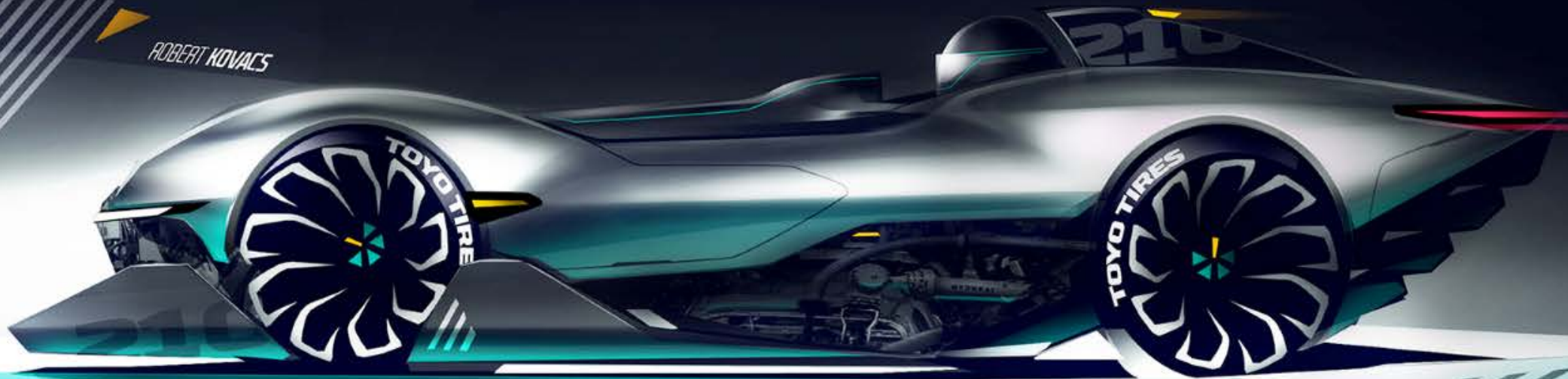


# TNT

Technology & Team playing



2017037174 이성원  
2017037238 장원석  
2017037329 최수형

# 차레



1. 주제 선정
2. 팀 명 선정
3. 제작과정
4. 특이점
5. 한계점
6. 구동 영상

# 팀 명 선정

why?

Technology and Teamplay

복잡한 완성체를 만들어내기 위한  
Team play



Sparkling idea



&

폭발적인 엔진 시스템



# 주제 선정

미래자동차 공학도들!!!

자동차의 다양한 움직임을 구현

자동차에 대한 이해도 증대

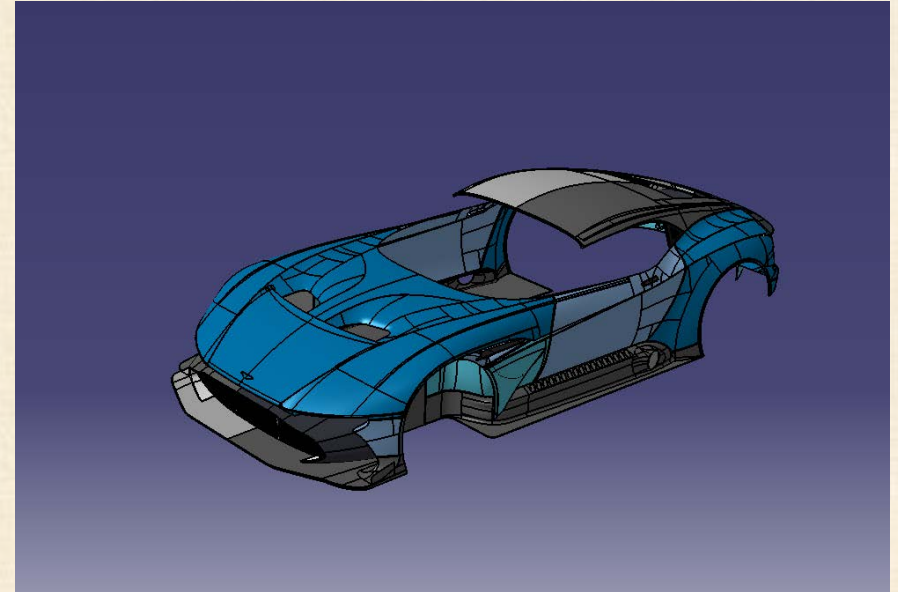
## Aston Martin Vulcan

모델을 파보자!!!



# 제작과정

자동차의 외면을 아웃소싱



내부 부품은 디자인 하자!

# 부품 디자인 목록

장원석

**Open top**  
**Brake movement**  
**Suspension**  
**Koenigsegg door**  
**Bonnet movement**

이성원

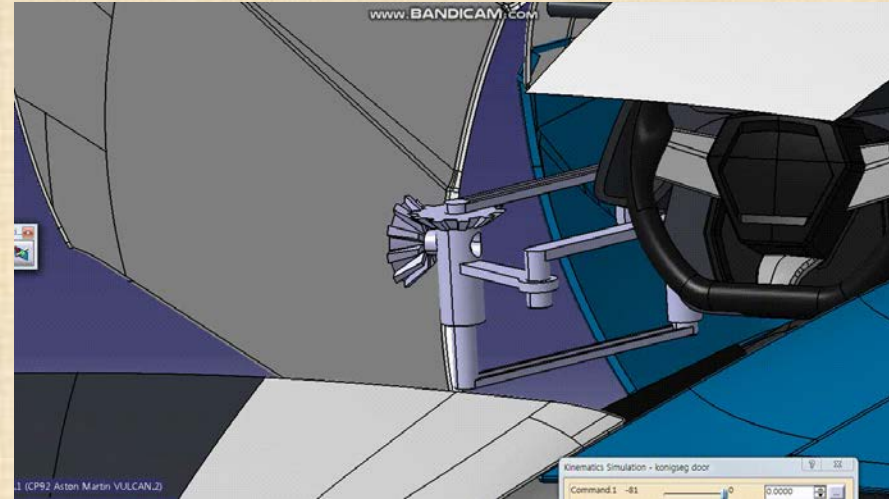
**Engine**

+

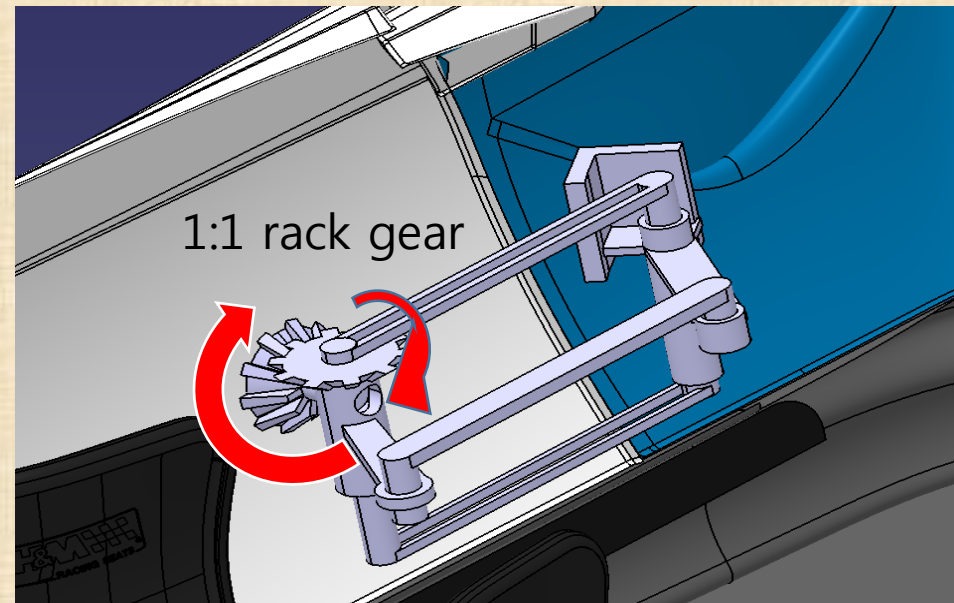
최수형

**Steering system**

# Koenigsegg door

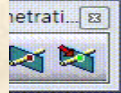
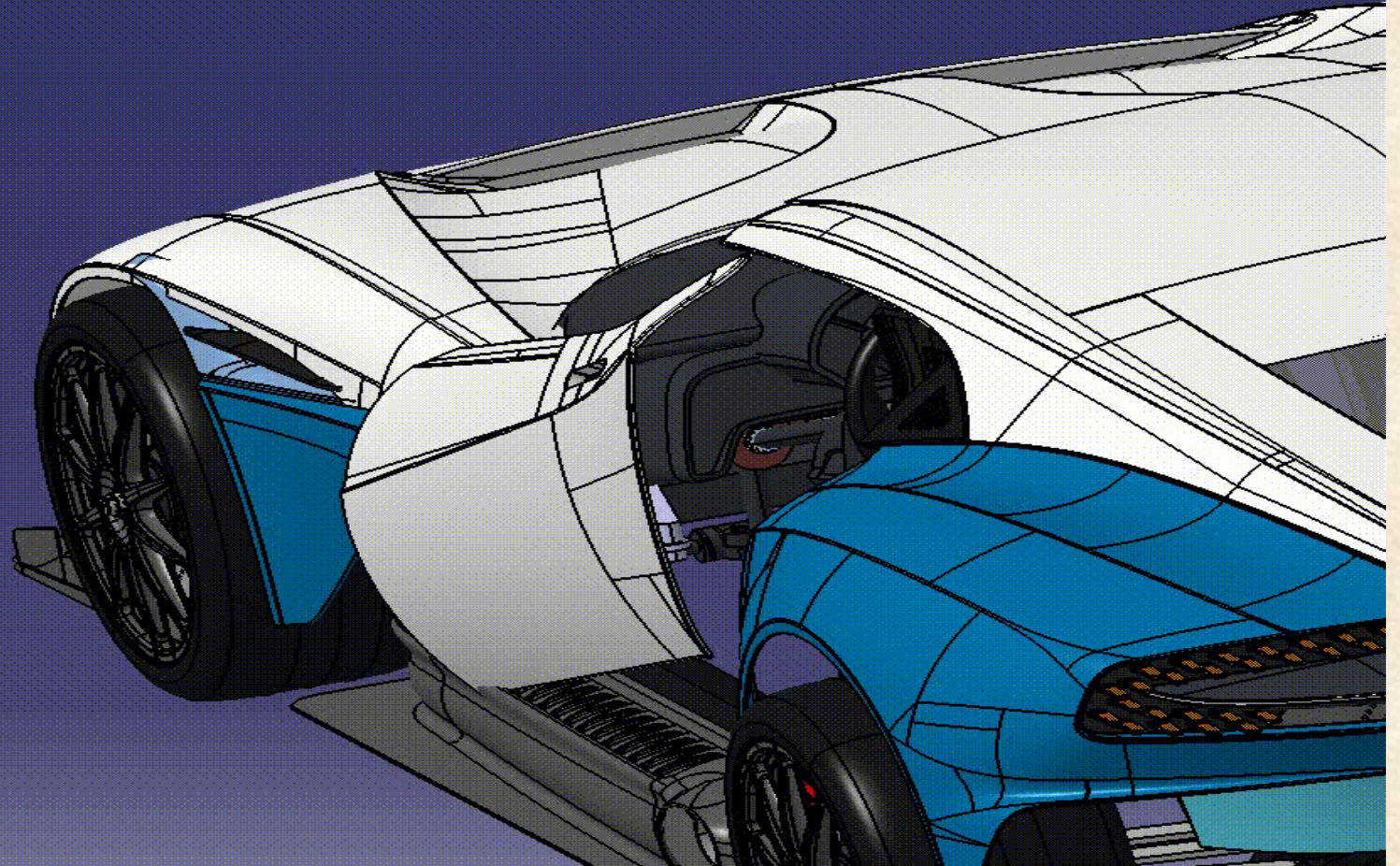


자유도 1  
Gear mechanism



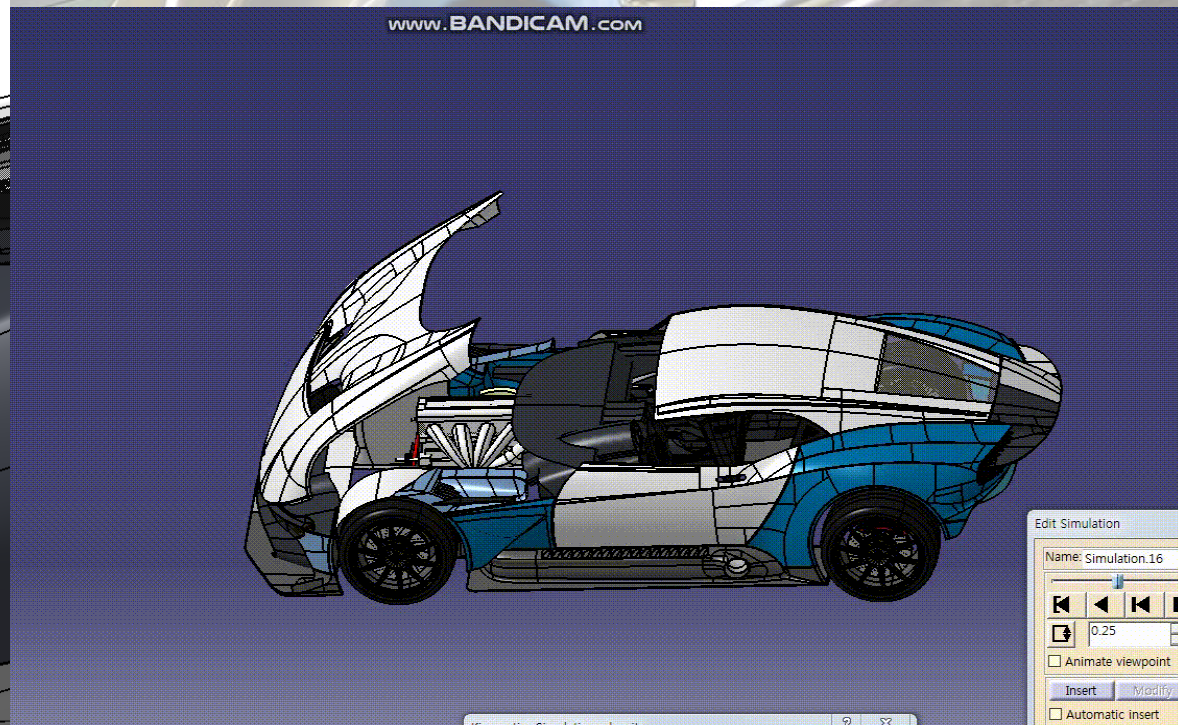
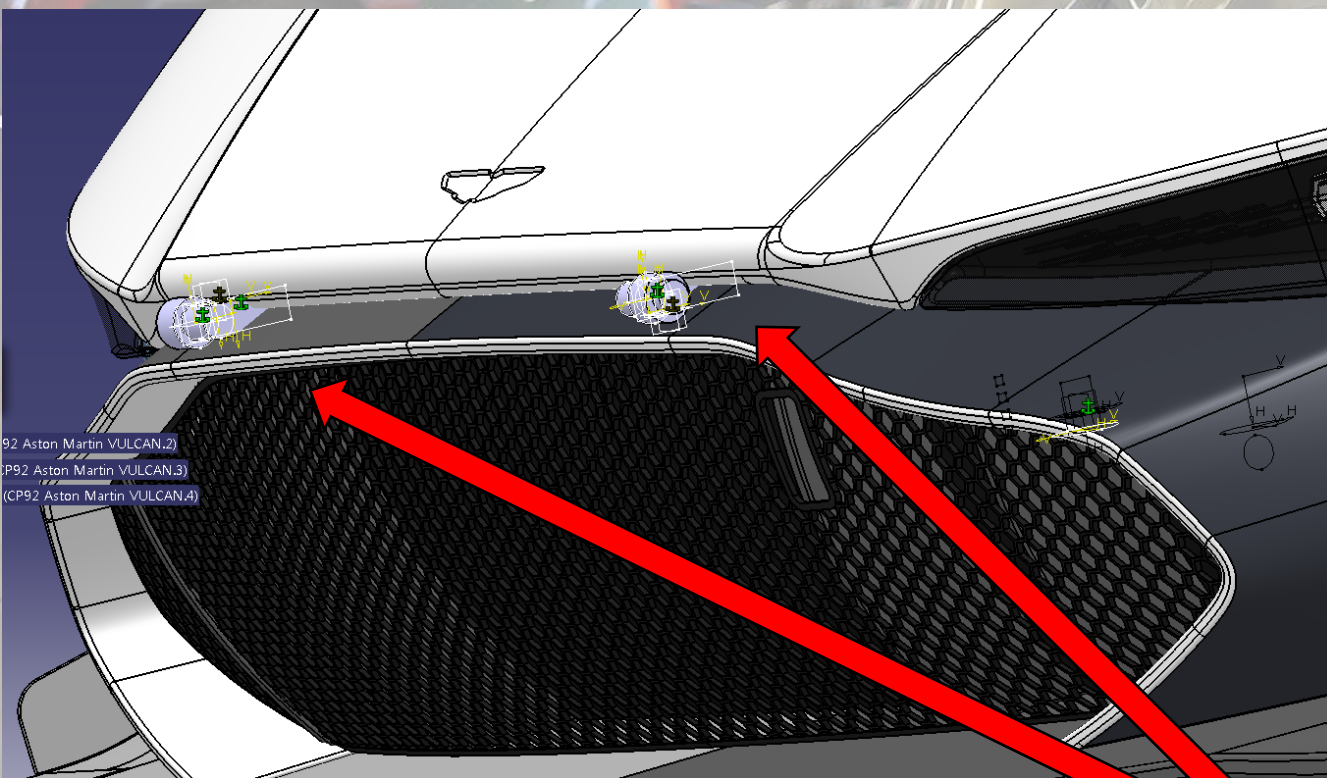
# Koenigsegg door

www.BANDICAM.com



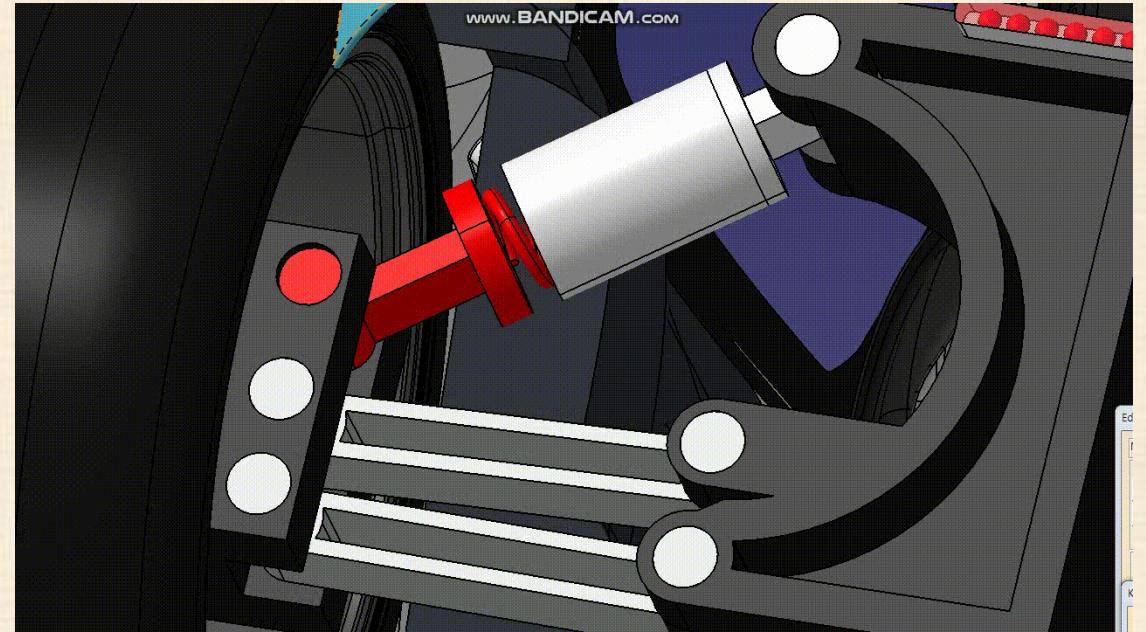
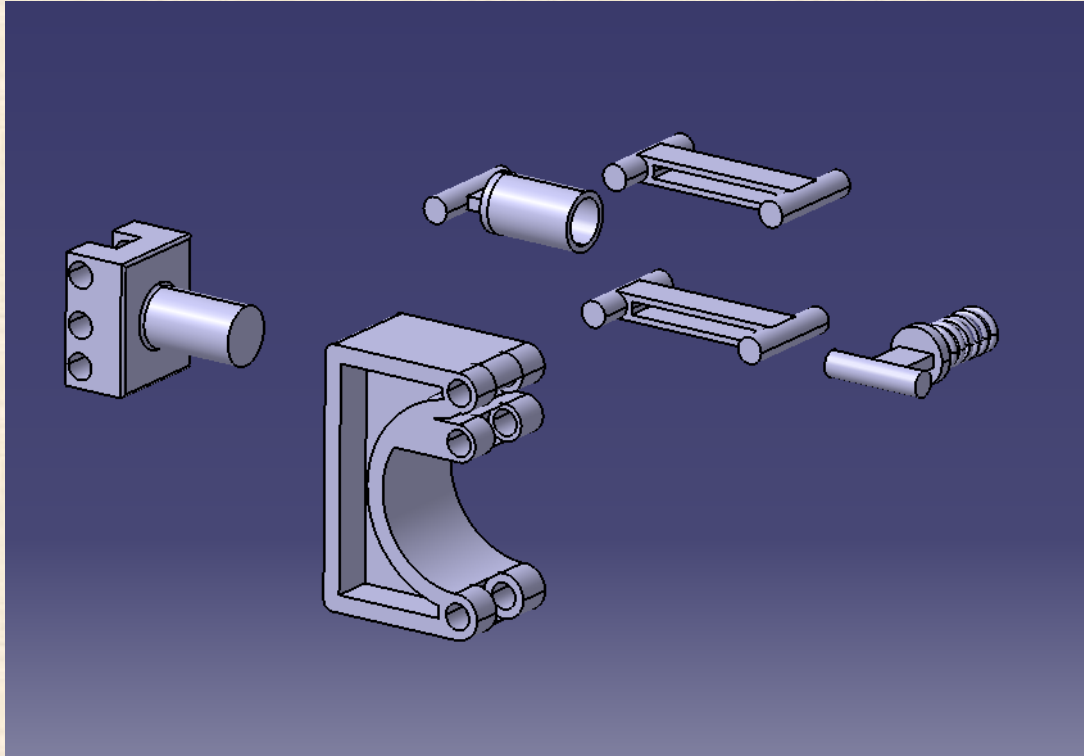


# bonnet



Revolute joint

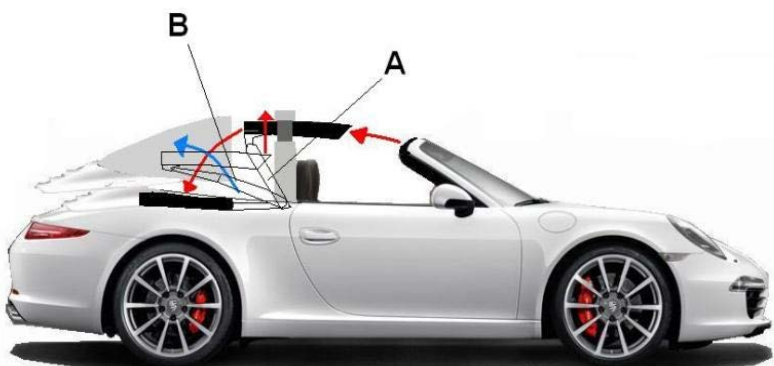
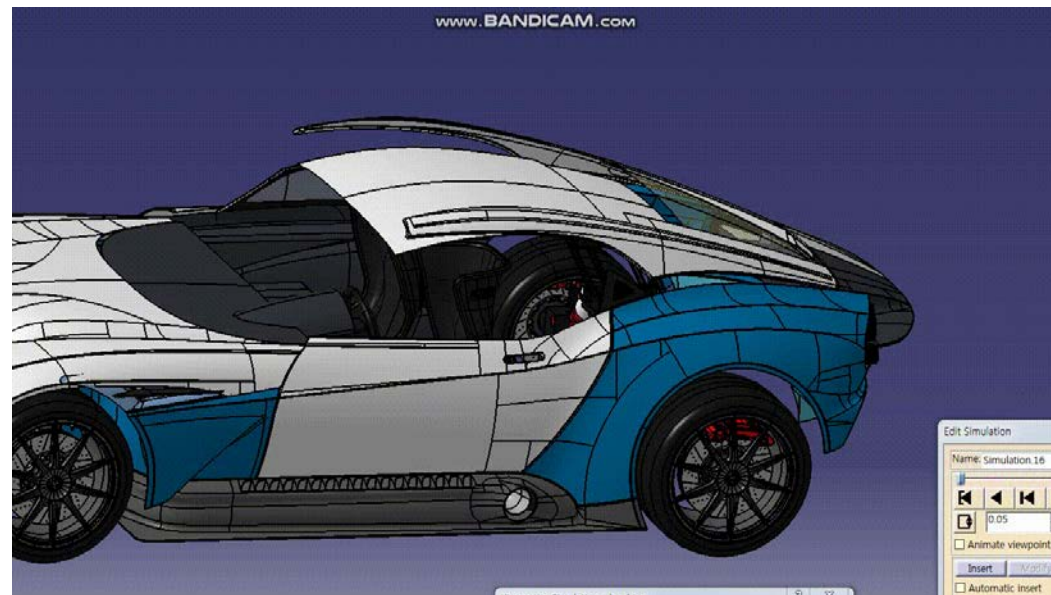
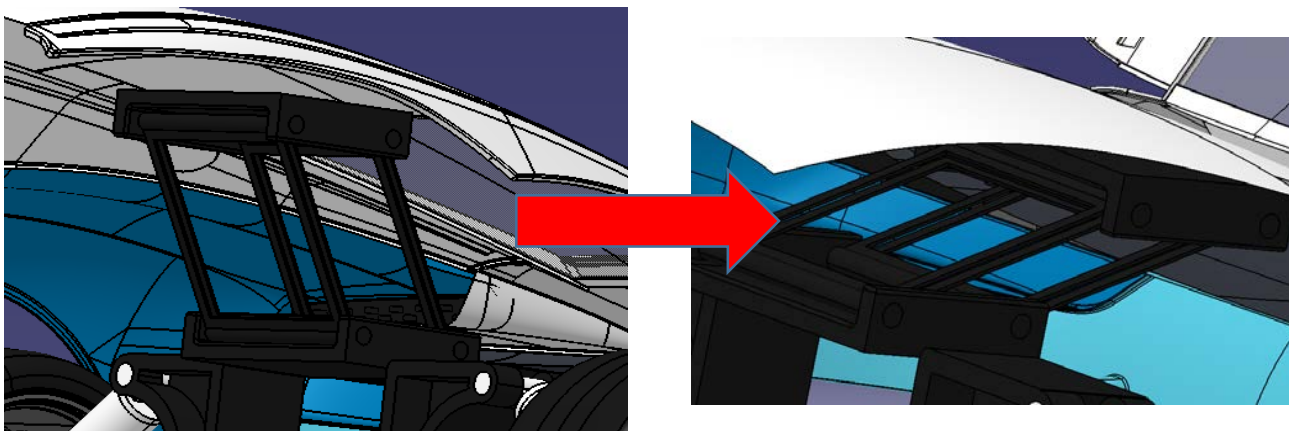
# suspension



자유도 1

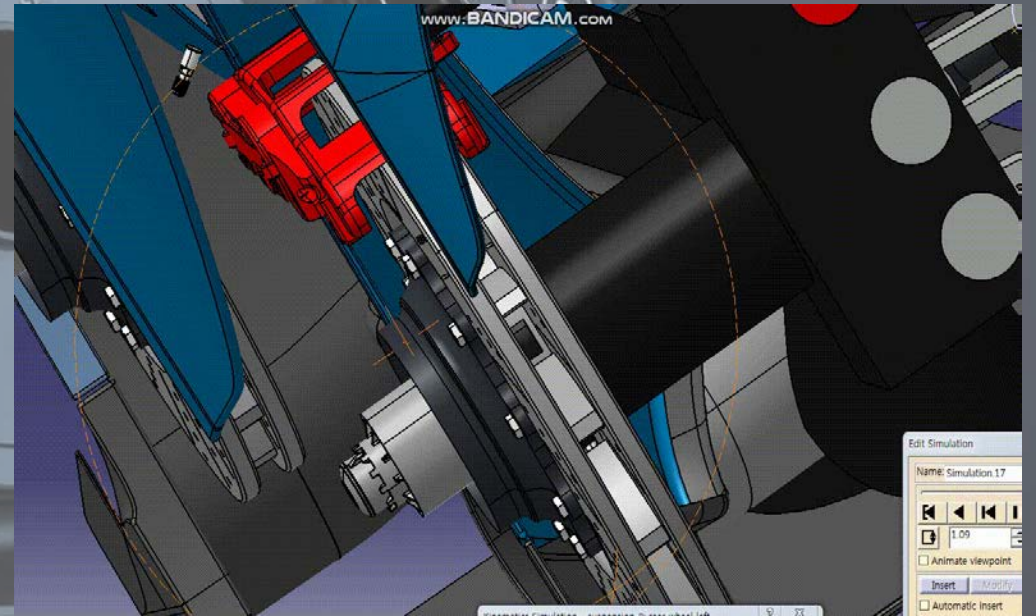
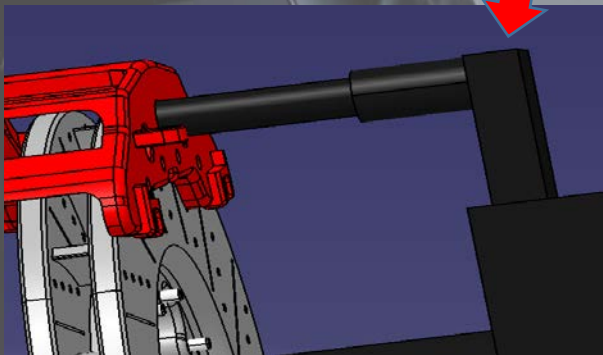
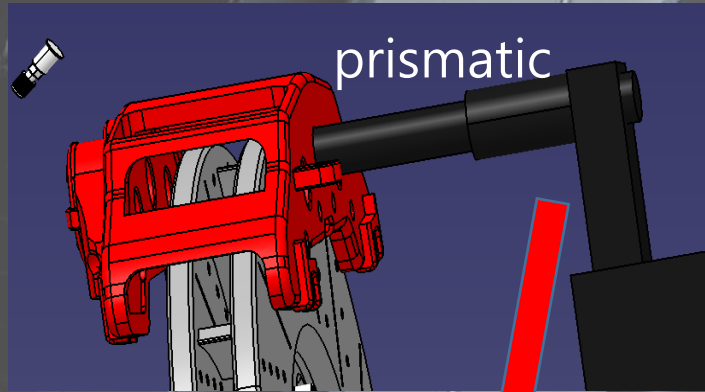
grabcad

# Open top



자유도 1

# Brake



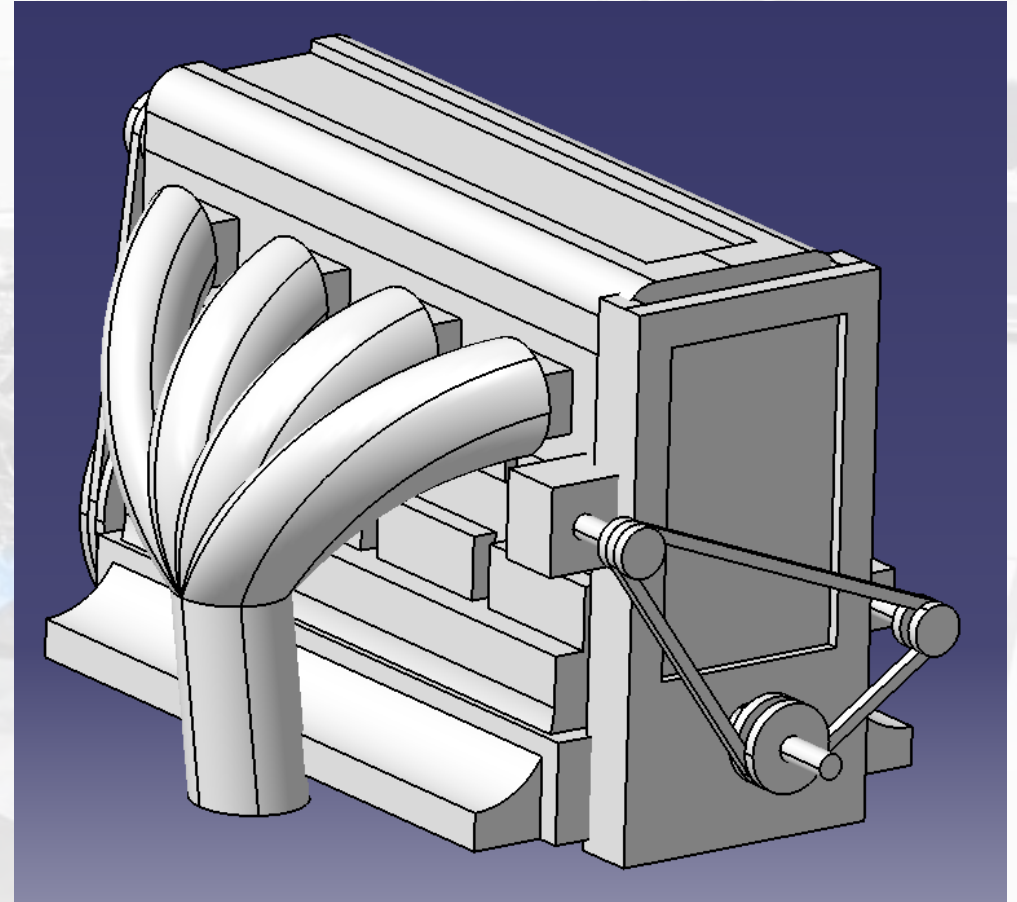
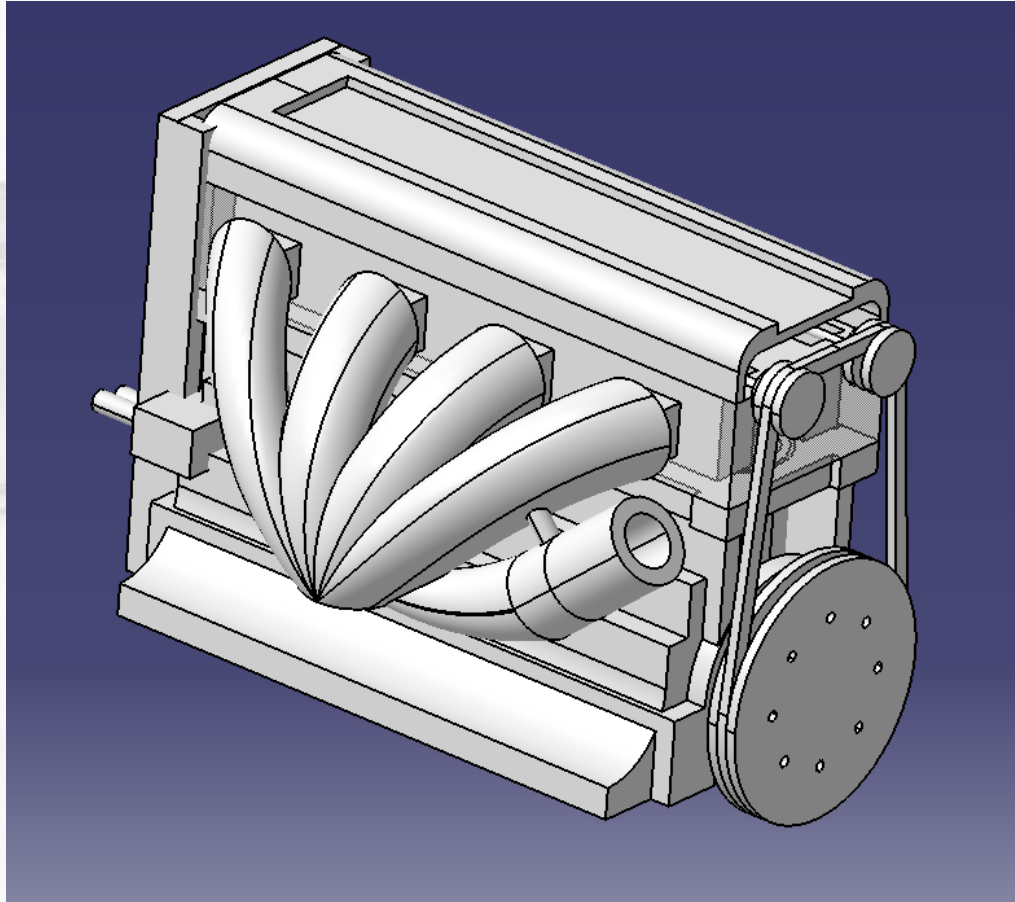


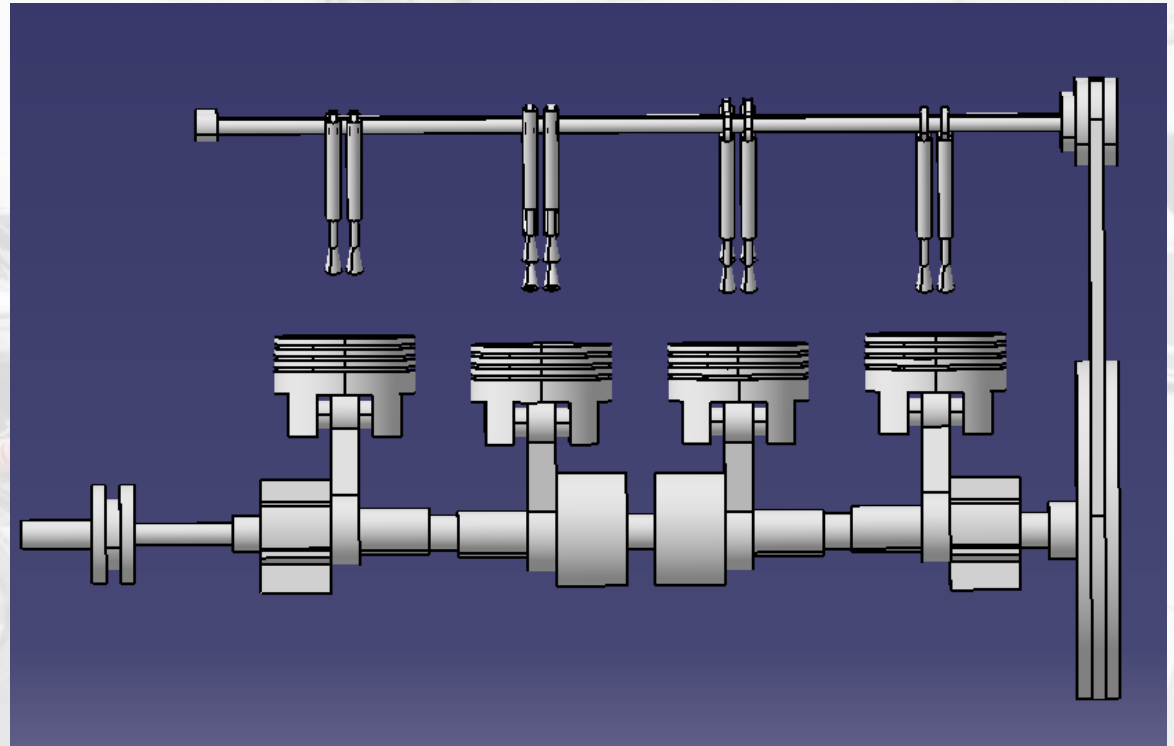
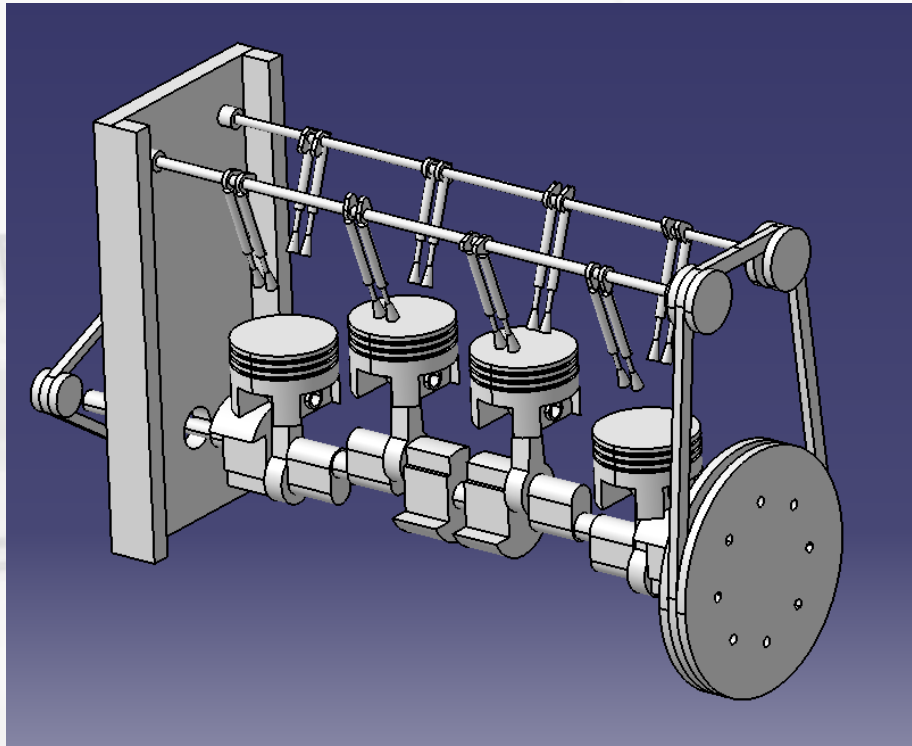
# Engine part

Model : Linear(Inline) 4 Engine



# Part Design

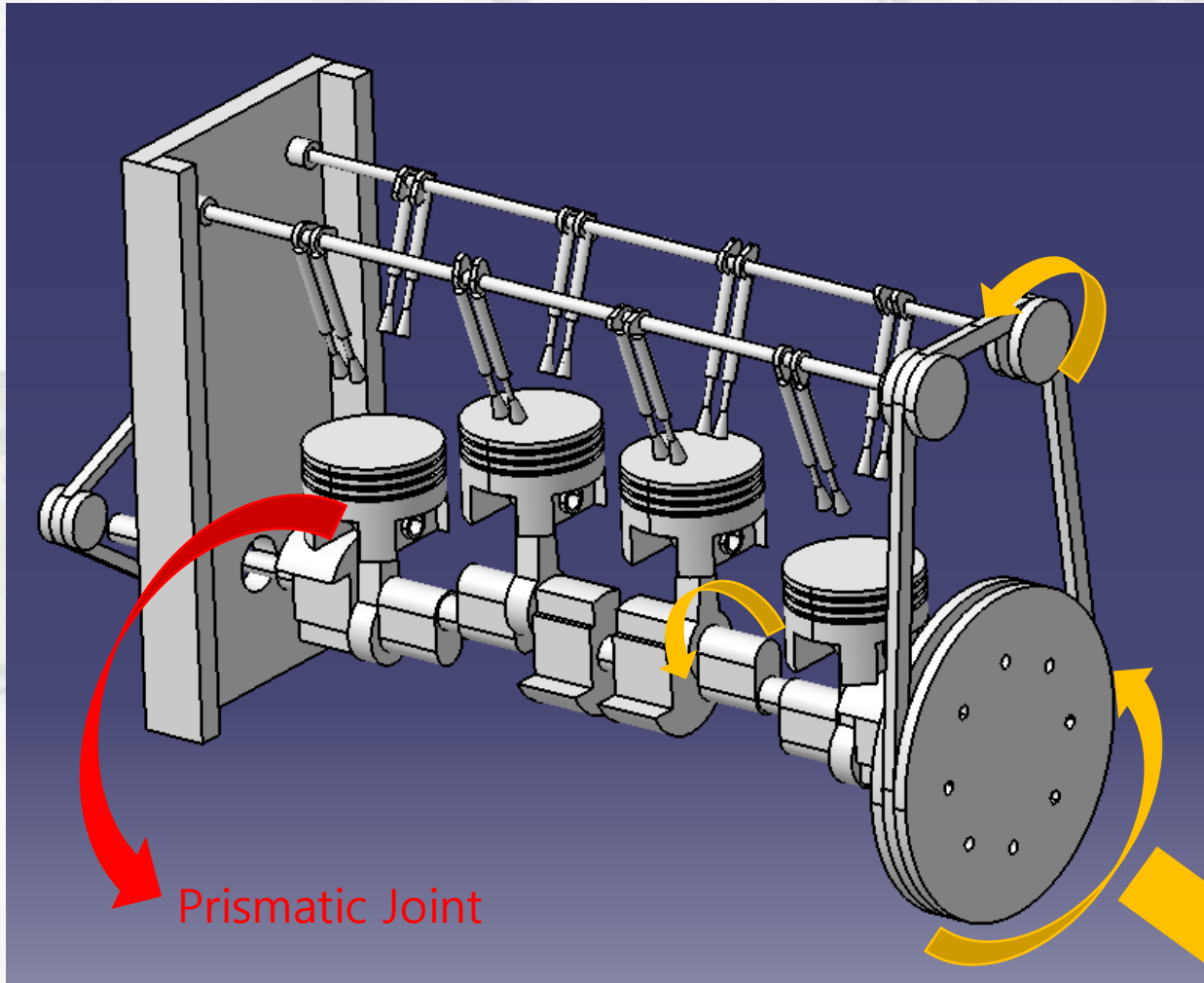




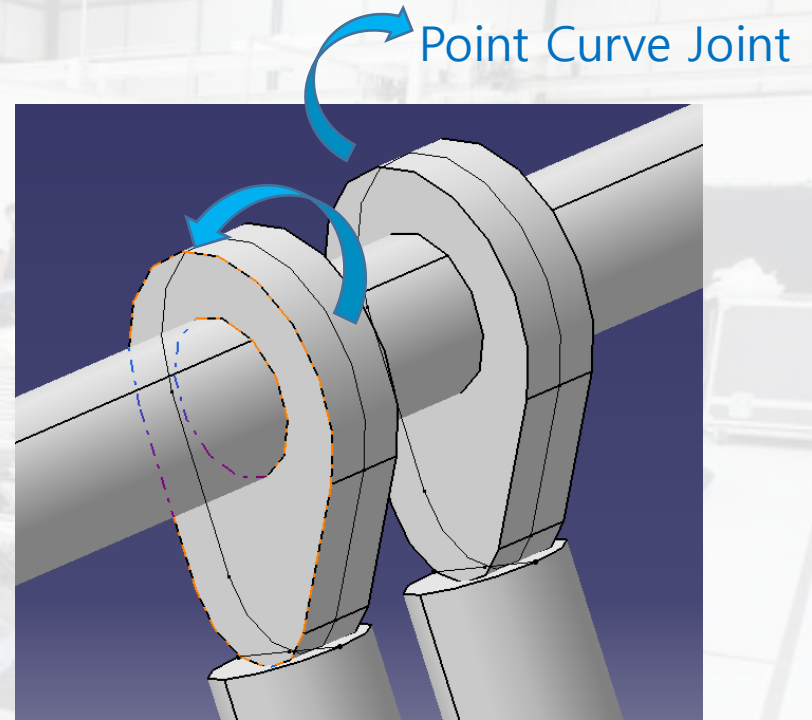


# DMU Kinematics

- Piston : Prismatic Joint
- Crank Shaft / Cam Shaft : Revolute Joint
- Cam : Point – Curve Joint

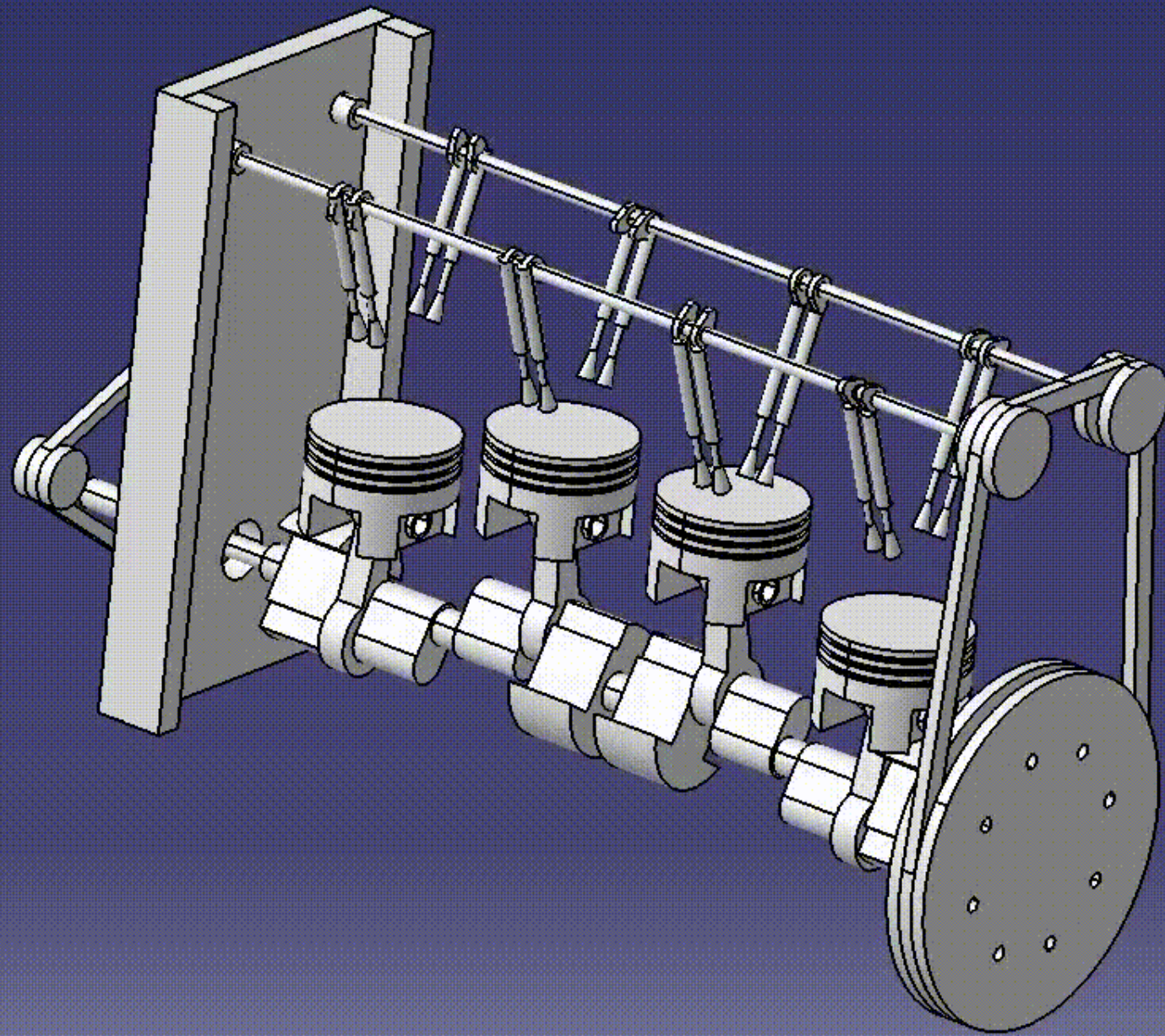


Prismatic Joint



Point Curve Joint

Revolute Joint



# 조향 장치(Steering System)

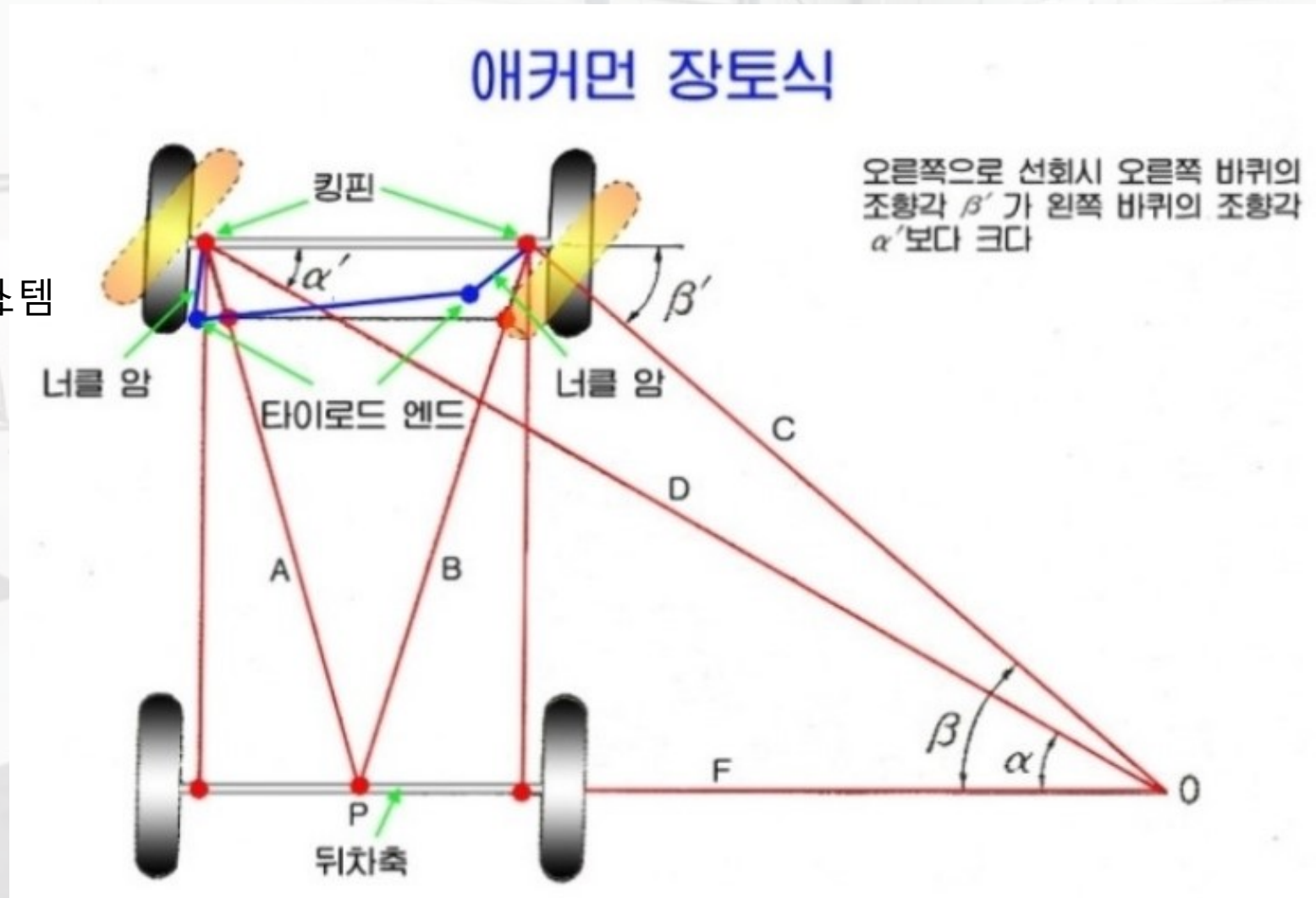


# 조향 장치(Steering System)

- 조향 이론

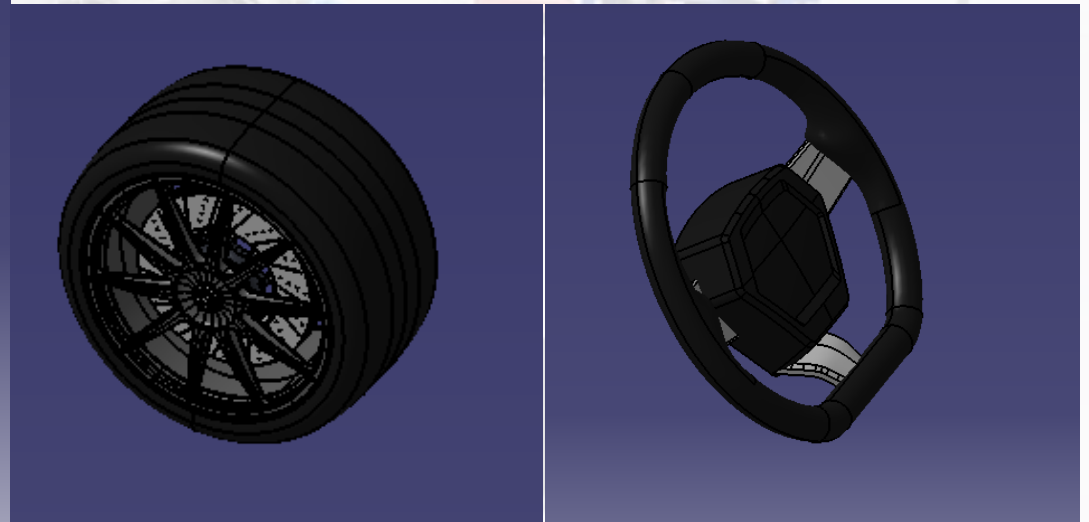
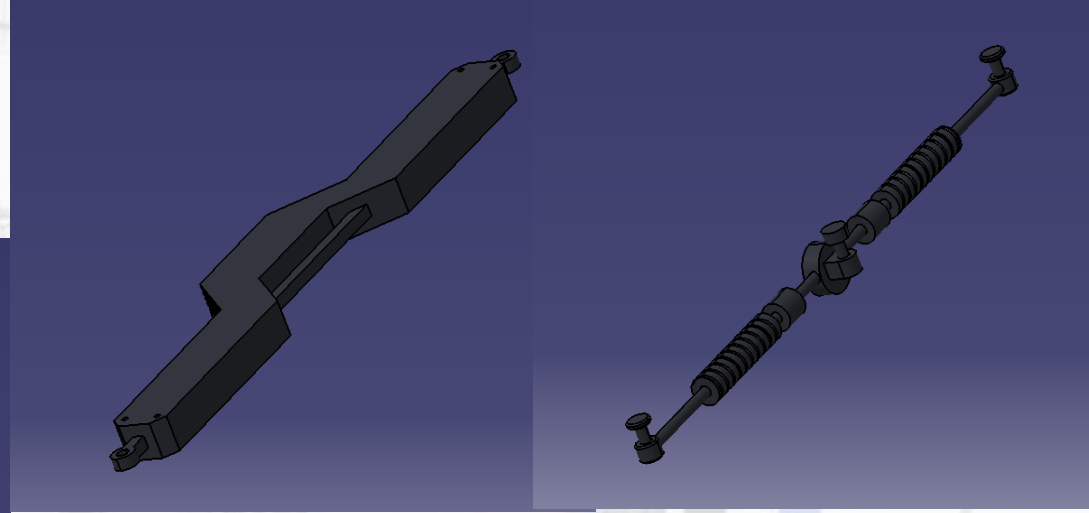
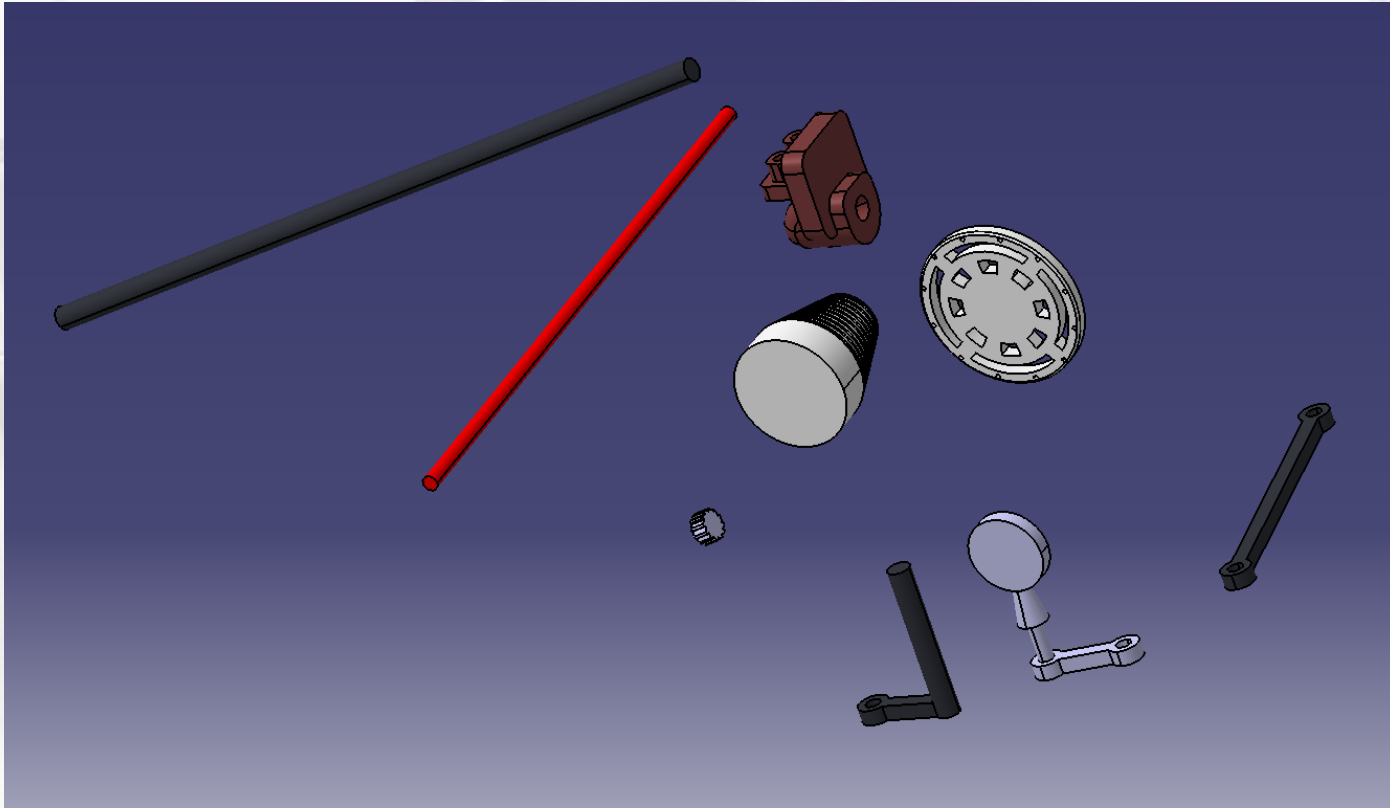
서라운드 스피커와 조향 시스템

시스템 설계



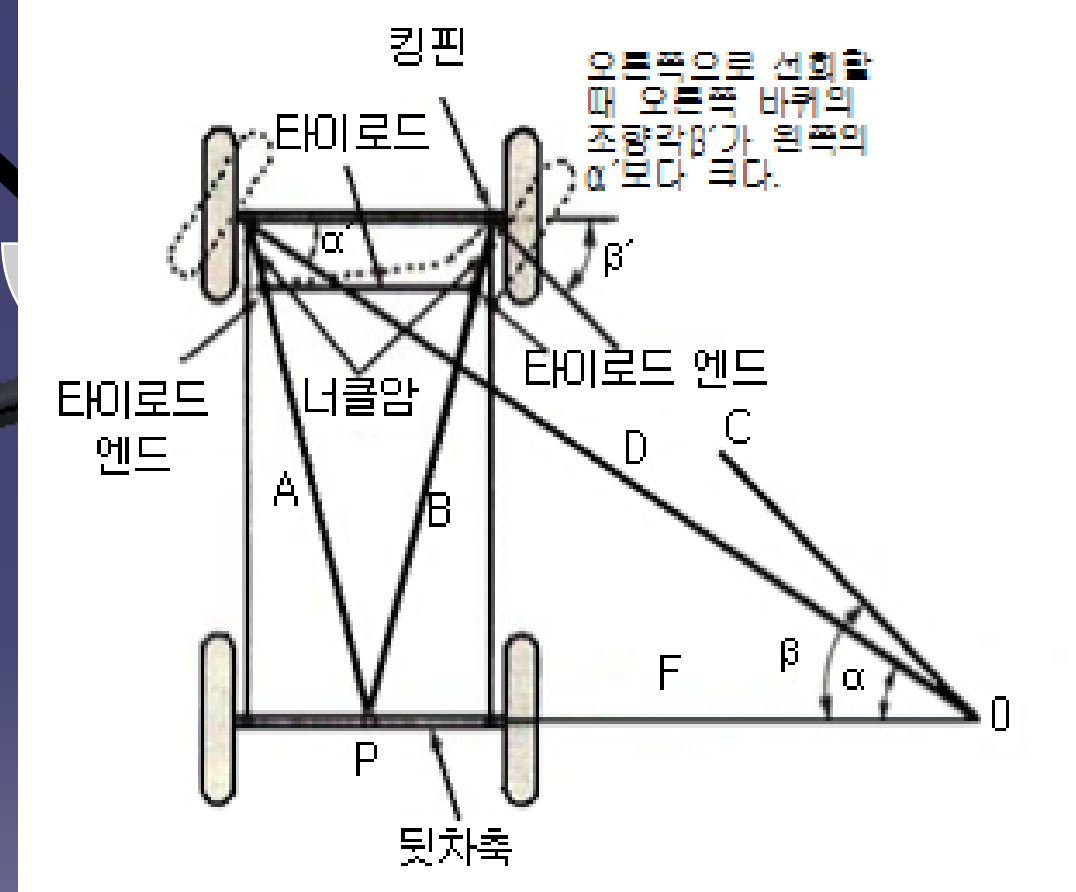
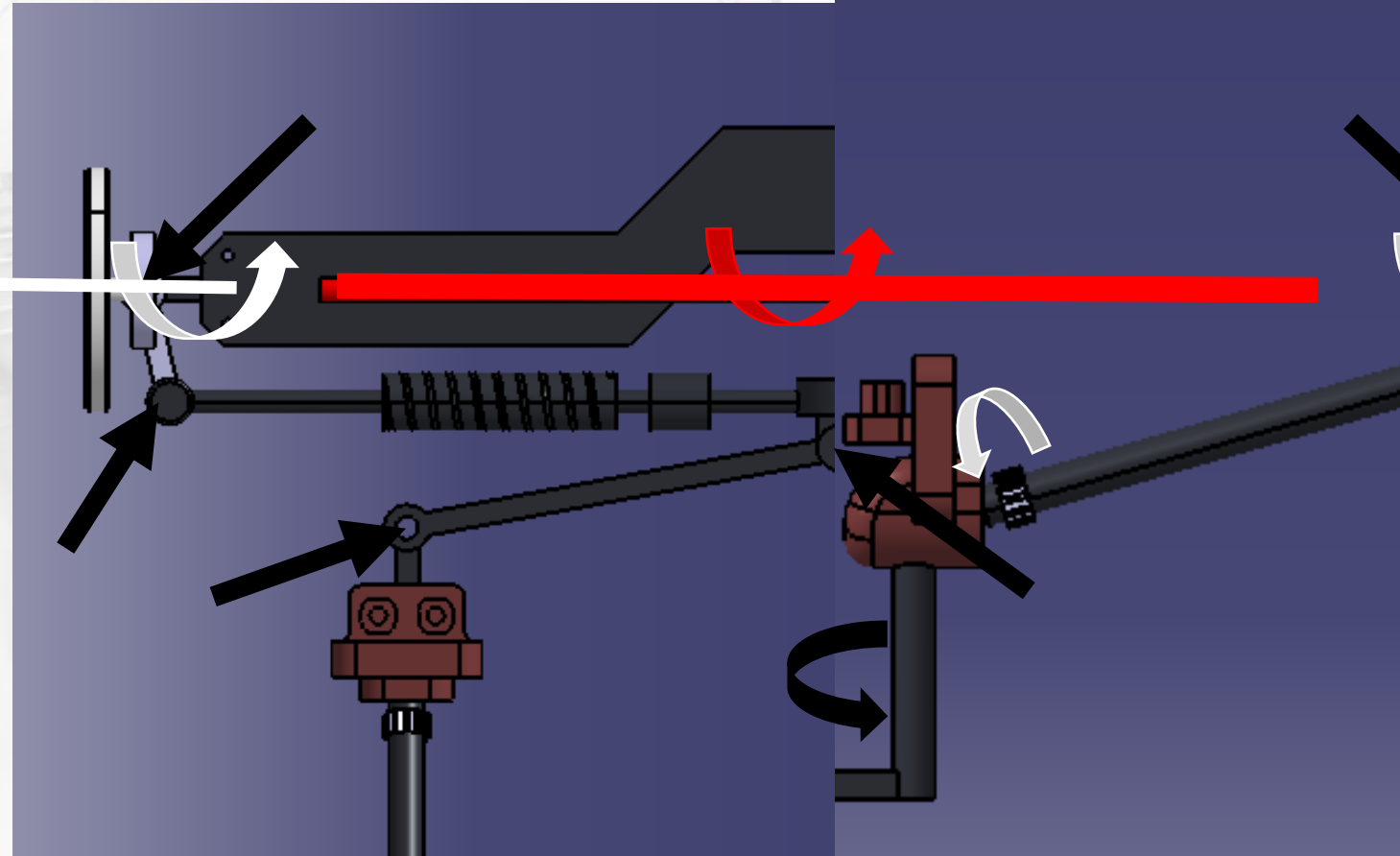
# 조향 장치(Steering System)

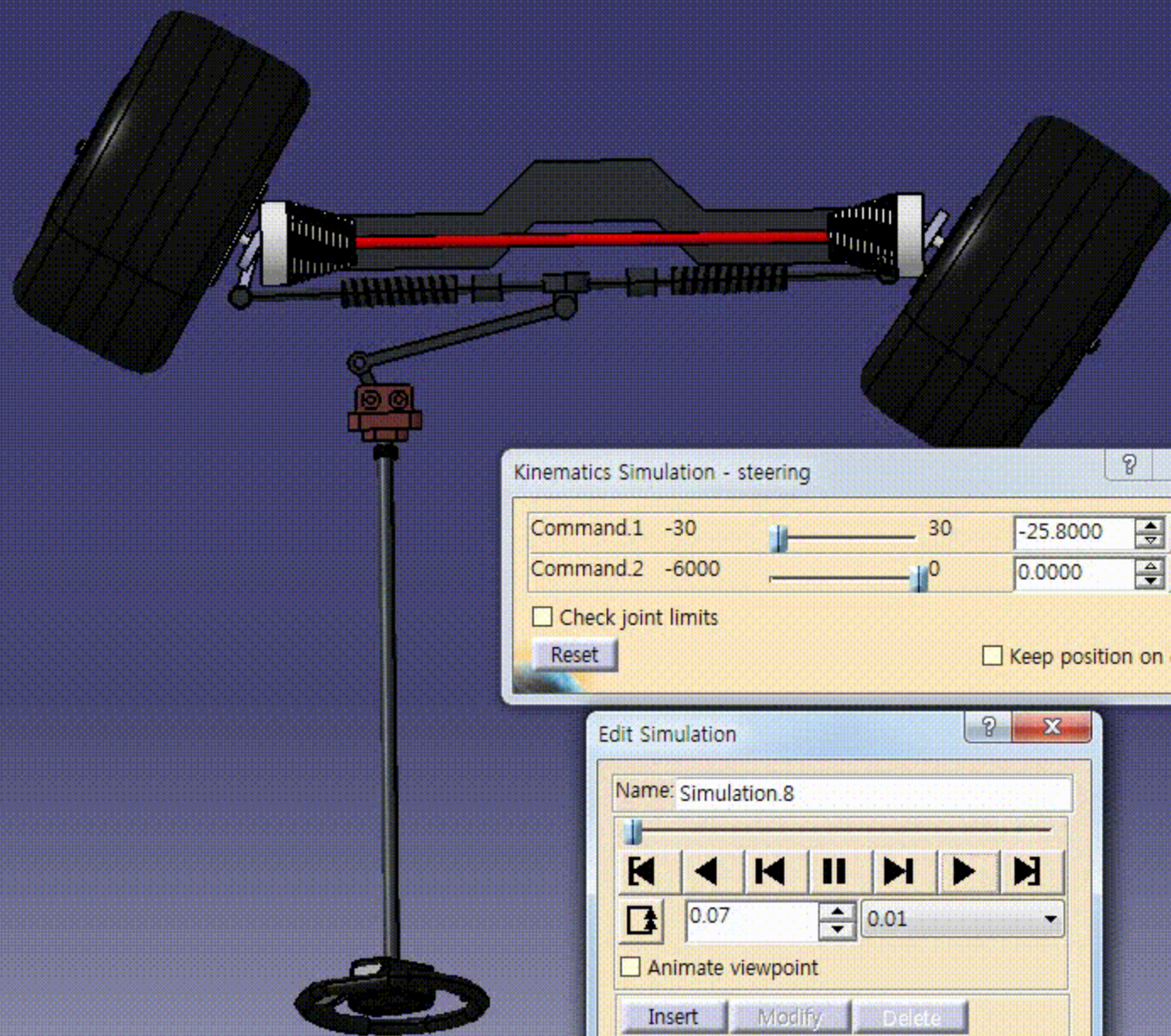
- Part Design



# 조향 장치(Steering System)

- DMU Kinematics





Kinematics Simulation - steering

|           |       |    |          |     |
|-----------|-------|----|----------|-----|
| Command.1 | -30   | 30 | -25.8000 | ... |
| Command.2 | -6000 | 0  | 0.0000   | ... |

Check joint limits

Reset  Keep position on exit

Edit Simulation

Name: Simulation.8

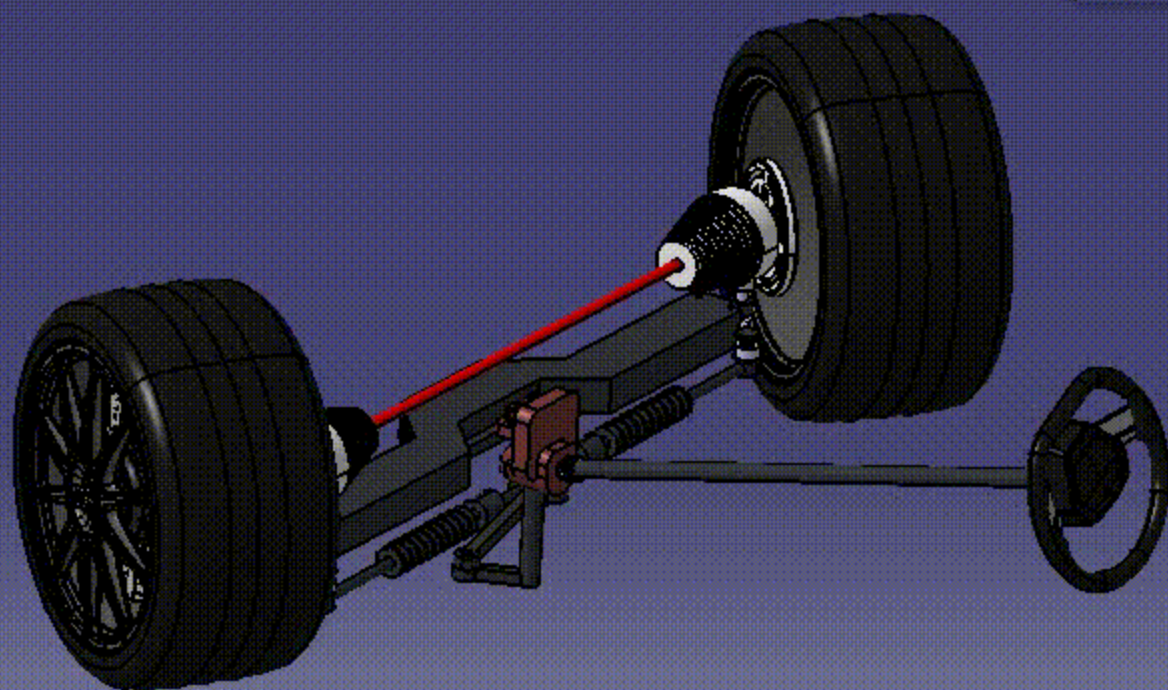
0.07 0.01

Animate viewpoint

Insert Modify Delete

Automatic insert





Kinematics Simulation - steering

|           |       |    |          |     |
|-----------|-------|----|----------|-----|
| Command.1 | -30   | 30 | -26.4000 | ... |
| Command.2 | -6000 | 0  | 0.0000   | ... |

Check joint limits

Keep position on exit

Edit Simulation

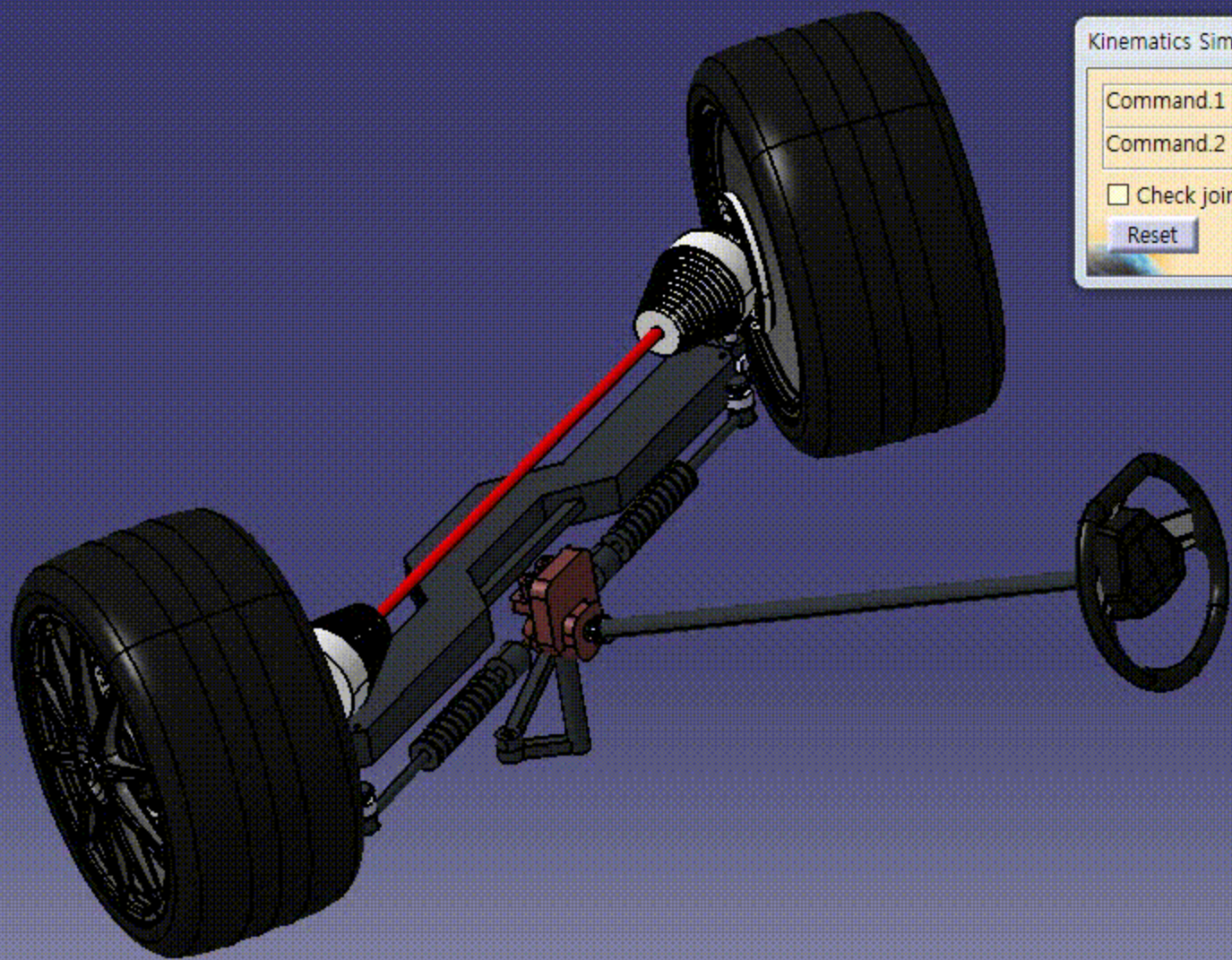
Name: Simulation.8

0.07 0.01

Animate viewpoint

Automatic insert

Interference: Off Distance: Off



Kinematics Simulation - steering

Command.1 -30 30 -29.4000

Command.2 -6000 0 -4.5000

Check joint limits

Reset  Keep position on exit

Edit Simulation

Name: Simulation.2

0.01 0.01

Animate viewpoint

Insert Modify Delete

Automatic insert

Interference Distance

Off Off

Edit analysis Edit simulation objects

Edit sensors

OK Cancel

# 동영상

<https://www.youtube.com/watch?v=TZIr6wKuOq0>



# 한계점 / 힘들었던 점

- 차의 외관을 디자인 하지 못했다.
- 차 부품 전체를 구현하지 못했다.
- Assembly와 Kinematics가 의도했던대로 매끄럽게 연결되지 않았다.

# 출처

<https://www.youtube.com/watch?v=c4LUy1rijdA>

<http://www.cato.com/QnA/QnAServiceView.aspx?PageNo=2&Idx=179&Category=car&SearchForm=&SearchTitle=>

<http://jwkang7.wo.to/pds03/317.htm>

[https://www.youtube.com/watch?v=BXQ27pU3\\_7E](https://www.youtube.com/watch?v=BXQ27pU3_7E)

<https://www.youtube.com/watch?v=vxt2qqHVfVE>





Thank you