





# 01 선정동기



**DMU Kinematics** 



# 01 모델 선정



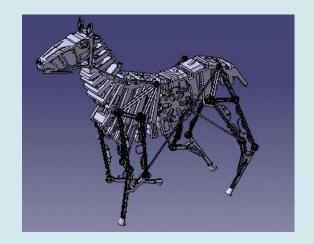
#### 01 설계목표

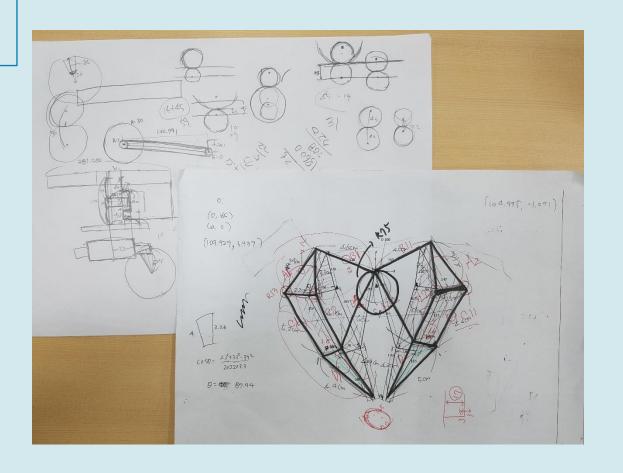
- 하나의 Angle driven
- 4족 보행
- 새로운 Gear
- 디자인

설계

#### 01 참고모델

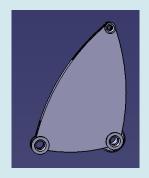


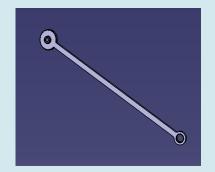




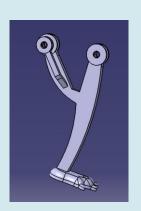
02 설계 -Part

Design(leg)-



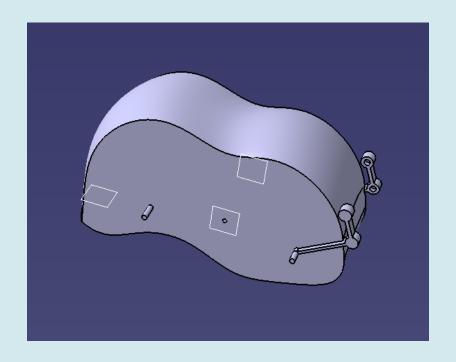






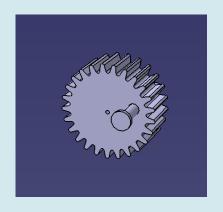
02 설계 -Part

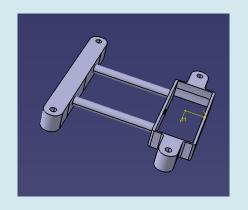
Design(body)-

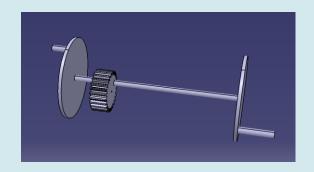


02 설계 -Part

Design(body)-

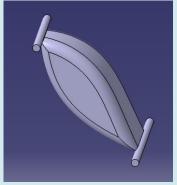


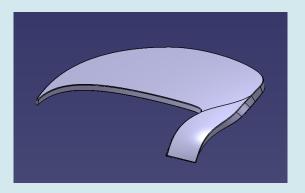


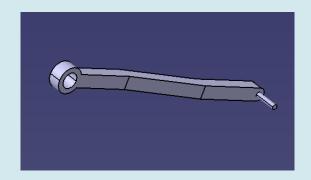


# 02 설계 -Part Design(etc)-

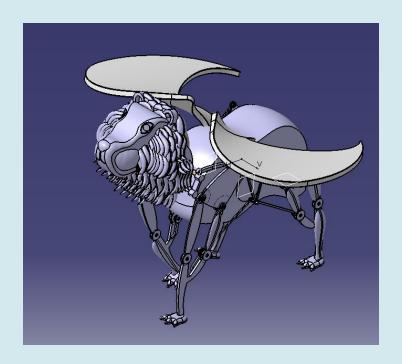


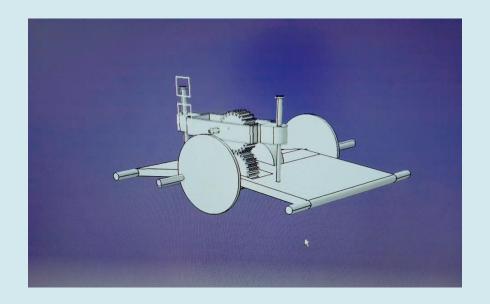


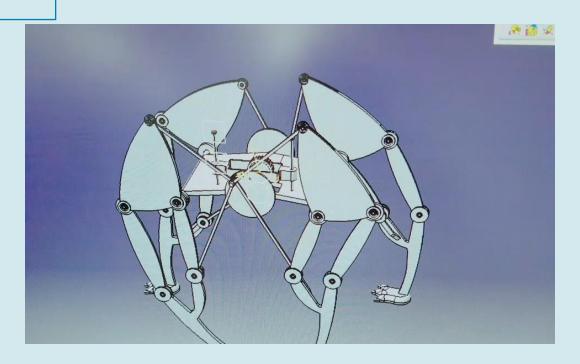


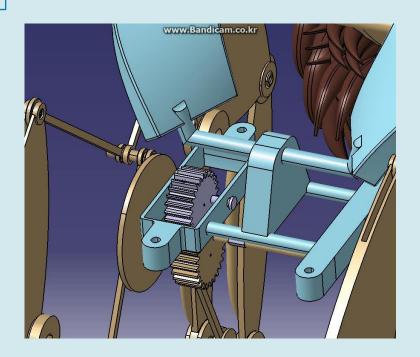


## 02 설계 -Assembly-

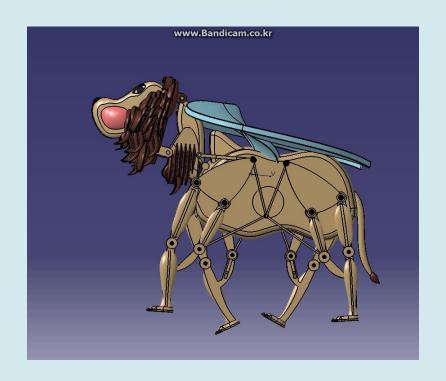














# 디테일의 부족..

- 1. 연결 링크(뼈대)를 감싸지 못해 앙상해 보임
- 2. 기계처럼 치수가 딱 맞아떨어지지 않음
- 3. 동물을 표현하기 위해 임의의 곡선들을 사용
- 4. 생각보다 간단해 보이는 움직임

