{\partial f}{\partial e_2} = -y_2 = \quad ; (2) 4 \rightarrow 5, f = \\ \frac{\partial f}{\partial e_3} = -y_3 = \quad ; (3) 1 \rightarrow 2, f = \end{array} \right.$$

# Ranging

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- Limits on changes in resources

$\Delta_k$  : possible change in  $b_k$

$$\max_i \left\{ \frac{-b'_i}{a'_{ij}}; a'_{ij} > 0 \right\} \leq \Delta_k \leq \min_i \left\{ \frac{-b'_i}{a'_{ij}}; a'_{ij} < 0 \right\}$$

$b''_i = b'_i + \Delta_k a'_{ij}$  : new values of design variables

- Ranging cost coefficients

$$c_k \rightarrow c_k + \Delta c_k$$

for cost coefficient of basic variables

$$\max_j \left\{ \frac{c'_j}{a'_{rj}} < 0 \right\} \leq \Delta c_k \leq \min_j \left\{ \frac{c'_j}{a'_{rj}} > 0 \right\}$$

$r$  : row that determines  $x_k^*$ ,  $j$  : nonbasic columns excluding artificial columns

$$f^*_{new} = f^* + \Delta c_k x_k^*$$

# Example 8.18+20+22 ( $\leq$ type)

| Basic<br>↓                  | $x_1$      | $x_2$      | $x_3$      | $x_4$      | $x_5$      | $b$      |
|-----------------------------|------------|------------|------------|------------|------------|----------|
| $x_4$ out $\rightarrow x_3$ | 2          | 1          | 1          | 0          | 0          | 9        |
| $x_1$ in $\rightarrow x_4$  | <u>1</u>   | -2         | 0          | 1          | 0          | 2        |
|                             | -3         | 2          | 0          | 0          | 1          | 3        |
| Cost                        | <u>-5</u>  | 2          | 0          | 0          | 0          | $f - 0$  |
| $x_3$ out $\rightarrow x_2$ | 0          | <u>5</u>   | 1          | -2         | 0          | 5        |
| $x_2$ in $\rightarrow x_3$  | 1          | -2         | 0          | 1          | 0          | 2        |
|                             | 0          | -4         | 0          | 3          | 1          | 9        |
| Cost                        | 0          | <u>-8</u>  | 0          | 5          | 0          | $f + 10$ |
| $x_2$                       | 0          | 1          | 0.2        | -0.4       | 0          | 1        |
| $x_1$                       | 1          | 0          | 0.4        | 0.2        | 0          | 4        |
| $x_5$                       | 0          | 0          | 0.8        | 1.4        | 1          | 13       |
| Cost                        | 0          | 0          | 1.6        | 1.8        | 0          | $f + 18$ |
|                             | $\uparrow$ | $\uparrow$ | $\uparrow$ | $\uparrow$ | $\uparrow$ |          |
|                             | $c'_1$     | $c'_2$     | $c'_3$     | $c'_4$     | $c'_5$     |          |

[constraint 1  $\rightarrow x_3$  (column 3)]

$$r_i = -\frac{b'_i}{a'_{i3}} = \left\{ -\frac{1}{0.2}, -\frac{4}{0.4}, -\frac{13}{0.8} \right\} = \{-5.0, -10.0, -16.25\}$$

$$-5.0 \leq \Delta_1 \leq \infty \xrightarrow{b_1=9} 4 \leq b_1 \leq \infty$$

[cost coefficient 1  $\rightarrow x_1$  (row 2)]

$$d_j = \frac{c'_j}{a'_{2j}} = \left\{ \frac{1.6}{0.4}, \frac{1.8}{0.2} \right\} = \{4.0, 9.0\}$$

$$-\infty \leq \Delta c_1 \leq 4 \xrightarrow{c_1=-5} -\infty \leq c_1 \leq -1$$

[constraint 1:  $9 \rightarrow 10$  ( $\Delta_1 = 1$ )]

$$\begin{cases} x_2 = b''_1 = b'_1 + \Delta_1 a'_{13} = 1 + (1)(0.2) = 1.2 \\ x_1 = b''_2 = b'_2 + \Delta_1 a'_{23} = 4 + (1)(0.4) = 4.4 \\ x_5 = b''_3 = b'_3 + \Delta_1 a'_{33} = 13 + (1)(0.8) = 13.8 \end{cases}$$

[cost coefficient 1:  $-5 \rightarrow -4$  ( $\Delta c_1 = 1$ )]

$$f_{new}^* = f^* + \Delta c_1 x_1^* = -18 + (1)(4) = -14$$

# Example 8.19+21+23 (= or ≥ type)

| Basic<br>↓     | $x_1$     | $x_2$     | $x_3$    | $x_4$           | $x_5$                           | $x_6$                            | $b$                |
|----------------|-----------|-----------|----------|-----------------|---------------------------------|----------------------------------|--------------------|
| $x_3$          | 1         | 2         | 1        | 0               | 0                               | 0                                | 5                  |
| $x_5$          | 2         | 1         | 0        | 0               | 1                               | 0                                | 4                  |
| $x_6$          | <u>1</u>  | -1        | 0        | -1              | 0                               | 1                                | 1                  |
| Cost           | -1        | -4        | 0        | 0               | 0                               | 0                                | $f - 0$            |
| Artificial     | <u>-3</u> | 0         | 0        | 1               | 0                               | 0                                | $w - 5$            |
| $x_3$          | 0         | 3         | 1        | 1               | 0                               | -1                               | 4                  |
| $x_5$          | 0         | <u>3</u>  | 0        | 2               | 1                               | -2                               | 2                  |
| $x_1$          | 1         | -1        | 0        | -1              | 0                               | 1                                | 1                  |
| Cost           | 0         | -5        | 0        | -1              | 0                               | 1                                | $f + 1$            |
| Artificial     | 0         | <u>-3</u> | 0        | -2              | 0                               | 3                                | $w - 2$            |
| $x_3$          | 0         | 0         | 1        | -1              | -1                              | 1                                | 2                  |
| $x_2$          | 0         | 1         | 0        | $\frac{2}{3}$   | $\frac{1}{3}$                   | $-\frac{2}{3}$                   | $\frac{2}{3}$      |
| $x_1$          | 1         | 0         | 0        | $-\frac{1}{3}$  | $\frac{1}{3}$                   | $\frac{1}{3}$                    | $\frac{5}{3}$      |
| Cost           | 0         | 0         | <u>0</u> | $\frac{7}{3}$   | <u><math>\frac{5}{3}</math></u> | <u><math>-\frac{7}{3}</math></u> | $f + \frac{13}{3}$ |
|                | $(c'_1)$  | $(c'_2)$  | $(c'_3)$ | $(c'_4)$        | $(c'_5)$                        | $(c'_6)$                         |                    |
| Artificial     | 0         | 0         | 0        | 0               | 1                               | 1                                | $w - 0$            |
| End of Phase I |           |           |          | End of Phase II |                                 |                                  |                    |

[constraint 2 : 4 → 5 ( $\Delta_2 = 1$ )]

$$\begin{cases} x_3 = b_1'' = b_1' + \Delta_2 a'_{15} = 2 + (1)(-1) = 1.0 \\ x_2 = b_2'' = b_2' + \Delta_2 a'_{25} = 2/3 + (1)(1/3) = 1.0 \\ x_1 = b_3'' = b_3' + \Delta_2 a'_{35} = 5/3 + (1)(1/3) = 2.0 \end{cases}$$

[constraint 2 →  $x_5$  (column 5)]

$$r_i = -\frac{b'_i}{a'_{i5}} = \left\{ -\frac{2}{-1}, -\frac{2/3}{1/3}, -\frac{5/3}{1/3} \right\} = \{2.0, -2.0, -5.0\}$$

$$-2.0 \leq \Delta_2 \leq 2.0 \xrightarrow{b_2=4} 2.0 \leq b_2 \leq 6.0$$

[cost coefficient 1 →  $x_1$  (row 3), exclude artificial columns]

$$d_j = \frac{c'_j}{a'_{3j}} = \left\{ \frac{7/3}{-1/3} \right\} = \{-7.0\}$$

$$-7.0 \leq \Delta c_1 \leq \infty \xrightarrow{c_1=-1} -8.0 \leq c_1 \leq \infty$$

[cost coefficient 1: -1 → -2 ( $\Delta c_1 = -1$ )]

$$f_{new}^* = f^* + \Delta c_1 x_1^* = -\frac{13}{3} + (-1)\left(\frac{5}{3}\right) = -6$$

# LP in Excel Solver: Example 8.19

|   | A  | B  | C        | D       |
|---|----|----|----------|---------|
| 1 | x1 | 0  |          | 1.66667 |
| 2 | x2 | 0  |          | 0.66667 |
| 3 | z  | 0  | max      | 4.33333 |
| 4 | g1 | -5 | $\leq 0$ | -2      |
| 5 | g2 | -4 | $= 0$    | 0       |
| 6 | g3 | -1 | $\geq 0$ | 0       |

| 1 | 2           |
|---|-------------|
| 1 | 1.666666667 |
| 0 | 0.666666667 |
| 1 | 4.333333333 |

**해 찾기 모델 설정**

목표 셀(E):

해의 조건: ☒ 최대값(M) ☐ 최소값(N) ☐ 지정값(V):

값을 바꿀 셀(B):

제한 조건(U):

- 
- 
- 

**해 찾기 옵션**

최대 계산 시간(T):  초

최대 계산 횟수(I):

정밀도(P):

허용 한도(E):  %

수렴도(V):

☒ 전형 모델 가정(M) ☐ 단위 자동 설정(U)

☒ 음수 마닌 것으로 가정(G) ☒ 중간 결과 보기(B)

근사 방법: ☒ 1차식(A) ☐ 2차식(Q)

미분 계수: ☒ 전진(F) ☐ 중앙(C)

탐색 방법: ☒ 뉴턴법(N) ☐ 공역 경사법(Q)

# Reports : Example 8.19+21+23

값을 바꿀 셀

| 셀      | 이름 | 계산 값        | 한계 비용 | 목표 셀 계수 | 허용 가능 증가치 | 허용 가능 감소치 |
|--------|----|-------------|-------|---------|-----------|-----------|
| \$D\$1 | x1 | 1.666666667 | 0     | 1       | 7         | 1E+30     |
| \$D\$2 | x2 | 0.666666667 | 0     | 4       | 1E+30     | 3.5       |

민감도보고서

Range of cost coeff.

$$-7.0 \leq \Delta c_1 \leq \infty$$

$$\xrightarrow{c_1=-1} -8.0 \leq c_1 \leq \infty$$

$$-\infty \leq \Delta c_2 \leq 3.5$$

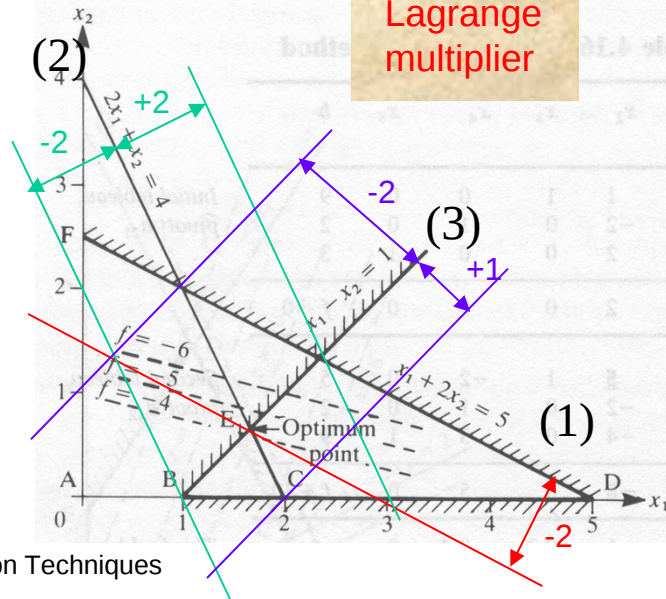
$$\xrightarrow{c_2=-4} -\infty \leq c_2 \leq -0.5$$

제한 조건

| 셀      | 이름       | 계산 값 | 제한 조건 우변 | 허용 가능 증가치 | 허용 가능 감소치 |
|--------|----------|------|----------|-----------|-----------|
| \$D\$6 | $\geq 0$ | 0    | 0        | 1         | 2         |
| \$D\$4 | $\leq 0$ | -2   | 0        | 1E+30     | 2         |
| \$D\$5 | 0        | 0    | 0        | 2         | 2         |

Lagrange multiplier

Range of resource limit



$$(1) x_1 + 2x_2 \leq 5 \rightarrow -2 \leq \Delta_1 \leq \infty \rightarrow 3 \leq b_1 \leq \infty$$

$$(2) 2x_1 + x_2 = 4 \rightarrow -2 \leq \Delta_2 \leq 2 \rightarrow 2 \leq b_2 \leq 6$$

$$(3) x_1 - x_2 \geq 1 \rightarrow -2 \leq \Delta_3 \leq 1 \rightarrow -1 \leq b_3 \leq 2$$

# Reports : Example 6.18+20+22

## 목표 셀 (최대값)

| 셀      | 이름          | 계산 전의 값 | 계산 값 |
|--------|-------------|---------|------|
| \$D\$4 | max optimal | 0       | 18   |

| 목표 셀   |             |    |
|--------|-------------|----|
| 셀      | 이름          | 값  |
| \$D\$4 | max optimal | 18 |

## 값을 바꿀 셀

| 셀      | 이름         | 계산 전의 값 | 계산 값 |
|--------|------------|---------|------|
| \$D\$2 | x1 optimal | 0       | 4    |
| \$D\$3 | x2 optimal | 0       | 1    |

| 값을 바꿀 셀 |            |   |
|---------|------------|---|
| 셀       | 이름         | 값 |
| \$D\$2  | x1 optimal | 4 |
| \$D\$3  | x2 optimal | 1 |

| 하한값 | 목표 셀 |
|-----|------|
| 한계값 | 결과   |
| 0   | -2   |
| 1   | 18   |

| 상한값 | 목표 셀 |
|-----|------|
| 한계값 | 결과   |
| 4   | 18   |
| 1   | 18   |

## 제한 조건

| 셀      | 이름          | 셀의 값        | 수식        | 만족 정도  | 조건과의 차 |
|--------|-------------|-------------|-----------|--------|--------|
| \$D\$5 | <=0 optimal | 3.40721E-10 | \$D\$5<=0 | 만족     | 0      |
| \$D\$7 | <=0 optimal | -13         | \$D\$7<=0 | 부분적 만족 | 13     |
| \$D\$6 | <=0 optimal | -1.3102E-11 | \$D\$6<=0 | 만족     | 0      |

## 값을 바꿀 셀

| 셀      | 이름         | 계산 값 | 한계 비용 | 목표 셀 계수 | 허용 가능 증가치 | 허용 가능 감소치 |
|--------|------------|------|-------|---------|-----------|-----------|
| \$D\$2 | x1 optimal | 4    | 0     | 5       | 1E+30     | 4         |
| \$D\$3 | x2 optimal | 1    | 0     | -2      | 4.5       | 8         |

## 제한 조건

| 셀      | 이름          | 계산 값        | 잠재 가격 | 제한 조건 우변 | 허용 가능 증가치 | 허용 가능 감소치   |
|--------|-------------|-------------|-------|----------|-----------|-------------|
| \$D\$5 | <=0 optimal | 3.40721E-10 | 1.6   | 0        | 1E+30     | 5           |
| \$D\$7 | <=0 optimal | -13         | 0     | 0        | 1E+30     | 13          |
| \$D\$6 | <=0 optimal | -1.3102E-11 | 1.8   | 0        | 2.5       | 9.285714286 |

# Matlab Optimization Toolbox

---

```
>> [x,fval,exitflag,output,lambda] = linprog([-1 -4],[1 2;-1 1],[5;-1],[2 1],[4])
```

```
x =
```

```
1.6667
```

```
0.6667
```

```
fval =
```

```
-4.3333
```

```
exitflag =
```

```
1
```

```
output =
```

```
iterations: 5
```

```
algorithm: 'large-scale: interior point'
```

```
cgiterations: 0
```

```
message: 'Optimization terminated.'
```

```
lambda =
```

```
ineqlin: [2x1 double]
```

```
eqlin: 1.6667
```

```
upper: [2x1 double]
```

```
lower: [2x1 double]
```

```
>> lambda.ineqlin
```

```
ans =
```

```
0.0000
```

```
2.3333
```